

AutoMax Network Communication Option Board for use with GV3000/SE AC Drives

M/N 2AX3000

Instruction Manual D2-3308-7



The information in this manual is subject to change without notice.

Throughout this manual, the following notes are used to alert you to safety considerations:



ATTENTION: Identifies information about practices or circumstances that can lead to personal injury or death, properly damage, or economic loss.

Important: Identifies information that is critical for successful application and understanding of the product.

The thick black bar shown on the outside margin of this page will be used throughout this instruction manual to signify new or revised text or figures.



ATTENTION: Only qualified personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, and/or service this equipment. Read and understand this instruction manual in its entirety before proceeding. Failure to observe this precaution could result in severe bod by injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, ockout, and tag at incoming power to the drive before performing installing any option kits. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five iminutes for the DC bus capacitors to discharge and then check the voltage with a voltmater to ensure that the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: The drive contains printed circuit boards that are static-sensitive. Anyone who touches the drive components should wear an anti-static wrist band. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed. Failure to observe this precaution can result in bod ly injury.

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CONTENTS

Chapter 1	Introduction	
	1.1 AutoMax Network Communication Option Board Description	1-1
	1.2 Where to Find Additional Information	
	1.3 Related Hardware and Software	
	1.4 Getting Assistance from Reliance Electric	
Chapter 2	Installation	
	2.1 Setting AutoMax Network Option Board Jumpers	2-3
	2.2 Installing the AutoMax Network Option Board in 1 to 5HP@460VAC Drives	
	2.3 Installing the AutoMax Network Option Board in 7.5 to 10HP@460VAC Drives	
	2.4 Installing the AutoMax Network Option Board in 1 to 20HP@230VAC Drives	
	2.5 Installing the AutoMax Network Option Board in	
	38 to 100HP@230VAC and 75 to 200 @ 460VAC Drives	2-16
	2.6 Installing the AutoMax Network Option Board in 15 to 25 HP and	
	25 to 60HP @ 460V Drives	2-21
	100 to 150 HP @ 460V Drives	9-94
	2.8 Installing the AutoMax Network Option Board in	
	200 to 400 HP@460 VAC Drives	2-29
	2.9 Installing the AutoMax Network Option Board in 2 to 15 Amp and	
	24 to 30 Amp GV3000/SE Bookshelf Drives	2-32
	2.10 Connecting the GV9000/SE Drive to an AutoMax Network	2-96
Chapter 3	Drive Configuration	
60	3.1 Configuring Network Communication	
	3.2 Drive Response to Loss of Network Communication	3-2
	3.3 GV3000/SE Drive Network Parameters	3-2
Chapter 4	Programming	
	4.1 The Network and Other Control Sources	
	4.2 Network Transfer Rates	
	4.2.1 I/O Jpdate Enable Logic Summary	
	4.3 Setting Jp Data Types That Can Be Transferred	4-2
	4.3.1 Tune/Config Update Synchronization Flag	44
	4.4 Monitoring Unacceptable Parameter Values	
	4.5 Timing Requirements	
	4.6 Drive Ready Status Bit	
	4./ Pulse Encoder Counter Register	
	4.8 Network Register Organization	4-t
	4.9 GV9000/SE Drive Parameters Not Accessible Over the Network	4-6
Chapter 5	Register Map Tables	
	5.1 Finding Data in the Register Map Tables	5-1

Contents

Appendix A	Register Map Summary
Appendix B	Parameter-to-Register Cross Reference

List of Figures

Figure 2.1 - Jumper Locations on AutoMax Network Option Board	2-3
Figure 2.2 - DC Bus Voltage Terminals (1 to 5HP @ 460 V)	
Figure 2.3 - 1 to 5HP @ 460V GV3000/SE Drive	
Figure 2.4 – DC Bus Voltage Terminals (7.5 to 10HP)	
Figure 2.5 - 7.5 to 10HP @ 460V GV3000/SE Drive	
Figure 2.6 – DC Bus Voltage Terminals (1 to 20HP @ 230V)	
Figure 2.7 - 1 to 20HP @ 230 V GV3000/SE Drive	
Figure 2.8 – DC Bus Voltage Terminals (30 to 100HP@230VAC and	
75 .d 200 @ 460 VAC Drives)	2-17
Figure 2.9 – Location of Terminal Cover and Regulator Board Cover in	
75 to 200 HP (460 VAC) and 30 to 100 HP (230 VAC) Drives	2-18
Figure 2.10 – Regulator Board's Connections to Option Board, Keypad, and Base Board	2-19
Figure 2.11 - DC Bus Voltage Terminals (15 to 25 HP @ 460V)	2-22
Figure 2.12 - DC Bus Voltage Terminals (25 to 60 HP @ 460V)	
Figure 2.13 - 15 to 25 and 25 to 60 HP @ 460 V GV3000/SE Dr vs	
Figure 2.14 - 50 to 100 HP GV3000/SE Drive Components and Locations	
Figure 2.15 - 100 to 150 HP GV3000/SE Drive Components and Locations	
Figure 2.16 - 200 to 400 HP GV3000/SE Drive	2-30
Figure 2.17 - 2 to 15 Amp GV3000/SE Bookshelf Drive	
Figure 2.18 - 24 to 30 Amp GV3000/SE Bookshelf Drive	
Figure 2.19 – 24 to 30 Amp GV3000/SE Bookshelf Drive	
(Cover and Front Panel Removed)	2-36
Figure 2.20 – Installing the AutoMax Network Option Board in	
GV3000/SE Bookshelf Drive	2-37
Figure 2.21 – Connecting a GV3000/SE Drive to the AutoMax Network	2-38
Figure 3.1 – Signal Selection for Network Output Registers	3-10
Figure 4.1 – I/O Upgare Enable Logic Strings	4.2

List of Figures III

List of Tables

Table 1.1 – Hardware and Software Used with AutoMax Network Option Board	
(Purchased Separately)	•-2
Table 2.1 – Locating the Appropriate Installation Procedure	2-1
Table 2.2 - Model Numbers for 1 to 5HP@460VAC Drives	
Table 2.3 - Model Numbers for 1 to 20HP@230VAC Drives	. 2-12
Table 2.4 – Model Numbers for 30 to 100HP@230VAC and	
75 to 200 @ 460VAC Drives	
Table 2.5 - Model Numbers for 15 to 25 HP and 25 to 60 HP@460 V Drives	
Table 2.6 – Model Numbers for 2 to 15 Amp and 24 to 30 Amp Drives	. 2-32
Table 5.1 – Location of Information in the Register Map Tables	5-1
Table 5.2 - Register Assignment for Drop_1 Area Read Only Registers	
Table 5.3 - Register Assignment for Drop_1 Area Read/Write Registers	5-5
Table 5.4 - Register Assignment for Drop_2 Area Read Only Registers	
Table 5.5 - Register Assignment for Drop_2 Area Read/Write Registers	
Table 5.6 - Register Assignment for Drop_3 Area (Vector)	170-11-12
Reac Only Registers	.5-12
Table 5.7 - Register Assignments for Drop_3 Area (Vector)	00700000
Reac/Write Registers	.5-13
Table 5.8 - Register Assignment for Drop_3 Area (Volts/Hertz)	norm-se
Reac Only Registers	.5-15
Table 5.9 - Register Assignment for Drop_3 Area (Volts/Hertz)	000000
Reac/Write Registers	.5-16
Table A.1 – Key to Table A.2	A-1
Table A.2 – Register Map Summary	
The series of th	C15100 -

List of Tables

Introduction

This manual describes the AutoMax^{1M} Network Communication Option board (M/N 2AX3000). This board allows a GV3000/SE^{1M} drive to be operated and monitored over the AutoMax network.

For normal operation, the GV3000/SE drive can be completely controlled using the Network Option board. This allows use of only a natwork interface connection, hardwired emergency stop, and three-phase input and output power wiring. Start, stop, reset, fault codes, and complete control can be done over the AutoMax network.

1.1 AutoMax Network Communication Option Board Description

The AutoMax Network Communication Option beard (M/N 2AX3000) ships with one Network Drop Cable (M/N 2NC3000). The Network Drop Cable connects the GV3000/SE drive to the passive tap.

The Network Option board makes the GV3000/SE drive a slave drop on the AutoMax network. It is a printed circuit board assembly that mounts inside a GV3000/SE drive and connects to the drive's Regulator board using a ribbon cable. The Network Option board is powered from the standard drive power supply.

The Network Option board has a two-connection terminal strip that connects to a single twisted-pair Network Drop Cable (M/N 2NC9000). The Network Drop Cable is connected to a passive tap on the AutoMax network.

1.2 Where to Find Additional Information

You must be familiar with all the instruction manuals that describe your system, configuration. They can include:

- GV0000/SE AC General Purpose (Volts/Hertz) and Vector Duty Drive Software Start-Up and Reference Manual (D2-3359)
- GV3000/SE AC Power Modules Hardware Reference, Installation, and Troubleshooting instruction menual (D2-3360)
- GV3000/SE 230 VAC 1-20 HP General Purpose (VoltsA lertz) and Vector Duty Drive Software Start-Up and Reference Manual (D2-3387)
- GV3000/SE AC Drive Hardware Reference, Installation, and Troubleshooting.
 1-20 HP @ 230 VAC (D2-3388)
- GV3000/SE 460 VAC General Purpose (Volts/Hertz) and Vector Duty Drive Software Start-Up and Reference Manual (D2-3391)
- GV3000/SE AC Drive Hardware Reference, Installation, and Troubleshooting 75-200 HP @ 460 VAC (D2-3392)

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- GV3000/SE 230 VAC 30-100 HP General Purpose (Volts/Hertz) and Vector Duty Drive Softwere Start-Up and Reference Manual (D2-3416).
- GV3000/SE AC Drive Hardware Reference, Installation, and Troubleshooting 30-100 HP @ 230 VAC (D2-3417)
- GV3000/SE AC General Purpose (Volts/Hertz) and Vector Duty Bookshelf Drive Software Start-Up and Reference Manual (D2-3426)
- GV3000/SE AC Bookshelf Power Modules Hardware Reference, Installation, and Troubleshooting (D2-3427)
- Network Communications Module (J2-3001).
- ReSource AutoMax Programming Executive instruction manual
- Control and Configuration Software (CS8000) instruction manual (D2-3348).

1.3 Related Hardware and Software

When the Network Option board is installed in a GV3000/SE drive, the drive can be used with the hardware and software listed in table 1.1.

Table 1.1 - Hardware and Saltware Usep with AutoMax Network Option Board (Purchased Separately)

Option Name	Model Number	Description
75 Ohm Terminating Load	45071	A terminating load is required at both ends of an AutoMax network coaxial cable system.
AutoMax Processor	57C430A 55C431 57C435	
AutoMax Programming Executive	Various	Includes the tools required for programming in Enhanced Basic, Control Block, and Lacder Logic/PC languages.
Communications Passive Tap	57C380	Required at each network drop for connection to coaxial cabling.
Drive Control and Configuration Software	2CS3000	Windows-based software that allows you to connect any personal computer running Microsoft Windows version 3.1 or later to a GV3000/SF crive. Allows you to create, store, upload, and cownload drive configurations.
Network Communications Module	57C404 57C404A 57C404B	The master drop (and all AutoMax rack slave crops) on the AutoMax network must contain a Network Communications module. The Network Option board emulates the functions of the Network Communications Module for the GV3000/SF drive.
BeSource™ Interface Cable	61C127	Cable that connects a personal computer to the AutoMax Processor module

1.4 Getting Assistance from Reliance Electric

If you have any questions or problems with the products described in this instruction manual, contact your local Reliance Electric sales office. For technical assistance, call 1-800-726-8112.

Introduction 1-3

Installation

Contact Reliance if the drive installation must be in compliance with the European Community Electromagnetic Compatibility Standards.

The AutoMax Network option board installation procedure differs depending on the crive-type. Use table 2.1 to locate the appropriate procedure for your drive.

Table 2.* - Locating the Appropriate Installation Procedure

Rating	GV3000/SE N	lodel Number	Use the Procedure in Section
1 HP	1V21xx	1V24xx	2.4
1 HP	1V41xx	1V44xx	2.2
2 HP	2V21xx	2V24xx	2.4
2 HP	2V41xx	2V44xx	2.2
3 HP	3V21xx	3V24xx	2.4
3 HP	3V41xx	3V44xx	2.2
5 HP	5V21xx	5V24xx	2.4
5 HP	5V41xx	5V44xx	2.2
7.5 HP	7V21xx	7V2Zxx	2.4
7.5 HP	7V41xx	7V42xx	2.3
10 HP	10V21xx	1DV22xx	2.4
10 HP	10V41xx	10V42xx	2.3
15 HP	15V21xx	15V22xx	2.4
15 HP	15V41xx	15V42xx	2.6
20 HP	20V21xx	20V22xx	2.4
20 HP	20V41xx	20V42xx	2.6
25 HP	25G4" xx 25G42xx	25V41xx 25V42xx	2.6
30 HP	30V20xx		2.5
30 HP	30V41xx	30V42xx	2.6
40 HP	40V20xx		2.5
40 HP	40V41xx	40V42xx	2.6

Installation 2-1

Table 2.1 – Locating the Appropriate Installation Procedure (Continued)

Rating	GV3000/SE M	lodel Number	Use the Procedure in Section
50 HP	50R41xx		2.7
50 HP	50T41xx		2.7
50 HP	50V20xx		2.5
50 HP	50V41xx	50V42xx	2.6
60 HP	60G41xx	60G42xx	2.6
60 HP	60V20xx		2.5
75 HP	75R41xx		2.7
75 HP	75T41xx		2.7
75 HP	75V20xx		2.5
75 HP	75V40xx		2.5
100 HP	100V2Dxx		2.5
100 HP	100V4Dxx		2.5
125 HP	125R41xx		2.7
125 HP	125V4Dxx		2.5
150 HP	150V4Dxx		2.5
200 HP	200V40xx		2.5
200 HP	200V41xx		2.8
250 HP	250V41xx		2.8
300 HP	300V41xx		2.8
350 HP	350V41xx		2.8
400 HP	400V41xx		2.8
2 to 15 Amp	31ER40xx 31ET40xx 38ER40xx 38ET40xx 55ER40xx 55ET40xx	85ER40xx 85ET40xx 126ER40xx 126ET40xx 150ER40xx 150ET40xx	2.9
24 to 30 Amp	240FR40xx 240FT40xx	300FR40xx 300FT40xx	2.9

2.1 Setting AutoMax Network Option Board Jumpers

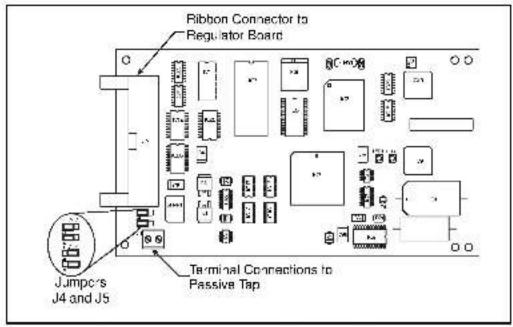
The AutoMax Network option board is shipped with jumpers J4 and J5 connecting pins 1 and 2 (see figure 2.1).

You must change the position of jumpers J4 and J5 to connect pins 2 and 3 before installing the AutoMax Network option board if your drive is one of these model numbers:

50R41xx	38ER40xx	126ET40xx
50T41xx	38ET40xx	150ER40xx
75R41xx	55ER40xx	150ET40xx
75T41xx	55ET40xx	240ER40xx
125R41xx	B5ER40xx	240ET40xx
31ER40xx	85ET40xx	300ER40xx
31ET40xx	126ER40xx	300ET40xx

To check the jumpers, remove the AutoMax Network option board from its anti-static wrapper. See figure 2.1 for jumper locations.

After changing or checking the jumpers, place the AutoMax Network option board back in its anti-static wrapper.



Higura 2.1 - Jumper Lacetions on AutoMax Network Uption Reard

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2.2 Installing the AutoMax Network Option Board in 1 to 5HP@460VAC Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: DC bus capacitors retain nazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before rouching any internal components. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive contains printed direct boards that are static-sensitive. An anti-static wrist band should be worn by any parson who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in the drives listed in table 2.2.

1V41xx 3V41xx 1V44xx 3V44xx 5V41xx 5V44xx 5V44xx

Table 2.2 - Model Numbers for 1 to 5 HP @ 460 VAC Drives

If the drive is panel-mounted, this procedure will be easier to perform if the drive is removed from the panel.

Unless otherwise indicated, keep all hardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

Important: Read and understand the warning labels on the cutside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag all incoming power to the drive.
- Step 1.2. Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Remove the cover by logsening the four cover screws.

Important: Read and understand the warning labels on the inside of the drive before proceeding.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the drive's AC input power terminals (R/L1, S/L2, T/L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - Use a voltmeter to measure the DC bus potential at the DC bus power terminals as shown in figure 2.2.

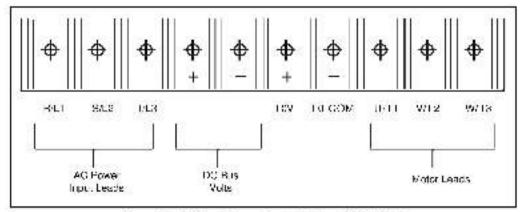


Figure 2.2 DC Bus Voltage Terminals (* to //HP © 460 V).

Step 3. Remove the Keypad Bracket from the Drive

- Step 9.1 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypad bracket.
- Step 9.2 Use a magnetic screwdriver to remove the three M4 x 10 screws that fasten the bottom of the keypad support bracket to the drive heat sink.

Important: The keypad support bracket is connected to the drive by wiring. Do not lift the bracket completely out of the drive to prevent damage to wiring.

- Step 3.3 Spread the retaining clips on the 26-conductor Regulator board ribbon cable connector to disconnect it from the Current Feedback board. The Current Feedback board is located on the right below the keypac.
- Step 3.4 Move the keypad support bracket aside.
- Step 3.5. Pinch the retaining dip that is through the center of the Current Feedback board and carefully pull out the Current Feedback board.
- Step 3.6 Unplug the internal fan assembly power connector (CONN7) from the drive.

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Step 4. Install the AutoMax Nelwork Option Board in the Keypad Bracket

Refer to figure 2.3 for component locations.

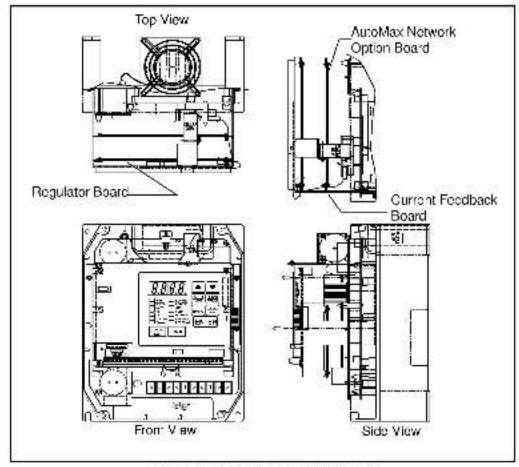


Figure 2.3 - 1 to 5HP @ 486V GV3000/SE Drive

- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 4.2 A ign the key on the connector of the AutoMax Natwork option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position:
- Step 4.3 Rours the 26-conductor ribbon cable for the Current Feedback board out of the side of the keypad bracket.
- Step 4.4 A ign the AutoMax Network option board on the four mounting tabs on the keypac bracket. Make sure that the ribbon cable is not pinched between the keypac bracket and the AutoMax Network option board.
- Step 4.5 Faster the right side of the AutoMax Network option board to the keypad bracks.. Use the two metal M3 screws and lock washers for grounding.

Important: You must use the lock washers to properly ground the option board. Improper grounding of the option board can result in erratic operation of the drive.

Step 4.6 Fasten the left side of the AuroMax Network option board to the keypactoracker using the two plastic rivets.

Step 5. Reinstall the Keypad Bracket in the Drive

Step 5.1 Reconnect the internal fan assembly power connector (CONN7) to the drive. Align the key on the connector with the slot in the receptable. Press the connector into position.



ATTENTION: Proper alignment of the Current Feedback board is critical. Verify that the connector pins on the Current Feedback board are correctly aligned with their corresponding connectors on the drive. Failure to observe this precaution can result in bod ly in ury.

- Step 5.2 Reinstall the Current Feedback board. Carefully align the two sets of connector pins on the Current Feedback board with their matching connectors on the drive. Gently press the board into place. The board should go in easily. If you fee ir resistance, a pin might be bent or misaligned. Recheck alignment and retry installation.
- Step 5.3 Inspect the Current Feedback board connector Incroughly for bent or misaligned pins.
- Step 5.4 A ign the keypad support bracket with the mounting holes in the drive heat sink. Faster the bracket with the three M4 x 10 screws removed earlier.
- Step 5.5 A ign the Regulater board's 26-conductor ribbon cable connector with the Current Feedback board connector. Press it in until it locks into position.
- Step 5.6 Roule the Network Drop Cable through the left-most opening at the bottom of the drive.
- Step 5.7 Connect the brown wire to terminal 1 of the 2-connector terminal strip. Connect the white wire to terminal 2.
- Step 5.8 Reconnect any wiring that was removed from the Regulator board.
- Step 5.9 NEMA 4X/12 drives only: Before installing the cover, check that the gaskets on the cover are flat and within the gasket channels.
- Step 5.10 Reinstall the cover. Aligh all cover screws into the heat sink before tightening any of them.

To maintain the integrity of NEMA 4X/12 drives, sequentially lighten the cover screws to ensure even compression of the gaskets. Do not exceed 2.2 Nm (20 in-lb) of torque on these screws.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

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2.3 Installing the AutoMax Network Option Board in 7.5 to 10HP@460VAC Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: DC bus capacitors retain nazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before roughing any internal components. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive contains printed direct boards that are static-sens tive. An anti-static wrist band should be worn by any parson who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in drives with model numbers 7V41xx. 7V42xx, 10V41xx, or 10V42xx.

If the drive is panel-mounted, this procedure will be easier to perform if the drive is removed from the panel.

Unless otherwise indicated, keep all hardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

Important: Read and understand the warning labels on the outside of the drivel before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag all incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Remove the cover by logsening the four cover screws.

Important: Read and understand the warning labels on the inside of the drive before proceeding.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the drive's AC input power terminals (R/L1, S/L2, T/L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - Use a voltmeter to measure the DC bus potential at the DC bus power terminals shown in figure 2.4.

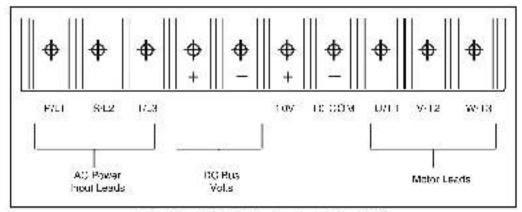


Figure 2.4 DC Bus Voltage Terminals (7.5 to 10 HP)

Step 3. Remove the Keypad Bracket from the Drive

- Step 9.1 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypad bracket.
- Step 9.2 Loosen the thumb screw on the left side of the keypad bracket. Hold the bracket on the left and lift the bracket up and to the left to separate it from the keypad support bracket.

Important: The bracket is connected to the drive by wiring. Do not attempt to lift the bracket out completely as this can damage or pull out wiring. Tie up or support the bracket to prevent damage to the wiring.

Step 9.3 Spread the retaining clips on the 26-conductor Regulator board ribbon cable connector to disconnect it from the Current Feedback board. The Current Feedback board is located on the right below the keypac.

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Step 4. Install the AutoMax Nelwork Option Board in the Keypad Bracket

Refer to figure 2.5 for component locations.

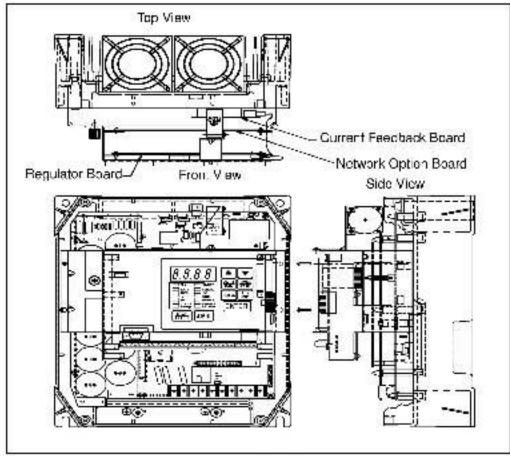


Figure 2.5 - 7.5 to 10HP @ 460V GV\$000/SE Dave

- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 4.2 A ign the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 4.3 Route the 26-conductor ribbon cable for the Current Feedback board out of the side of the keypad bracket.
- Step 4.4 A ign the AuroMax Network option board on the four mounting tabs on the keypac bracket. Make sure that the ribbon cable is not pinched between the keypac bracket and the AutoMax Network option board.
- Step 4.5 Faster the right side of the AutoMax Network option board to the keypadbracket. Use the two metal M3 screws and lock washers for grounding.

Important: You must use the lock washers to properly ground the option board.
Improper grounding of the option board can result in erratic operation of the drive.

- Step 4.6 Fasten the left side of the AuroMax Network option board to the keypacbracker using the two plastic rivets.
- Step 4.7 Reconnect the keypad bracket to the keypad support bracket by inserting the mounting tabs into the slots in the support bracket and rightening the thumb screw.
- Step 4.8 A ign the Regulator board's 26-conductor ribbon cable connector with the Current Feedback board connector. Press it in until it locks into position.

Step 5. Reinstall the Keypad Support Bracket in the Drive

- Step 5.1 Rours the Natwork Drop Cable through the left-most opening at the bottom of the drive.
- Step 5.2. Connect the brown wire to terminal 1 of the 2-connector terminal strip.

 Connect the white wire to terminal 2.
- Step 5.3. Reconnect any wiring that was removed from the Regulator board.
- Step 5.4 NFMA 4X/12 drives only: Before installing the cover, check that the gaskets on the cover are flat and within the gasket channels.
- Step 5.5 Reinstall the cover. Align all cover screws into the heat sink before tightening any of them.

To maintain the integrity of NEMA 4X/12 drives, sequentially tighten the cover screws to ensure even compression of the gaskets. Do not exceed 2.2 Nm (20 in-lb) of torque on these screws.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

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2.4 Installing the AutoMax Network Option Board in 1 to 20HP@230VAC Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive contains printed directly boards that are static-sens tive. An anti-static wrist band should be worn by any person who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in the drives listed in table 2.3.

1V21xx	7V21xx
1V24xx	7V22xx
2V21xx	10V21xx
2V24xx	10V22xx
3V21xx	15V21xx
3V24xx	15V22xx
5V21xx	20V21xx
5V24xx	20V22xx

Table 2.3 - Model Numbers for 1 to 20HP@230 VAC Drives

If the drive is panel-mounted, this procedure will be easier to perform if the drive is removed from the panel.

Unless otherwise indicated, keep all hardware that is removed. You will need it for reassembly. This includes scraws, lock washers, and rivets.

Important: Read and understand the warning labels on the outside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag at incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Remove the cover by loosening the four cover screws.

Important: Read and understand the warning labels on the inside of the drive before proceeding.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the drive's AC input power terminals (R/L1, S/L2, T/L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - Use a voltmeter to measure the DC bus potential at the DC bus power terminals shown in figure 2.6.

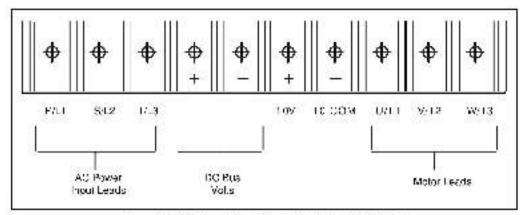


Figure 2.6 DC Bus Voltage Terminals (1 to 20HP @ 230V).

Step 3. Remove the Keypad Bracket from the Drive

- Step 3.1 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypac bracket.
- Step 3.2. Use a magnetic screwdriver to remove the M4 x 10 screws that faster the bottom of the keypac support bracket to the drive heat sink.
- Step 3.3 Spread the retaining clips on the Regulator board ribbon cable (on the right side) to disconnect it from the Base Board.
- Step 8.4 Remove the keypad bracket. Place it with the keypad down on a flat surface. If you cannot lay it flat, tie it up to prevent damage to wiring.

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Step 4. Install the AutoMax Nelwork Option Board in the Keypad Bracket

Refer to figure 2.7 for component locations.

- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 4.2 Align the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 4.3. Bours the other ribbon cable out of the side of the keypad bracket.
- Step 4.4 A ign the AuroMax Network option board on the four mounting tabs on the keyped bracket. Make sure that the ribbon cable is not pinched between the keyped bracket and the AutoMax Network option board.
- Step 4.5 Faster, the right side of the AutoMax Network option board to the keypad bracket. Use the two metal M3 screws and lock washers for grounding.

Important: You must use the lock washers to properly ground the option board.
Improper grounding of the option board can result in erratic operation of the drive.

Step 4.6 Faster the left side of the AutoMax Network option board to the keypac bracket using the two plastic rivets.

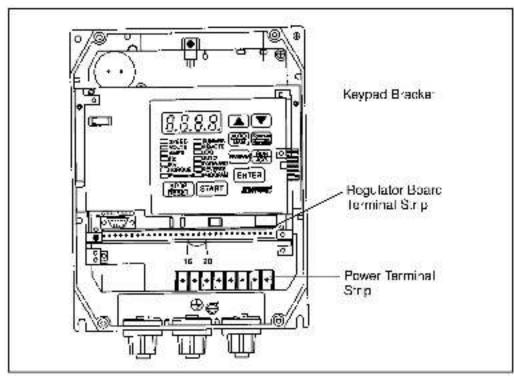


Figure 2.7 - 1 to 20 FP @ 230 V GV5000/SE Drive

Step 5. Reinstall the Keypad Bracket in the Drive

- Step 5.1 Place the keypad support bracket back into position. Use a magnetic screwdriver to fasten it to the heatsink with the screws removed earlier.
- Step 5.2 Realign the 26-conductor ribbon cable connector with the connector inside the slot in the keypad support bracket. Carefully press the ribbon cable connector in until the retaining clips lock into place.
- Step 5.3 Rours the Natwork Drop Cable through the left-most opening at the bottom of the drive.
- Step 5.4 Connect the brown wire to terminal 1 of the 2-connector terminal strip.

 Connect the white wire to terminal 2.
- Step 5.5. Reconnect any wiring that was removed from the Regulator board.
- Step 5.6 NEMA 4X/12 drives only: Before installing the cover, check that the gaskets on the cover are flat and within the gasket channels.
- Step 5.7 Reinstall the cover. Align all cover screws into the heat sink before tightening any of them.

To maintain the integrity of NEMA 4X/12 drives, sequentially tighten the cover screws to ensure even compression of the gaskets. Do not exceed 2.2 Nm (20 in-lb) of torque on these screws.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

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2.5 Installing the AutoMax Network Option Board in 30 to 100HP@230VAC and 75 to 200 @ 460VAC Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hezards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive contains printed directly boards that are static-sensitive. An anti-static wrist band should be worn by any parson who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in the drives I sted in table 2.4.

30 to 100HP@230VAC	75 to 200 @ 460 VAC
30V20xx	75V40xx
40V20xx	100V40xx
50V20xx	125V40xx
60V20xx	150V40xx
75V20xx	200V40xx
100V20xx	

Table 2.4 – Model Numbers for 30 to 100 HP@ 230 VAC and 75 to 200 ⊕ 480 VAC Drives

Unless otherwise indicated, keep all hardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

Important: Read and understand the warning labels on the cutside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag all incoming power to the drive.
- Step 1.2 Wait five in nutes for the DC bus capacitors to discharge.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the crive's AC input power terminals (R/L1, S/L2, T/L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - Use a voltmeter to measure the DC bus potential at the DC bus power terminals shown in figure 2.8.

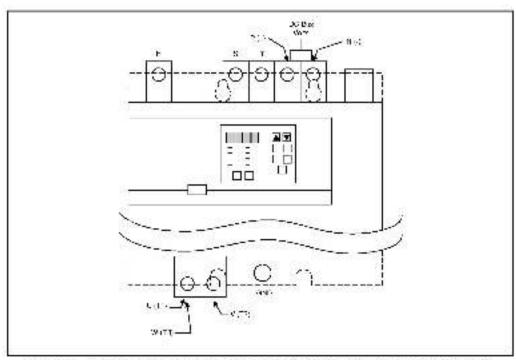


Figure 2.8 - DC Bus Vol.ape Terminals (30 to 100 HP@ 230 VAC and 75 to 200 @ 480 VAC Drives)

Step 3. Remove the Keypad Brackel from the Drive

Step 3.1 If the drive has:

- A Regulator board cover and terminal cover: Remove the three M4 screws from the Regulator board cover. Remove the cover. See figure 2.9.
- A terminal cover only: If you have this type of drive, this procedure is
 easier to perform if you lay the drive on its side. Remove the side cover
 from the drive. Use a long magnetized screwdriver to unfasten the four
 screws that hold the keypad bracket in.

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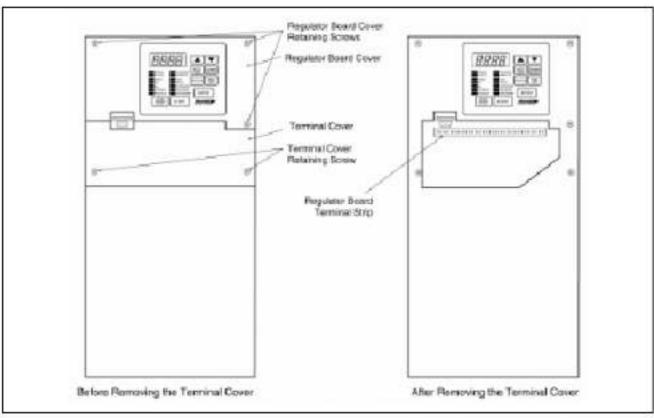


Figure 2.9 Location of Terminal Cover and Regulator Board Cover in 30 to 100 HP @ 250 VAC and 75 to 200 HP @ 460 VAC Drives

- Step 9.2 Remove the terminal cover, which is below the keypad and fastened with two M4 screws. See figure 2.9.
- Step 3.3 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keyped bracket.
- Step 3.4 Pull the keypac assembly partly out of the drive. Spread the retaining clips on the Regulator board ribbon cable (on the right side) to disconnect it from the Base Board. See figure 2.10.
- Step 3.5 Remove the keypad bracket. Place it with the keypad down on a flat surface. If you cannot lay it flat, tie it up to prevent damage to wiring.

Step 4. Install the AutoMax Nelwork Option Board in the Keypad Bracket

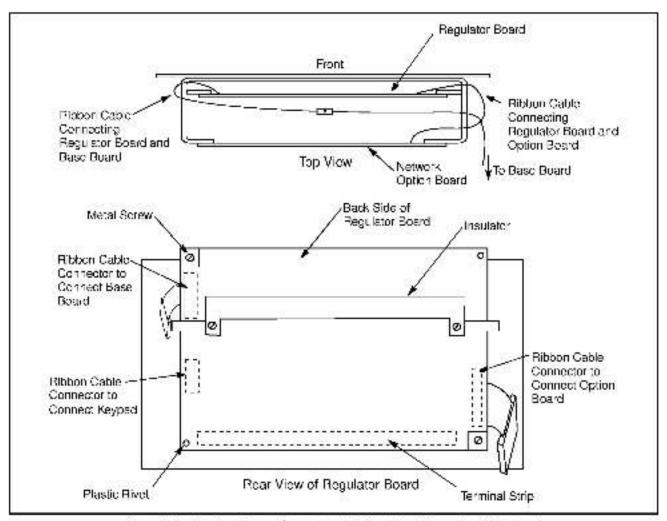
Refer to figures 2.9 and 2.10.

- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 4.2 A ign the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 4.3 Route the other ribbon cable out of the side of the keypac bracket.
- Step 4.4 A ign the AutoMax Network option board on the four mounting rabs on the keypad bracket. Make sure that the ribbon cable is not pinched between the keypad bracket and the AutoMax Network option board.

Step 4.5 Faster the right's delet the AutoMax Network option board to the keypad bracker. Use the two metal M3 screws and lock washers for grounding.

Important: You must use the lock washers to properly ground the option board.
Improper grounding of the option board can result in arranic operation of the drive.

Step 4.6 Faster the left side of the AutoMax Network option board to the keypact bracket using the two plastic rivets.



Higure 2.10 - Hegulstor Board a Connections to Option Board, Keypad, and Base Board

Step 5. Reinstall the Keypad Bracket in the Drive

Step 5.1 A ign the Hagulator beard ribbon cable connector with the connector to the Base board. Carefully press the ribbon cable connector in until the rotating clips lock into place.

Step 5.2 Place the keypad bracks; back into pesition.

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Step 5.3 If the drive has:

- A Regulator board cover and terminal cover: Replace the Regulator board cover. Fastern it using the three M4 screws removed earlier.
- Only a terminal cover: Use a long magnetized screwdriver to fasten the four screws that hold the keypad bracket. Replace the side cover on the drive.
- Step 5.4 Route the Network Drop Cable through the left-most opening at the bottom of the drive.
- Step 5.5. Connect the brown wire to terminal 1 of the 2-connector terminal strip.

 Connect the white wire to terminal 2.
- Step 5.6. Reconnect any wiring that was removed from the Regulator board.
- Step 5.7 Replace the terminal cover (below the keyped). Fastern it using the two M4 screws removed earlier.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

2.6 Installing the AutoMax Network Option Board in 15 to 25 HP and 25 to 60 HP @ 460 V Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Faiture to observe this precaution could result in severe bod by injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after inputpower has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bod by injury or loss of life.

ATTENTION: The drive contains printed circuit boards that are static sens tive. An anti-static wrist band should be worn by any person who touches the crive's components, connectors, or wiring. Enable machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in drives with the model numbers listed in table 2.5.

15 to 25 HP	25 to 60HP
15V41xx	25V41xx
15V42xx	25V42xx
20V41xx	30V41xx
20V42xx	30V42xx
25G41∞	40V41xx
25G42xx	40V42xx
	50V41xx
	50V42xx
	60G41xx
	60G42xx

Table 2.5 Model Numbers for 15 to 25 HP and 25 to 60 HP & 460 V Drives.

Unless otherwise indicated, keep all hardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

If the drive is panel-mounted, this procedure will be easier to perform if the drive is removed from the panel.

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Important: Read and understand the warning labels on the cutside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag at incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Remove the cover by logsening the four cover screws.

Important: Read and uncerstand the warning labels on the inside of the drive before proceeding.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the drive's AC input power terminals (R/L1, S/L2, T/L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - Use a voltmeter to measure the DC bus potential at the DC bus power terminals as shown in figures 2.11 (15 to 25 HP) and 2.12 (25 to 60 HP).

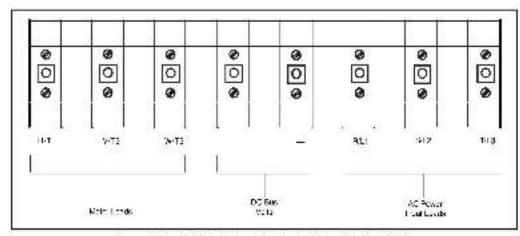


Figure 2.11 DC Bus Voltage Terminals (15 to 25 HP @ 460V;

Step 3. Remove the Keypad Bracket from the Drive

- Step 9.1 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypad bracket.
- Step 3.2 Loosen the thumb screw on the left side of the keypad bracket. Hold the bracket on the left and lift the bracket up and to the left to separate it from the keypad support bracket.

Important: The bracket is connected to the drive by wiring. Do not attempt to lift the bracket out completely as this can damage or pullout wiring. Tie up or support the bracket to prevent damage to the wiring.

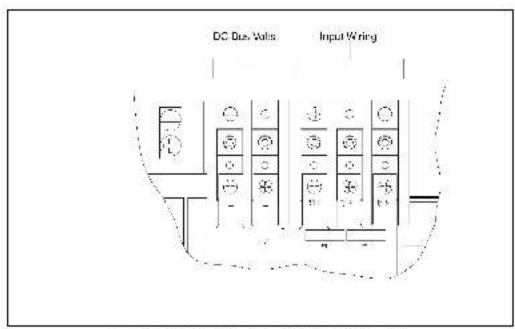


Figure 2.12 DC Bus Voltage Terminals (25 to 80 HP @ 480V).

Step 9.3 Disconnect the 26-conductor Regulator board ribbon cable from the Power Supply board (located on the right side below the keypad). You can see the connector through the slot on the keypad support bracket. Use a small screwdriver inserted through the slot to spread the retaining clips on the connector to release it.

Step 4. Install the AutoMax Network Option Board in the Keypad Bracket

Refer to figure 2.13 for component locations.

- Step 4.1. Remove the AutoMax Network option board Formits anti-static wrapper.
- Step 4.2 A ign the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 4.3 A ign the AutoMax Network option board on the four mounting tabs on the keypac bracket. Make sure that the ribbon cable is not pinched between the keypac bracket and the AutoMax Network option board.
- Step 4.4 Faster the right side of the AutoMax Network option board to the keypad bracket. Use the two metal M3 screws and lock washers for grounding.

Important: You must use the lock washers to properly ground the option board.
Improper grounding of the option board can result in arratic operation of the drive.

- Step 4.5. Fastern the left side of the AutoMax Network option board to the keypac bracket using the two plastic rivets.
- Step 4.6 Realign the 26-conductor ribbon cable connector with the Power Supply board connector inside the slot in the keypad support bracket. Carefully press the ribbon cable connector in until the retaining clips lock it into place.

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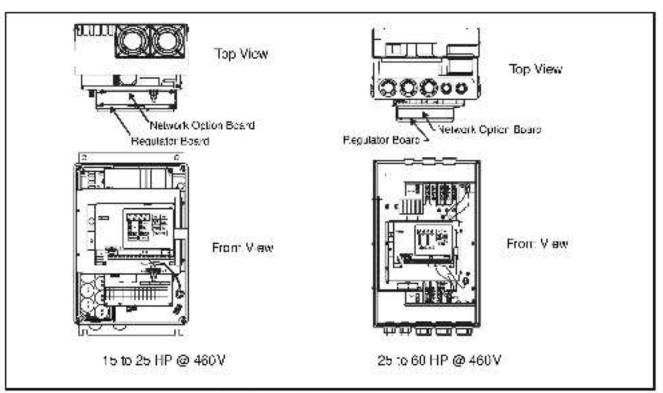


Figure 2.13 - 15 to 25 and 25 to 60 FP @ 480V (5V3000/6F Linive)

Step 5. Reinstall the Keypad Bracket in the Drive

- Step 5.7 Reconnect the keypad bracket to the keypad support bracket by inserting the mounting tabs into the slots in the support bracket and tightening the thumb screw.
- Step 5.8 Route the Network Drop Cable through the left-most opening at the bottom of the drive.
- Step 5.9 Connect the brown wire to terminal 1 of the 2-connector terminal strip.

 Connect the white wire to terminal 2.
- Step 5.10 Reconnect any wiring that was removed from the Regulator board.
- Step 5.11 NEMA 4X/12 drives only: Before installing the cover, check that the gaskets on the cover are flat and within the gasket channels.
- Step 5.12 Reinstall the cover. Align all cover screws into the heat sink before tightening any of them.

To maintain the integrity of NEMA 4X/12 drives, sequentially tighten the cover screws to ensure even compression of the gaskets. Do not exceed 2.2 Nm (20 in-lb) of torque on these screws.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

2.7 Installing the AutoMax Network Option Board in 50 to 100 HP and 100 to 150 HP @ 460 V Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before rouching any internal components. Failure to observe this precaution could result in severe bod by injury or loss of life.

ATTENTION: The drive contains printed circuit boards that are static-sens tive. An anti-static wrist band should be worn by any parson who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in drives with the model numbers 50R41xx. 50T41xx. 75R41xx. 75T41xx, or 125R41xx.

Unless otherwise indicated, keep all nardware that is removed. You will need it for reassembly. This includes scraws, lock washers, and rivets.

Important: Read and understand the warning labels on the cutside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag all incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Remove the cover from the drive by removing the six cover screws.

Important: Read and understand the warning labels on the inside of the drive before proceeding.

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Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verity that there is no voltage at the drive's AC input power terminals (1L1, 1L2, 1L3).
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - b. 50 to 100 HP @ 460 V only: Use a voltmeter to measure the DC businestertal at the diode bridge. Refer to figure 2.14.
 - c. 100 to 150 HP @ 460 V only: Take care not to touch any conductive traces. Use a voltmeter to measure the DC bus potential at the bottom of the fuse holders on the Power Module Interface board on the back of the Regulator panel. Refer to figure 2.15.

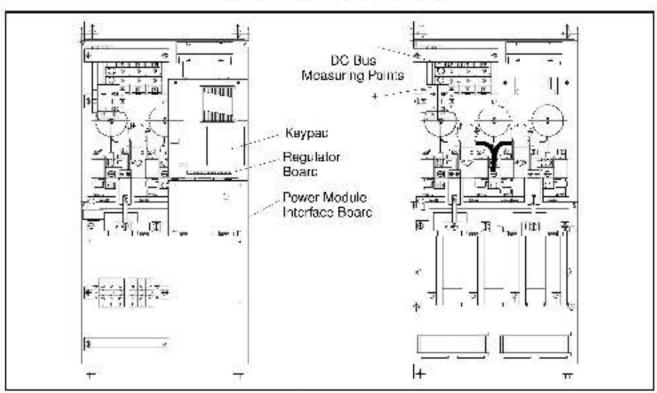


Figure 2.14 - 50 to 100 HP GV3000/SE Drive Companents and Locations

Step 3. Remove the Keypad Bracket from the Drive

- Step 9.1 Loosen the two screws from the top of the hinged panel (where the keypad bracket is mounted). Tilt the mounting panel forward out of the chassis.
- Step 3.2 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypac bracket.
- Step 3.3 Spread the retaining clips on the Regulator board's 60-conductor ribbon cable connector to disconnect it from the Power Module Interface board. This ribbon cable runs from the top of the Regulator board through a slot in the mounting panel to the Power board on the other side. Slip their board cable out of the slot to free it from the mounting panel.

Step 3.4. Use a magnetic screwdriver to remove the four screws and lock washers that faster the keypad bracket to the hinged mounting panel. Hold the keypad bracket as you remove the screws.

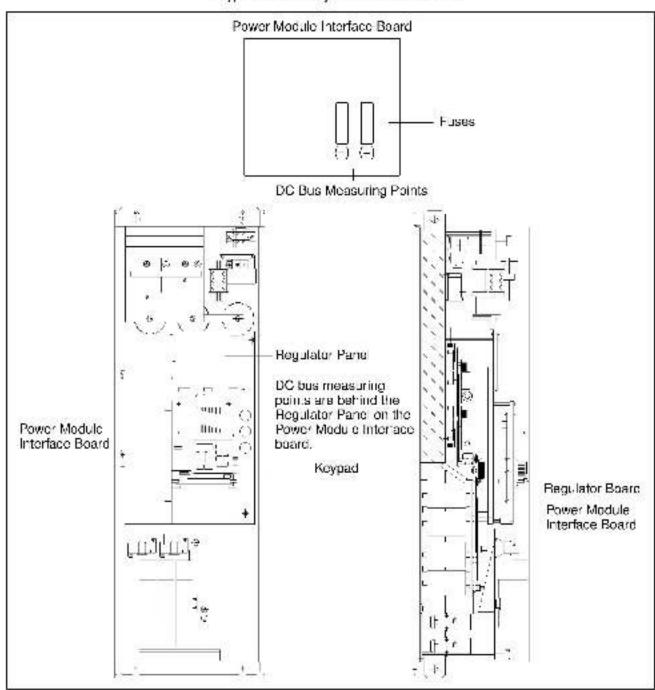


Figure 2.15 – 100 to 150 HP GV3000/SE Drive Components and Locations

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Step 4. Install the AutoMax Nelwork Option Board in the Keypad Bracket

- See figure 2.14 (50 to 100 HP drives) or 2.15 (100 to 150 HP drives) for part locations.
- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 4.2 A ign the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 4.3 A ign the AuroMax Network option board on the four mounting tabs on the keypad bracket. Make sure that the ribbon cable is not pinched between the keypad bracket and the AutoMax Network option board.
- Step 4.4 Faster the right side of the AutoMax Network option board to the keypad bracket. Use the two metal M3 screws and lock washers for grounding.
- **Important:** You must use the lock washers to properly ground the option board. Improper grounding of the option board can result in erratic operation of the drive.
- Step 4.5 Faster the left side of the AutoMax Network option board to the keypac bracket using the two plastic rivets.

Step 5. Reinstall the Keypad Bracket in the Drive

- Step 5.1 Reconnect the keypac bracket to the hinged mounting panel using the fourscrews and lock washers removed earlier.
- Step 5.2 100 to 150 HP drives: Remove the tie that was fastened to the Power Module Interface board earlier.
- Step 5.3: 100 to 150 HP drives: Align the Power Module Interface board on the eight plastic standoffs on the back of the mounting panel. Carefully press it into place. Make sure good contact has been made with the two grounding standoffs.
- Step 5.4 Route the Regulator board's 60-conductor ribbon cable through the slot in the hinged mounting panel to the connector on the Power Module Interface board. Align the two connectors. Place your thumb beneath the Power Module Interface board for support and carefully press the ribbon cable connector in until 1 locks into position.
- Step 5.5 Swing the hinged mounting panel back into position. Make sure no wires or cables are pinched by the panel.
- Step 5.6. Refaster the two screws at the top of the panel.
- Step 5.7 Route the Network Drop Cable through the right-most opening at the bottom of the drive, away from the AC lines.
- Step 5.8 Connect the brown wire to terminal 1 of the 2 connector terminal strip. Connect the white wire to terminal 2:
- Step 5.9 Reconnect any wiring that was removed from the Regulator board.
- Step 5.10 Replace mounting panel and faster with two screws at the top of the hinged panel (where the keypad bracket is mounted).
- Step 5.11 NFMA 4X/12 drives only: Before installing the cover, check that the gaskets on the cover are flat and within the gasket channels.
- Step 5.12 Reinstall the cover with the six screws removed in step 1.3. Make sure no wires or cables are pinched by the cover.
 - To maintain the integrity of NEMA 4X/12 drives, sequentially tighten the six cover screws to ensure even compression of the gaskets. Do not exceed 2.2 Nm (20 in-lb) of torque on these screws.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

2.8 Installing the AutoMax Network Option Board in 200 to 400 HP@460 VAC Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hezards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bod by injury or loss of life.

ATTENTION: The drive contains printed circuit boards that are static-sens five. An anti-static wrist band should be worn by any parson who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use this procedure to install the AutoMax Network option board in drives with part number 200V41xx, 250V41xx, 300V41xx, 350V41xx, or 400V41xx.

Unless otherwise indicated, keep all nardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

Important: Read and understand the warning labels on the outside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag at incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.

Important: Read and understand the warning labels on the inside of the drive before proceeding.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Open the drive's outer cabinet door.
- Step 2.2. Lower the plastic terminal strip shield at the top of the drive.
- Step 2.3. Use a voltmeter to verify that there is no voltage at the drive's AC input power terminals, R, S, and T.
- Step 2.4 Replace the plastic terminal strip shield.

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- Step 2.5 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves. (600 V).
 - Use a voltmeter to check the DC bus potential at the Voltmeter Test.
 Points on the Power Module Interface board. See figure 2.16.

Step 3. Remove the Keypad Bracket from the Drive

Heter to figure 2.16 for component locations.

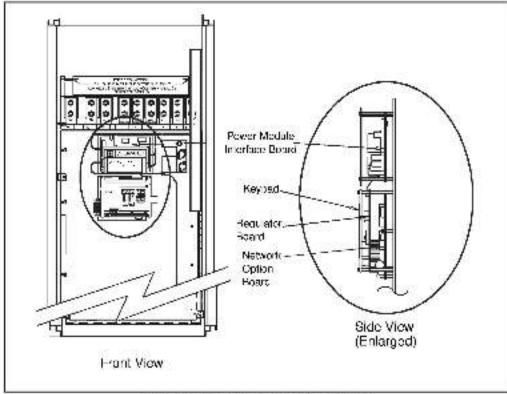


Figure 2.16 - 200 to 400 HP GV3000/SE Unive

- Step 3.1 Record connections to the Regulator board terminal strip if they must be disconnected to remove the keypad bracket.
- Step 3.2 Use a magnetic screwdriver to remove the four screws and lock washers that tasten the keypad bracket to the hinged mounting panel. Hold the keypad bracket as you remove the screws.
- Step 3.3 Disconnect the Regulator board ribban cable from the Power Medule Interface board.

Step 4. Install the AutoMax Nelwork Option Board

- Step 4.1 Remove the AutoMax Network option board from its anti-static wrapper.
 The AutoMax Network option board mounts on four standoffs behind the Regulator board.
- Step 4.2 A ign the AutoMax Network option board's four mounting holes with the four standoffs on the hinged mounting pane of the drive.

- Step 4.3 Faster the board to the drive with four $\frac{\pi}{2}$ nuts. Metal nuts must be used for proper grounding of the AutoMax Network option board.
- Step 4.4 Connect the brown wire to terminal 1 of the 2-connector terminal strip. Connect the white wire to terminal 2.
- Step 4.5 A ign the key on the connector of the AutoMax Network option board ribbon cable with the key on the Regulator board connector, Press the ribbon cable connector in until it locks into position.
- Step 4.6 Route the Network Drop Cable through the signal wiring tray on the right side of the drive.

Step 5. Reinstall the Keypad Bracket in the Drive

- Step 5.1 A ign the key on the connector from the Regulator board with the key of the connector on the Power Module Interface board. Press the ribbon cable connector in until it locks into position.
- Step 5.2 Reconnect the keypac bracket to the hinged mounting panel using the four screws removed earlier.
- Step 5.3. Reconnect any wiring that was removed from the Regulator board.
- Step 5.4. Close and secure the outer cabinet door of the drive.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

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2.9 Installing the AutoMax Network Option Board in 2 to 15 Amp and 24 to 30 Amp GV3000/SE Bookshelf Drives



ATTENTION: Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive is at line voltage when connected to incoming AC power. Disconnect, lock out, and tag all incoming power to the drive before performing the following procedure. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: DC bus capacitors retain hazardous voltages after input power has been disconnected. After disconnecting input power, wait five minutes for the DC bus capacitors to discharge and then check the voltage with a voltmeter to ensure the DC bus capacitors are discharged before touching any internal components. Failure to observe this precaution could result in severe bod ly injury or loss of life.

ATTENTION: The drive contains printed circuit boards that are static-sensitive. An anti-static wrist band should be worn by any person who touches the crive's components, connectors, or wiring. Erratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Use the procedure in this section to install the AutoMax Network option board in the drives listed in table 2.6.

2 to 15 Amp	24 to 30 Amp
31ER40xx 31ET40xx	240ER40xx 240ET40xx
98ER40xx 38ET40xx	300ER40xx 300ET40xx
55ER40xx 55ET40xx	
85ER40xx 85ET40xx	
126ER40xx 126ET40xx	
150ER40xx 150ET40xx	

Table 2.6 Model Numbers for 2 to 15 Amp and 24 to 30 Amp Drives.

This procedure requires access to the right side of the drive. Remove the drive from the panel if necessary.

Unless otherwise indicated, keep all nardware that is removed. You will need it for reassembly. This includes screws, lock washers, and rivets.

Important: Read and understand the warning labels on the outside of the drive before proceeding.

Step 1. Shut Down the Drive

- Step 1.1 Disconnect, lock out, and tag at incoming power to the drive.
- Step 1.2 Wait five minutes for the DC bus capacitors to discharge.
- Step 1.3 Disconnect all faceplate wiring.
- Step 1.4 2 to 15 A drives: Remove the cover by removing the cover screw on the faceptate of the drive. See figure 2.17.

24 to 30 A drives: Remove the cover by removing the cover screw on the faceptate of the drive. Then remove the front panel by removing the two screws on the faceptate of the drive. See figure 2.18.

Important: The cover is connected to the drive by the keypad/cisp ay cable. To disconnect the cover, use a screwdriver to slide the cable out of the connector.

Step 2. Verify That the DC Bus Capacitors are Discharged

- Step 2.1 Use a voltmeter to verify that there is no voltage at the crive's AC input power terminals (R/L1, S/L2, T/L3). Refer to figure 2.17 or 2.19 for the location of these terminals.
- Step 2.2 Ensure that the DC bus capacitors are discharged. To check DC bus potential:
 - a. Stand on a non-conductive surface and wear insulated gloves.
 - b. Use a voltmeter to measure the DC bus potential at the DC bus power terminals ((-)45, (+)47)) shown in figure 2.17 or 2.19.
- Step 2.3 24 to 30 amp drives: Reattach the front panel after chacking the DC bus potential.

halalaran 2-33

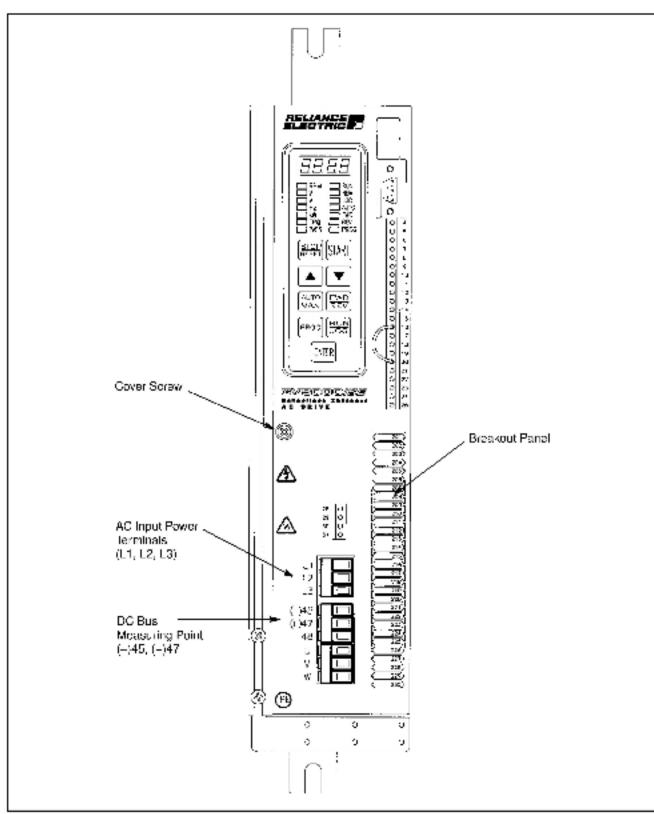


Figure 2.17 – 2 to 15 Amb GV3000/SE Bookshelf Drive

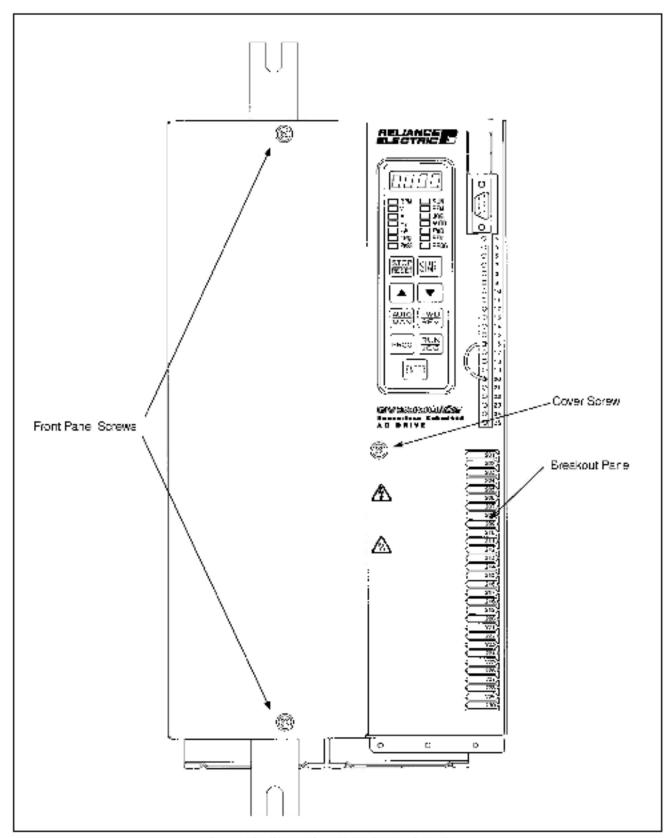


Figure 2.18 - 24 to 30 Amp GV3000/SE Bookshelf Drive

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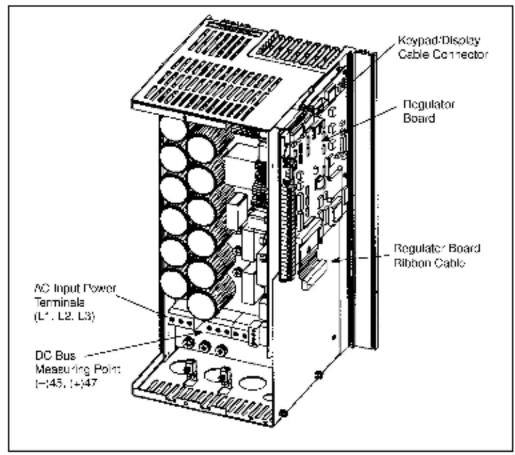


Figure 2.19 – 27 to S0 Amp GV3000/SE Bookshelf Drive (Coverland Front Panel Removed)



ATTENTION: The drive contains printed directly boards that are static sensitive. An anti-static wrist band should be worn by any person who touches the crive's components, connectors, or wiring. E-ratic machine operation and damage to, or destruction of, equipment can result if this procedure is not followed.

Step 3. Install the AutoMax Nelwork Option Board in the Drive

- Step 3.1 Remove the AutoMax Network option board from its anti-static wrapper.
- Step 3.2 A ign the key on the connector of the AutoMax Network option beard ribbon cable with the key on the Hegulator board connector. Press the ribbon cable connector in until it locks into position.
- Step 3.3 Faster the AutoMax Network option beard to the drive using the screws provided.
- Step 3.4 Connect the brown wire of the Network Drop Cable to terminal 1 of the 2-connector terminal strip. Connect the white wire to terminal 2.

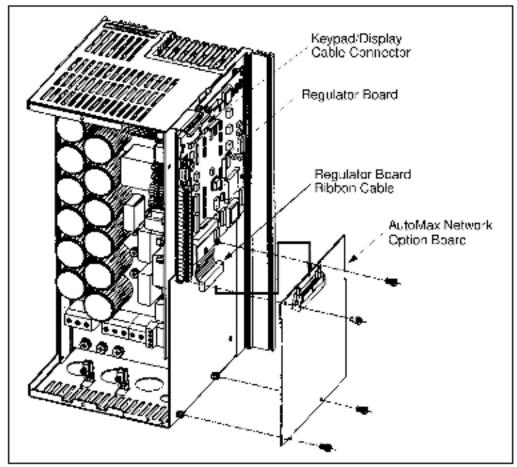


Figure 2.20 ... Installing the AutoMax Network Option Board in GV\$000/SE Bookshelf Drive.

Step 4. Reattach the Cover

- Step 4.1 Remove enough tabs on the faceplate breakout panel to allow the Network Drop Cable through.
- Step 4.2 Route the Network Drop Cable through the breakout panel.
- Step 4.3 Reconnect the keypad/display cable to the cover.

Important: For 24 to 30 amp drives, fold and slide the keypad/disp ay cable under the heatsink at the top of the drive before attaching the cover.

- Step 4.4 Reattach the cover using the single faceplate screw.
- Step 4.5 Reconnect all faceplate wiring.

This completes the hardware installation of the AutoMax Network option board. Do not remove the lockout and tag until you have completed section 2.10, which provides instruction on connecting to the AutoMax network.

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2.10 Connecting the GV3000/SE Drive to an AutoMax Network



ATTENTION: AutoMax networks with more than 5 drops might produce communication errors if 10-foot drop cables are used. Wherever possible, 30-inch drop cables or, if necessary, 5-foot drop cables should be used. Failure to observe this precaution could result in damage to, or destruction of, equipment.

See figure 2.21 for cabling and termination connections.

Refer to the Network Communications Module instruction manual (J2-3001) for a cetal cd description of how to add a drop to the AutoMax network.

To connect the GV3000/SE drive to an AutoMax network:

- Step 1. Step any application tasks that are running.
- Step 2. Use the 30-inch Network Drop Cable (M/N2NC3000) to connect to the Communications Passive Tap (M/N57C380).
- Step 3. If the drop is at the end of the coaxial cable system. It must be term nated, ferminate by connecting a 75 onm term nating load (M/N 45C71) to the remaining BNC connector on the passive tap.
- Step 4. Remove the lockout and tag. Apply power to the drive. SELF is displayed white the drive performs power-up diagnostics. If there is an error during diagnostics, it is logged. See the so tweetermanual for information on errors.

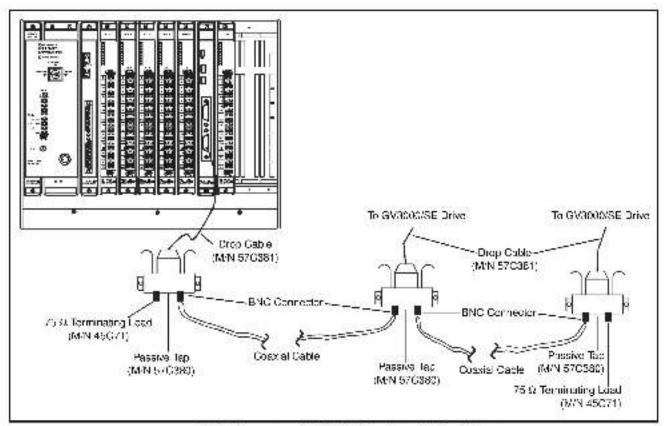


Figure 2.21 – Cannecting a GV900(VSF Drive to the AutoMax Network

Drive Configuration

This section describes how to configure a GV3000/SE drive for use with an AutoMax network.

When the Network Connection Type (P.061) parameter is configured for basic drive connection (P.061=0), the GV3000/SE drive occupies a single network drop. This first crop image is referred to as Drop_1 in this manual. The actual drop number is configured using the Network Drop Number (P.060) parameter.

When P.061 is configured for full crive connection (P.061–1), the GV3000/SE drive occupies three sequential network drops. They are referred to as Drop_1, Drop_2, and Drop_3 in this manual.

For network parameter descriptions, see section 3.3. For other crive parameter descriptions, see the drive software instruction manual (see section 1.2, "Where to Find Additional Information", for a listing of the manuals).

3.1 Configuring Network Communication

The drive will become active on the AutoMax network after you:

- Step 1. Install the Network Option board in the GV3000/SE drive and connect the board to the network using a passive tap. See chapter 2 for this procedure.
- Step 2. Apply power to the drive.
- Step 3. Set the Volts/Hertz or Vector Regulation (P.048) parameter for your application.
- Step 4. Assign a valid AutoMax network drop number to the drive through the Network Drop Number (P.060). You must set this parameter through the drive keypad or through the CS3000 software.
 - This drop number is the base drop the GV3000/SE drive will occupy.

 After P.060 is set, you can set parameters using the network.
- Step 5. Set the network connect on type using the Network Connection Type (P.061) parameter. This defines the scope of data to be communicated and control that the master has with the connected drive.
- Step 6. Apply power to the AutoMax network.
- Step 7. Set the Control Source (P.000) to option part (OP) using the drive keypad or the CS3000 software.

Serial communication is established and information can be exchanged with the network master. The drive transfers output data whenever this connection is made.

Prive Configuration 3-1

3.2 Drive Response to Loss of Network Communication

The Network Option board artempts to remain active on the AutoMax network at all times, regardless of the control source setting.

At power up, the drive delays for approximately 20 seconds before indicating a loss of network communication.

If communication is interrupted:

- Step 1. The Network Option board immediately notifies the drive regulator.
- Step 2. The Network Option board attempts to re-establish communication with the network master.
- Step 3. If Control Source (P.000) is set to Option port when the network is lost, the drive reacts to a network communication loss based on the setting of Option Port: Communication Loss Response (P.062).
- Step 4. The front panel REMOTE LED blinks, indicating that the network is inactive. If you have an OIM connected to the drive, the NE WORK indicator above the GONTEOL SOURCE SELECT key blinks, indicating that the network is inactive.

3.3 GV3000/SE Drive Network Parameters

Use these parameters to set up the GV3000/SE drive for use with the AutoMax network.

For DeviceNet applications, refer to the DeviceNet Network Communication Option Board manual (HE-HGV3DN).

For Contro Net applications, refer to the ControlNet Network Communication Option Board manual (D2-3390).

P.060 Network Drop Number

This parameter specifies the base drop number to which the AutoMax Network Communication board will respond on the AutoMax network.

Parameter Range: 1 to 55 (Rasid drive connection)

1 to 53 (Full drive connection).

Default Setting:

Parameter Type: Configurable

Refer also to parameters: R061 Network Connection Type

This parameter must be set at the crive through the keypac/display or a personal computer serial interface. This parameter cannot be written to the drive by the network master.

P.061 Network Connection Type

This parameter selects one of two AutoMax network connection types.

Parameter Range: 0 = Basic drive connection

1 = Full drive connection

Default Setting: 0

Parameter Type: Configurable

Refer also to parameters: N/A

Setting P.061 – 0 provides basic drive control from the AutoMax network. Only essent a drive data (reference, sequencing, basic tuning, and feedback data) are transferred over the network. This allows a higher density network with moderate functionality. Select the basic connection type if your application does not require a complete configuration of the drive over the network.

Using the basic drive connection, you can control functions such as start/stop, reset, reference, and basic tunable parameters such as accel, decel, minimum speed, and maximum speed.

When basic drive connection is selected, the GV3000/SE drive occupies a single network drop. This drop area contains 32 read registers and 32 write registers.

Setting R061 = 1 provides full drive control from the AutoMax network. Any drive data that has been assigned a network register is transferred over the network. Select this connection type if your application must be able to configure the drive over the network and have access to most parameters, operating variables, and diagnostic information.

The large amount of data transferred using the full connection type requires that the drive occupy multiple network drops, thus decreasing the potential number of devices on the network. When full drive connection is selected, the GV3000/SE drive will occupy three sequential network drops, beginning with the drop number specified with E060.

Drive Configuration 3-3

P.062 Option Port: Communication Loss Response

This parameter specifies how the crive responds to a network communication loss when the Control Source (P.000) parameter is set to OP (Option port).

Parameter Range: 0 = ET fault

1 - Hold last reference

2 = Use terminal strip reference

Default Setting: 0

Parameter Type: Tunable

Refer also to parameters: P.000 Control Source

If the option part is not in control of the drive, but is only monitoring drive operation, then loss of network communications has no effect on drive operation. In all cases, the Network Option board, upon loss of communication with the network master, will attempt to re-establish the communication link.

To eliminate extraneous fault conditions when a drive configured for network operation is powered up, the drive will delay for approximately 20 seconds after power up before annunciating a fault condition. A fault condition will be annunciated if network communication is not established before the 20-second power-up times expires, or if network communication was established and then lost.

If the drive loses communication with the network, overspeed protection for the drive will be in effect under all direcumstances. For V/Hz regulation, you program overspeed protection in H.022. For vector regulation, overspeed protection is fixed at 130% of Maximum Speed (P.004). When the motor goes above the overspeed limit, the drive faults and stops.

II P.062 = 0

The drive will consider a loss of network communication to be a drive fault, resulting in an IET-type stop sequence.

When P.062 is set to IET fault (0) and communication is lost:

- The drive latches a fault condition and performs a coast stop.
- The network communication loss fault is generated (nCL is displayed).
- The front panel REMOTE LED blinks, incleating that the network is inactive.

When network communication is re-established, you must reset the fault before the drive can be re-started. See the drive software instruction manual for information on resetting faults. (A fault reset does not clear the error log.)

P.062 Option Port: Communication Loss Response (continued)

HP.062 = 1

The drive continues to operate, using the last reference received from the network master.



ATTENTION: In volts/hertz regulation, if P.000 (Control Source) is set to OP (Option Port), and P.062 is set to 1 (hold last reference), and the drive oses communication with the network, the drive will maintain the last frequency command sent to it. Ensure that crive machinery, all drive-train mechanisms, and application material are capable of safe operation at the maximum operating speed of the drive. Failure to observe this precaution could result in bodily in ury.

ATTENTION: In vector regulation, if U.000 (Torque Reference Source) is set to 2 (Option Port), and P.062 is set to 1 (Hold Last Reference), and the drive loses communication with the network, the drive will no longer be regulating speed. Instead, motor speed will vary according to the load, up to the overspace limit. Ensure that driven machinery, all drive-train mechanisms, and application material are capable of safe operation at the maximum operating speed of the drive. Failure to observe this precaution could result in bodily in ury.

ATTENTION: When P.055 is set to ON, the STOP/RESET key is functional only from the selected control source. As a safety precaution, Reliance Electric recommends that an emergency stop pushbutton be located near the drive in an easily accessible location. As a further safety precaution, the user should post a warning on the drive to alert personnel that the STOP/RESET key is not functional. Failure to observe this precaution could result in severe bodily injury or loss of life.

The response to network communication loss is:

- The drive continues to operate, using the last reference received from the network master.
- An entry is made into the drive's error log for each active-to-inactive transition of network communication status.
- The front panel REMOTE LED blinks, indicating that the network is inactive.

If network communication is re-established, the drive will again follow the reference and sequencing control inputs supplied by the network master. Note that if P.054 = ON and the start and stop inputs are on (1), the drive will start.

Note that in this configuration, it might not always be possible to stop the drive over the network.

Prive Configuration 3-5

P.062 Option Port: Communication Loss Response (continued)

H P.062 = 2

The drive gets its speed/forcue reference from the terminal strip analog input and its stop input from the terminal strip stop input. All other inputs are held at the last values received from the network master.

This allows the network master to continue controlling the drive reference with a direct-wired analog output to input, and to stop the drive with a direct-wired digital output to input.

Note that if P.054 (Level Sense Start Enable) = OFF and the drive is stopped while in this mode, if cannot be re-started until network communication is re-established or the Control Source (P.000) is changed.



ATTENTION: If P.062 – 2 and P.054 (I evel Sense Start Fnable) – ON and network communication is lost while the drive is running, the terminal strip stop input will function as a STOP/RUN input. If the terminal strip stop input is opened, the drive will stop. If the terminal strip stop input is closed, the drive will re-start. Failure to observe this precaution could result in severe bodily injury or loss of life.

Note that in this configuration, it might not always be possible to stop the drive over the network.

The response to network communication loss is:

- The drive continues to operate, using the analog input from the Regulator board ferminal strip.
- An entry is made into the drive's error log for each active-to-inactive transition of network communication status.
- The front panel REMOTE LED blinks, indicating that the network is inactive.

If network communication is re-established, the drive will again follow the reference and sequencing control inputs supplied by the network master. Note that if P.054 – CN and the start and stop inputs are on (1), the drive will start.



ATTENTION: The drive is not equipped with a coast-stop pushbutton. You must install a hardwired operator-accessible pushbutton that provides a positive interrupt and shuts down the drive. See the drive nardware instruction manual for wiring information. Failure to observe this precaution could result in bodily injury.

P.063 Option Port: Network Reference Source

This parameter specifies where the crive gets its speed or torque reference when the option port is selected as the control source (P.000 = OP).

Parameter Range: 0 Direct reference

to 8 = Broadcast

Default Selting: 0

Parameter Type: Configurable

Refer also to parameters: U.000 Torque Reference Source

Speed or torque control is configured by parameter J.000 (Torque Reference Source) and by specifying TRQ/SPD in P.007 (Terminal Strip Digital Inputs Configure). One of the selections in U.000 is the option port.

If P.063 = 0, the reference is from register 33 of the drive's Drop_1 register map.

In V/Hz regulation, the value in register 33 represents speed in hertz scaled 0 to 4095 for 0 to Max mum Speed (P.004).

In vector regulation, if U.000 = 2, the value in register 33 represents torque scaled 0 to 4095 for 0 to 150% rorque. If $U.000 \neq 2$, this value represents speed in RPM scaled 0 to 4095 for 0 to Top Speed (U.017).

If P.063 = 1 to 8, the reference is from one of the eight network broadcast data registers (network drop area 0, registers 32 to 39).

Refer to the *AutoMax Network Communications Module* instruction manual (J2-3001) for a description of network broadcast registers.

Drive Configuration 3-7

P.064 Option Port: Network Trim Reference Source

This parameter specifies where the crive gets its trim reference when the option port is selected as the control source (P.000 = OP).

Parameter Range: 0 – Direct trim reference register

1 to 8 = Broadcast register 1 to 8, respectively

Default Selting: 0

Parameter Type: Configurable

Refer also to parameters: P.063 Option Port: Network Reference Source

U.000 Torqua Reference Sourca

The option partiti minerarence can be used as the outer control loop reference or the speed in minerarence (see P.014 Trim Reference Source in the drive software instruction manual).

If P.064 = 0, the trim reference is from register 34 of the first drop image.

If P.064 = 1 to 8, the trim reference is from network broadcast registers 1 through 8, respectively. For a description of the broadcast registers, refer to the *AutoMax Network Communications Module* manual (J2-3001).

In V/Hz regulation, the frim reference represents speed in herrz scaled 0 to 4095 for 0 to Maximum Speed (P.004).

In vector regulation, the trim reference represents speed scaled 0 to 4095 for 0 to Top Speed (U.017). When used for the outer control loop, the value should be scaled based on the scaling of the selected feedback.

See the drive software instruction manual for more information on drive regulation...

P.065 Option Port: Type and Version

This parameter c splays the option type and the software version number of the option board. Parameter Range: N/A
Default Setting: N/A

Parameter Type: Read-only

Refer also to parameters: N:A

The display format is N.vvv, where N represents the option type (1 - RMI, 2 = AutoMax natwork, 4 = DaviceNet natwork, and 5 = ControlNet network) and v represents the software version number.

For example, if 2.103 is displayed, it means the drive is using the AutoMax network option and is running version 1.03 software.

P.066 to P.069 Network Output Register 1 Source through Network Output Register 4 Source

These parameters select the signal written to the option port network output registers 1 through 4.

See figure 3.1.

Parameter Range:

0 = (P.066) Motor Kwid spiey value (P.067) Motor forque display value (P.068) Output power factor (P.069) Encoder counter (x4)

Speed reference rate limit output (vactor only).

2 = Speed reference at the relifidbk summing junction (includes CCL output and current compounding) (vector only)

3 - Speed loop feedback (vector only).

4 = Speed loop error (vector only)

5 - Speed Pliourpur (vector only).

6 = Outer control loop feedback (vector only)

7 - Outer control loop error (vector only)

8 = Outer control loop output (vector only):

9 - Terminal strip and og input normalized to speed (see drive software instruction manual)

10 = Terminal strip analog input scaled (see drive

software instruction manual) 11 = Torque reference (vector only)

12 = Torque feedback (vector only)

Default Selting: 0

Parameter Type: Tunable

Refer also to parameters: N/A

Drive Configuration 3-9

P.066 to P.069 Network Output Register 1 Source through Network Output Register 4 Source (continued)

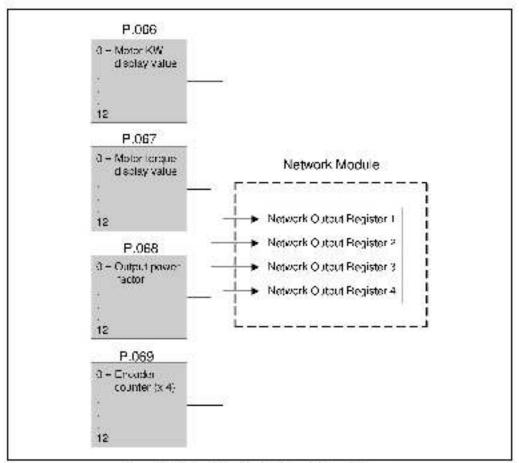


Figure 3.1 Signal Selection for Network Output Fegisters

Programming

This section describes the organization of data in the AutoMax Network Option Board and how the network accesses the data.

4.1 The Network and Other Control Sources

You can use the front pane, keypad/display to change parameter values when the Control Source parameter (P.000) is set to 2 (OP). However, if the tune/config input enable bit (Drop_1, register 32, bit 14) is on, any changes made through the keypad might be overwritten when the next network update occurs.

4.2 Network Transfer Rates

To write data to the drive, the Network Option board must be communicating with the master and the Control Source parameter (P.000) must be set to 2 (OP).

Data transfer rates between the AutoMax Network Option Board and Regulator board cepend on whather input or output data are being transferred.

Input data is one of three types:

- Control/Reference: This is data that requires the fastest update rates. This
 includes data such as the sequencing inputs (Stop, Run, Jog, Fwd/Rev) and
 speed/forque reference. These inputs are transferred every speed loop scan period
 (every 5ms), or as required by the drive. For example, if the drive is configured to
 obtain its torque reference from the option port, it will read this data from the option
 port every forque loop control scan (512µs).
- Tunable: This is data that can be changed while the drive is running or stopped.
 Tunable data includes parameters such as Accel Time 2 (RAMP 2) (R.017) and
 Overfrequency I mit (H.022). Tunable inputs are transferred approximately every
 350ms when the tune-config input enable bit (Drop_1, register 32, bit 14) is on.
- Configurable: This is data that cannot be changed while the drive is running.
 Configurable data includes parameters such as Terminal Strip Speed Reference Source (P.008) and Motor Nameplate Base Frequency (H.001). Configurable inputs are transferred from the Network Option board to the Regulator board approximately every 350ms while the crive is stopped and the tune/config input enable bit (Drop_1, register 32, bit 14) is on. Values sent from the network master while the drive is running are stored in the Network Option board but are not sent to the Regulator board until the drive is stopped.

Programming 4-1

Output data is one of two types:

- Runtime Signal: This is data such as the selected speed reference value, drive status (such as ready or running), drive fault flags, the state of terminal strip digital inputs, and motor status values (RPM, VOLTS, AMPS). This information is transferred every speed loop scan period (5ms).
- Tunable, Configurable, and Status: All other information provided by the drive.
 This typically includes all stored drive parameter values. For a full connect on type,
 this output data provides a complete image of how the drive is configured and
 operating. Tunable, Configurable, and Status data are transferred approximately
 every 350 ms.

Output data is transferred from the Regulator board to the Network Option board regardless of the status of the AutoMax network (active or inactive) or the selected drive control source (keypad, terminal strip, or network).

4.2.1 I/O Update Enable Logic Summary

The logic strings shown in figure 4.1 summarize the output and input enable logic described in section 4.2.

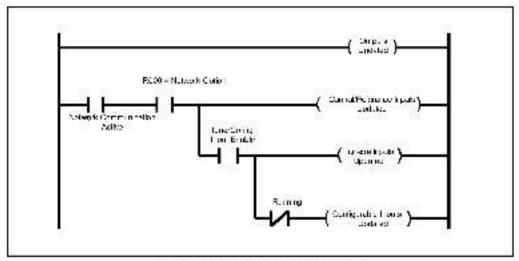


Figure 4.1 - I/O Update Enable Logic Strings

4.3 Setting Up Data Types That Can Be Transferred

You must enable the transfer of tunable and configurable inputs from the Network Option board to the Regulator board. Until you enable transfer, only control/reference cata will be read by the Regulator board.

To enable transfer of tunable and configurable data, set the network-master-controlled tune/configurable bit (Drop. 1, register 32, bit 14) to 1.

For example, the master application program would typically initialize the tunable and configurable parameter data in the master's Network module's dual port memory before setting the tune/config. nput enable bit to 1.

If you only want to transfer control/reference data, leave the tune/config input enable bit at 0 (off). This forces you to configure the drive through another control source, such as the front panel keypad/display or CS3000 software, but allows you to control the drive (run, log, stop, reset, and the reference) from the network master.

4.3.1 Tune/Config Update Synchronization Flag

This flag allows the network master application program to track when the drive has updated funable and configurable inputs. By toggling the tune/config update synchronization flag in the master and by monitoring the copied value from the drive, the master's application program can determine when the drive has read in that data. This feature has no effect on drive operation. The tune/config update synchronization flag is at Drop_1, register 32, bit 15.

The drive regulator:

- Step 1. Copies this bit to the tune/config update synchronization (lag loopback bit (Drop_1, register 0, bit 7).
- Step 2. Copies the tune/config update synchronization flag to the tune/config update synchronization flag loopback bit after it has read in and processed at tunable and configurable input registers.

To use the synchronization flag, set the tune/config input enable bit (Drop_1, register 32, bit 14) to 1.

Configurable inputs are only read in by the drive while it is not running. This will not affect the copying of the tune/config update synchronization flag to the tune/configurable synchronization flag toppback bit, since tunable inputs will still be transferred.

To determine when changes to tunable and configurable data in the drive have been completed, the master performs the following sequence:

- Step 1. Modify the funable and/or configurable register data in the appropriate network register(s).
- Step 2. Set the tune/config input enable flag (Drop_1, register 32, bit 14).
- Step 3. Toggle the tune/config update synchronization flag (Drop_1, reg.32, bit 15).
- Step 4. Monitor the fune/config update synchron zation flag loopback bit (Drop_1, register 0, bit 7) until it equals the value written in step 3.

The tune/config update synchronization flag is defined in the first drop of the drive network drop connection. Therefore, it can only be used to indicate when data for the first drop has been read in and processed by the drive.

Programming 4-3

Allernative Synchronization Methods

The tune/config update synchronization flag applies only to Drop_1. To determine if the drive received data written to other drops, you must use other methods.

Some a ternate methods are:

- Program a delay after writing to the network master's memory. If you know the
 number of drops on the network, and 350ms is added for processing time at the
 drive end, this time is predictable. (See your ReSource AutoMax Programming
 Executive instruction manual for information on calculating processing time.) Note
 that this method assumes that all requirements have been met for the drive to obtain
 its inputs from the network.
- Verify that output register data from the drive matches input data written to the drive.
 All parameter data written to the drive can be read back by the master in a different network register. This is usually the best alternative for full connection synchronization.

4.4 Monitoring Unacceptable Parameter Values

The parameter processing error status flag (Drop_1, register 14, bit 8) a lows the network master to monitor parameter values that are unacceptable to the drive.

When this flag is set to 1, one or more parameters sent to the drive were rejected.

When this flag is set to 0, all parameters sent to the drive were accepted.

The tune/config inputs enable bit (Drop_1, register 32, bit 14) must be set to 1 before the drive will read or process any tune/config parameters. The parameter processing error flag is updated approximately every 350 ms.

4.5 Timing Requirements

The transmit time required by the network master to transmit data to the GV3000/SE drive depends on the number of drops on the network.

Tunable and configurable drive input register values must be maintained by the network master's application program for the transmit time plus at least 350 ms to assure that they are read by the drive.

Control/reference data types do not have this 350ms requirement because they are read by the drive every 5 to 20ms.

To start the drive, the Start input must be set to 0 for at least 20ms, then set to 1 for at least 20ms (a 0-to-1 transition). The drive might delay acting on the 0-to-1 transition for up to 100ms because of variable processing delays. This also allows the drive to synchronize a drive start to the processing of new configurable data.

To clear the error log, the clear error log bit (Drop_1, register 32, bit 8) must be set to 0 for at least 350ms, then to 1 for at least 350ms (a 0-to-1 transition).

To perform a fault reset, the fault reset bit (Drop_1, register 32, bit 2) must be set to 0 for at least 20ms, then to 1 for at least 20ms (a 0-to-1 transition).

4.6 Drive Ready Status Bit

The Drive Ready status bit (Drop_1, register 0, bit 0) indicates that a 0-to-1 transition on the start input will start the drive. The Drive Ready bit is ON (1) when a Lof these conditions are met, and OFF (0) if any one of these is not met:

- No drive faults are active (Drop 1, register 0, b t 2 1).
- Stop input is on (Drop 1, register 32, bit 1 = 1).
- Front-panel stop/Reset button is not pressed or is disabled.
- Function loss terminal strip input is closed (Drop. 1, register 0, bit 12 1)
- A download from the serial port (using the CS3000 software) is not in progress.
- On larger drives (more than 50 HP) that contain a DC bus pre-charge resistor bypass relay, the pre-charge relay is closed.
- In JOC mode (Drop. 1 reg ster 0, bit 3 1), the vector parameter Torque Self-Tune Enable (U.008) is OFF.

4.7 Pulse Encoder Counter Register

The pulse encoder counter register (Drop_1, register 11 when P.069 is set to 0) is a 16-bit up/down roll-over counter of motor pulse encoder pulses received. The value in this register is the number of pulses times 4.

The counter counts up when the motor is rotating in the forward direction (CCW when viewing the motor from the shaft end). For example: 0, 1, 2, ... 65534, 65535, 0, 1 ...

The counter counts down when the motor is rotating in the reverse direction. For example: 65535, 65534, 65533, ... 2, 1, 0, 65535, 65534 ...

4.8 Network Register Organization

The register maps in tables 5.2 through 5.9 describe the registers and bits used by the GV3000/SE drive on the AutoMax network.

Registers 0 to 31 are read-only, while registers 32 to 63 are read/write. Refer to instruction manual J2-3001 (*Network Communications Module*) for a detailed description of network register assignments.

U parameters are updated only when the Volts/Hertz or Vector Regulation P.048 parameter is set to 1 (Vector).

Hiparameters are updated only when the Volts/Hertz or Vector Regulation R.048 parameter is set to 0 (V/Hz).

The data in Drop_3 depends on whether the selected regulator type is Vector or V/Hz.

Voits/Hertz or Vector Regulation P.048 can be set from either the front panel keypad/display or the CS3000 software. It cannot be set over the AutoMax network.

Programming 4-5

Update times assume communication is active. Outputs are transferred whenever communication is active. Inputs are only transferred when communication is active and P.000 is set to 2 (OP). See section 4.3 for information on setting up transferrable catally yees.

4.9 GV3000/SE Drive Parameters Not Accessible Over the Network

The following GV3000/SE drive parameters are not accessible over the AutoMax network at any time.

P.008, Second Menu Password:

P.007, Terminal Strip Digita, Inputs Configure

R008, Terminal Strip Speed Reference Source

P.017, Accel Time 2 (RAMP 2)

R018, Decel Time 2 (RAMP 2).

P.023, MOP Accel/Decel Time

P.024, MOP Reset Configuration

P.031, Preset Speed 1

P.032, Preset Speed 2

P.033, Preset Speed 3

P.034, Preset Speed 4

P.035, Preset Speed 5

P.035, Praset Speed 6

P.037, Preset Speed 7

P.035, Presct Speed 8

R050, Restore Defaults

P. 550, Residie Delaulis

P.051, Programming Disable

P.363, Network Dree Number 1 P.363, Diagnostics Source

P.091, Diagnostics Display

U.608, Torque Self Tune Engale

H.020, Identification Request

RMI (r.) parameters

Register Map Tables

This section presents the register map tables. Brief descriptions of parameters are provided in the register map tables. For detailed parameter descriptions, refer to the software manual. For parameter descriptions of network-specific parameters, see section 3.3.

These map tables are for version 6.03 of the Regulator board. Earlier versions of the board might have different parameter options.

5.1 Finding Data in the Register Map Tables

The register maps are listed in tables 5.2 through 5.9. The register maps describe the registers and bits used by the GV3000/SE drive on the AutoMax network.

Table 5.1 — Location of Information in the Register Map Tables

Drop	Data Type	Table	Page
1	Read Only	5.2	5-2
	Road/Write	5.3	5-5
2	Read Only	5.4	5-8
	Read/Write	5.5	5-1D
3: Vector	Road Only	5.6	5-12
	Road/Write	5.7	5-13
3: V/Hz	Read Only	5.8	5-15
	Road/Write	5.9	5-16

Register Map Tables 5-1

Table 5.2 – Register Assignment for Drop it Area Read Only Registers

Regisler	Bit	Description or GV3000/SE Parameter	Settings	Update*
0		Status word 1 (includes terminal strip digital inputs)		5ms
[0	Drive roady		5ms
Ī	1	Drive running		5ms
[2	Fault active		5ms
[3	Funyjog mode status	1 – Jog	5ms
[4	Forward/reverse reference invert command	1 = Reverse	5ms
[5	Stop sequence in progress		5ms
[8	Tune/config input enable (copied from Drop_1, register 32, bit 14)		5ms
[7	Tuno/config update synchronization flag (cooled from Drop. 1, register 32, bit 15)		5ms
[8	Terminal strip digital input 1 (start)		5ms
[9	Terminal strip digital input 2 (stop)		5ms
[10	Terminal strip digital input 3 (fault reset)		5ms
[11	Terminal strip digital input 4 (run/jeg select)		5ms
[12	Terminal strip digital input 5 (function loss)		5ms
[13	Torminal strip digital input 6		5ms
[14	Terminal strip digital input 7		5ms
	15	Terminal strip digital input 6		5ms
1		Selected speed reference value	Vector: 4095=Motor Top Speed (U.017)	5ms
2.		Speed reference sum. Limit block output, including trim and draw	WHz:4095=Maximum Speed (P.004)	5ms
3		Speed feedback	Vector: 4095 =Motor Top Speed (U.017)	5ms
4		Terminal strip analog input value (conditioned with offset, gain, and inversion)	_4095 = ±10V	5ms
5		Output speed/irequency (front panel RPM display)		5ms
6		Output voltage (front panel VOLTS display)		5ms
7		Output current (front panel AMPS display = amps x 10)		5ms
8		Notwork output register 1 (value determined by Drop. 2, register 45, bits 0 to 7, (P.066))		5ms
9		Notwerk output register 2 (value determined by Drop. 2, register 45, bits 8 to 15 (R967))		5ms
-0		Notwork output register 3 (value is dotermined by Drop. 2, register 46, bits 0 to 7 (P.088)).		5ms
100		Notwork output register 4 (value determined by Dreo 12, register 46, bits 5 to 15 (P.069))		5ms

*Update Times: 5 ms = 5 ms. 350 ms = 350 ms or less.

Table 5.2 – Register Assignment for Drop 1 Area Read Only Registers (Continued)

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
12		Drive fault latch bits – word 1		
Ī	0	Overcurrent, steady state (OC)		350ms
1	1	Overcuirent, at acceleration (OCA)		350mis
	2	Overcurrent, at deceleration (OCd)		350ms
1	3.	Overcurrent, at DC braking (OCb)		350ms
	4	High DC bas vollage (HU)		350ms
	5	Low DC bus voltage (LU)		350ms
1	6	Electronic thermal overload (OL)		350ms
1	7	Drive evertemperature (OH)		350ms
1	8	Function loss (FL)		350ms
	9	Default parameter restore — chocksum error (CHS)		350ms
1	10	Communication loss between Regulator/PC/OIM (Srt.)		350ms
1	11	Spurious host PC comminterrupt (CAr)		350ms
1	12	Self-tuning status (SF), Vector only,		350ms
1	13	Overspeed (OSP). Vector unity.		350m
1	14	Motor cutput phase loss (OPI)		350m:
	15	Overfrequency (OF)		350ma
13		Drive fault latch bits — word 2		
	0	Network communication loss (nCL)		350ms
	1	DC bus charging bypass contactor (bYC)		350m
	2	High time identification aborted (HId)		350m
	3.	Identification Request not yet performed (nld). V/Hz only.		350ma
	4	High line voltage (HIL)		350ma
1	5	NVRAM write failure (EEr)		350m
ı	6	Drive power electronic overload (PUc)		350ms
ı	7	Earth current failure (ground fault) (EC)		350ms
Ī	8	Asymmetrical busicharge (UbS)		350m:
ı	9	Missing Power Module ID connector (PUc)		350ms
ı	10	Power Module not identified (PUn)		350ms
ı	11	Input phase loss (IPI)		350m
ı	12	Encodor loss (ELI		350ms

Table 5.2 – Register Assignment for Drop 1 Area Read Only Registers (Continued)

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
13 (conft.)	13	Analog input signal less (Aln)		350ms
	14	Reserved		
	15	Fatal system error		350ms
14	0 to 7	Number of error log entries		350ms
	8	Parameter processing error flag		350ms
	9 to 15	Acserved		
15	0.007	Error log entry (second most recent error)		350ms
	8 to 15	Error og entry (most recent error)		350ms
18		Control Source (P.666)	0 = Front-panel (Local); 1 = Terminal strip; 2 = Option Port (Network master) 3 = Serial Port (PC HOST)	350ms
:7		Accel Time 1 (RAMP 1) (R001)	1 = 0.1 seconds	350ms
:8		Decel Time (RAMP 1) (P.002)	1 - 0.1 seconds	350 ms
: 9		Minimum Speed (P.003)	V/Hz: 1 = 0.1 Hz. Vector: 1 = 1 RPVI	350ms
20		Maximum Speed (R004)	V/Hz: 1 = 0.1 Hz. Vector: 1 = 1 RPVI	350ms
2-		Current Limit (P.005)	1 - 1%	350ms
22		Trim Gain Percentage (P.015)	1 = 0.1%	350ms
23		Draw Gain Percentage (R618)	1 = 0.1%	350ms
24		Speed Regulator Proportional Gain (U.012). Vector only.	1 = 0.01	350ms
25		Speed Regulator Integral Gain (U.013), Vector only.	1 = 0.01	350ms
28		Status word 2		
	0	Torque or speed regulation. Vector only.	1 = speed	5ms
	1	Auto or manual (local) reference selected	1 = manual	5ms
	2	Outer control loop enabled	1 = chabled	5ms
	3 to 15	Reserved		
27		Elapsod Time Meter (R.029)	days	350ms
28		Notwork Connection Type (R081)	0 = basic; 1 = full	350ms
29		Option Port: Communication Loss Response (P.062)		350ms
30	0 to 7	Option Port: Network Reference Source (R063)	θ = direct; 1 to 8 = broadcast 1 to 8	350 ms
	8.to 1.5	Option Port: Network Trim Reference Source (P.884)	0 = direct; 1 to $8 = $ broadcast 1 to 8	350 ms
3-		Software Version Number (P.098)	601 = Version 6.01	350ms

Table 5.3 – Register Assignment for Drop [1 Area Read/Write Registers]

Regisler	Bil	Description or GV3000/SE Parameter	Settings	Update [†]
32		Sequending control word		5ms
	ď	Start	Hun: 0 to 1 transition to start og: 0 = stop; 1 = start	5ms
	1	Step	0 = stop; 1 = no stop	5ms
	2	Fault reset	U to 1 transition to reset	5ms
	3	Run/jog select	1 = [cg	5ms
	4	Forward/reverse select	1 = reverse	5ms
	ត	Outer control loop (OCL) enable		5ms
	-6	Reserved	Must be 0	5ms
	7	Speed regulation select. Vector only.	0 = torque regulation based on U.000 1 = speed regulation regardless of U.000	5me
	8	Clear error log. Must be maintained for 350 ms to assure detection by the drive	0 to 1 transition to olean	350ms
	9 to 13	Heserved	Must be 0	
	14	Tune/config input enable	0 – read only control/refidata from network registers 1 – read all inputs from network registers	Т
	15	Tune/config update synchronization flag (write)		Т
33		Option port speed/forque direct reference	Vector: 4095 – Votor Top Speed (U.017) V/Hz:4095 – Maximum Speed (H.004)	5/0.5
34		Option portitif m and OCL direct reference	Vector: 4095 – Motor Top Speed (U.017) V/Hz:4095 – Maximum Speed (P.004)	5ms
35		Network Inertia compensation		5ms
38		Reserved	Must be 0	
37		Accel Time 1 (HAMP 1) (P.001)	1 = 0.1 seconds	1
36		Decel Time (RAMP 1) (P.002)	1 = 0.1 seconds	T
39		Minimum Speed (E003)	V/Hz: 1 = 0.1 Hz. Vector: 1 = 1 HPM	1
40		Max'mum Speed (P.004)	V/Hz: 1 = 0.1 Hz. Vector: 1 = 1 RPM	T
41		Current Limit (P.005)	1 = 1%	T
42		Terminal Strip Analog Input Offset (P.009)		Т

*Only the low byte (bits 0 to 7) of this register is transferred. The high byte is 'ghored by the drive.

 † Update Times: 5 ms = 5 ms. 5/0.5: 5ms if speed reference; 0.5 ms if torque reference. 350 ms = 350ms or less. T = 350ms or less when tune/config enable is on. C = 350ms or less when tune/config enable is on and the drive is stopped.

Table 5.3 - Register Assignment for Drop. 1 Ares, Read Write Registers (Continued)

Register	Bil	Description or GV3000/SE Parameter	Settings	Update [†]
43		Terminal Strip Analog Input Gain (P010)	1 = 0.001	T
44		Terminal Strip Analog Input Configure (R011)	See software manual for settings.	T
45		Trim Gain Percentage (R015)	1 = 0.1%	Ţ
46		Draw Gain Percentage (P.016)	1 = 0.1%	T
47		Speed Regulator Proportional Gain (U.012). Vector only.	1 = 0.01	T
48		Speed Regulator Integral Gain (U.018). Vector only.	1 = 0.01	T
49		Jog Speed Reference (P020)	V/Hz: 1 = 0.1 Hz; Vector: 1 = 1 HPM	T
50°	G to Z	Stop Type (RD25)	0 = coast: 1 = ramp	T
	8 to 15	Reserved		
51"	G to 7	Function Loss Response (P.026)	0 = fault; 1 = coast without fault	T
	8 to 15	Reserved		
52		Speed Display Scaling (R028). Affects front-panel HPM display value reflected in Drop_1, register 5 (master read).		T
53		Control word		
	G	P.030, Elapsed Time Meter Reset	Heset: transition from 0 to 1	T
	1	Network inertia comp register chable (chaples use of Drop_1, register 35)		-5ms
	2	Network speed Pillimit control enable (enables use of Drop_1, registers 59 & 60)		5ms
	3 to 15	Reserved	Must be 0	
54 and 55		Heserved	Must be 0	
56"	0 to 7	Output Fieley Configuration (F.013)	0 - fault;1 & 2 - running; 3 - nework active	С
	8 to 15	Heserved		
57*	Cite 7	Trim Reference Source (R014)		C
	8 to 15	Heserved		
58	G to 7	Torque Reference Source (C.000). Vector only.		C
	8 to 15	Outer Control Loop Feedback Select (U.040), Vector only.		С
59		Option port speed Pt high fmit. Vector only.		5ms
50		Option port speed Pi low limit. Vector only.		5ms

*Only the low byte (bits 0 to 7) of this register is transferred. The high byte is ignored by the drive.

 † Update Times: 5 ms = 5 ms. 5/0.5: 5ms if speed reference; 0.5 ms if torque reference. 350 ms = 350ms or less. T = 350ms or less when tune/config enable is on. C = 350ms or less when tune/config enable is on and the drive is stopped.

Table 5.3 - Register Assignment for Drop. 1 Ares, Read Write Registers (Continued)

Register	Bil	Description or GV3000/SE Parameter	Settings	Update [†]
51"	0 to 7	Network Connection Type (P.061)	0 - basic; 1 - full	c
	8 to 15	Reserved		
52"	0 to 7	Option Port: Communication Loss Response (E062)		Ţ
	8 to 15	Reserved		
63	G to 7	Option Port: Network Reference Source (P.063)	0 = direct; 1 to 8 = broadcast 1 to 8	c
	8 to 15	Option Port: Network Trim Reference Source (P.064)	0 = direct; 1 to 8 = broadcast 1 to 8	С

*Only the low byte (bits 0 to 7) of this register is transferred. The high byte is 'ghored by the drive.

 † Update Times: 5 ms = 5 ms. 5/0.5: 5ms if speed reference; 0.5 ms if torque reference. 350 ms = 350ms or less. T = 350ms or less when tune/config enable is on. C = 350ms or less when tune/config enable is on and the drive is stopped.

Table 5.4 – Register Assignment for Drop 12 Area Read Only Registers

Register	Bit	Description or GV3000/SE Parameter	Settings	Update*
0		Vector terque reference	4095 = 150% terque	5 ms
1		Voctor torque feedback	4095 = 150% turque	ōms
2		Reserved		
3	3 to 7	Network Output Register 1 Source (P.666)		350 ms
	8 to 15	Network Output Register 2 Source (P.067)		350 ms
4	0 to 7	Network Output Register 3 Source (P.068)		350 ms
	8 to 15	Network Output Register 4 Source (P.069)		350ms
5		Terminal Strip Analog Input Offset (P.009)		350 ms
6		Terminal Strip Analog Input Gain (P.010)	1 = 0.001	350 ms
7		Terminal Strip Analog Input Configure (P.011)	See software manual for settings.	350 ms
6		Terminal Strip Analog Output Source (R012)		350 ms
9		Output Relay Configuration (R013)		350 ms
10		Trim Reference Source (P.014)		350 ms
11		S Curve Enable (R019)	1 = chabled	350ms
12		⊌cq Speed Reference (P.020)	V/Hz: 1 = 0.1 Hz; Vector: 1 = 1 RPM	350ms
13		ucg Ramp Accel Time (P.021)	1 = 0.1 seconds	350ms
14		Jog Ramp Deccl Time (R022)	1 = 0.1 seconds	350ms
1.5	3 to 7	Step Type (R025)	0 = coast; 1 = ramp	350 ms
	8 to 15	Reserved		350 ms
18		Function Loss Response (P.026)		350 ms
17		Forward/Reverse Configuration (P.027)	See drive software instruction manual	350 ms
18		Speed Display Scaling (P.026). Affects front panel RPM display value reflected in Drep. 1, register 5 (master road).		350 ms

*Update Times: 5 ms = 5 ms. 350 ms = 350ms or less.

Table 5.4 – Register Assignment for Drop. 2 Area Read Only Registers (Continued).

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
19		Configurable Booleans (read)		
	C	Motor Overload Enable (R040)	1 = cnabled	350ms
	1	Level Sense Start Enable (R054)	1 = cnabled	350ms
	2	Low DC Bos Fault Avoidance Enable (SVC only) (U.023)	1 = cnabled	350ms
	3	High DG Bus Fault Avoidance Enable (U.024). Vector only.	1 = chabled	350 ma
	4	Outer Control Loop Proportional Trim Enable (U.048)	1 = chabled	359 ms
	5 to 15	Reserved		
20		Motor Overload Type (R041)	0 = nC; 1 = FC	350ms
21		Line Dip Ride Through Time (P.042), WHz only.	1 = 0.1 seconds	350ms
22		Fault Auto Roset Attempts (R043)	0 = d'sable auto reset	350 ms
23		Fault Auto Roset Time (P.044)	1 = 1 second	350 ms
24		Tunable Booleans (Read)		
	C	Encoder Loss Enable (P.039)	1 = enabled	350m:
	1	Oulput Phase Loss Enable (P.045)	1 = cnabled	350ms
	2	Manual Reference Preset Enable (P.053)	0 = do not preset the manual reference 1 = enable (see software manual)	350 ms
	3	AUTO/MAN Key Disable (R082)	1 = key disabled	350ms
	4	STOP/RESET Key Disable (P.055)	1 = key disabled	350ms
	5 to 15	Reserved		
25		Current Compounding Gain (U.026), Vector only.	1 = 0.001	350 ms
28		Carrier Frequency (kHz) (R047)	0 = 2kHz; $1 = 4kHz$; $2 = 0kHz$	350ms
27		Volts/Hertz or Vector Regulation (R:048)	0 = V/Hz; 1 = Vactor	380ms
28		Country Defaults (P.048)	0 = USA; 1 = EUr; 2 = «Pri	350ms
29		Inertia Compensation Gain (U.027). Vector only.	1 = 0.001	350ms
30		Losses Compensation Gain (U.028). Vector only.	1 = 0.001	359 ms
31		Option Port: Type and Version (P.065)	2103 = AutoMax Notwork V1.03	350ms

Table 5.5 – Register Assignment for Drop. 2 Area Read/Write Registers

Register	Bit	Description or GV3000/SE Parameter	Settings	Update†
32 to 33		Reserved	Must be 0	
34*	0 to 7	Terminal Strip Analog Output Source (R012)	See drive software instruction manual	T
	8 to 15	Reserved	Must be 0	
35		uog Hamp Accel Time (EC21)	1 = 0.1 seconds	T'
38		Log Ramp Decel Time (R.022)	1 = 0.1 seconds	Т
37		Forward/Heverse Configuration (E027)	See drive software Instruction manual	1
38	G	Encoder Loss Enable (R039)	1 – enabled	T'
	1	Output Phase Loss Enable (E045)	1 = enabled	Ţ,
	2	Manual Reference Preset Enable (R053)	See drive software instruction manual	T
	3	ALITO-MAN Key Disable (P.052)	1 = key disabled	Ľ
	4	sторуньвет Key Disable (Р.055)	1 – key disabled	Т
	5 to 15	Heserved	Must be 0	
39		S-Curve Enable (R019)	1 = enabled	С
40	G	Motor Overload Enable (P040)	1 = enabled	С
	1	Level Sense Start Enable (R054)	1 = enabled	С
	2	Low DC Bus Fault Avoidance Enable (SVC only) (U.023)	1 = enabled	С
	3	High DC Bus Fault Avoidance Enable (U.024). Vector only.	1 – enabled	С
	4	Outer Control Loop Proportional Trim Enable (U.048)	1 = enabled	С
	5 to 15	Reserved	Must be 0	
41.		Motor Overload Type (RO41)	II = nC; 1 = FC	С
42		Line Dip Ride-Through Time (P.042). WHz only.	1 = 0.1 seconds	С
43		Fault Auto Heset Attempts (P.043)	II = d'sable auto reset	С
44		Fault Auto Reset Time (P.044)	1 – 1 second	С
45	0 to 7	Network Output Hegister 1 Source (P.066)	Set to 0 for backward compatibility. See	Ţ ^c
	8 to 15	Network Output Register 2 Source (R067)	section 3.3.	Т
45	0 to 7	Network Output Hegister 3 Source (E068)		I.
	8 to 15	Network Output Register 4 Source (R069)		Т

[&]quot;Unly the low byte of this register is transferred. The high byte is ignored by the crive.

 $^{^{\}dagger}$ Update Times: 350 ms = 350 ms or less. T = 350 ms or less when tune/config enable is on. C = 350 ms or less when tune/config enable is on and the drive is stopped.

Table 5.5 - Register Assignment for Drop. 2 Ares, Read Write Registers (Continued)

Register	Bit	Description or GV3000/SE Parameter	Settings	Update [†]
47*	0 to 7	Carrier Frequency (kHz) (P.047)	0 = 2kHz; 1 = 4kHz; 2 = 8kHz	С
	8 to 15	Reserved		
48		Heserved	Must be 0	
49*	0 to 7	Country Defaults (E.049)	0 = USA; 1 = EUr; 2 = "Pn	С
	8 to 15	Reserved		

[&]quot;Only the low byte of this register is transferred. The high byte is ignored by the crive.

[†]Update Times: 350 ms = 350ms or less. T = 350ms or less when tune/config enable is on. C = 350ms or less when tune/config enable is on and the drive is stopped.

Table 5.6 – Register Assignment for Drop. 3 Area (Vector) Read Only Registers

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
Ū	0 to 7	Torque Reference Source (U.000).		350 ms
	8 to 15	Outer Control Loop Feedback Select (U.040)		350 ms
1		Encoder PPR (U.001)	0=512; 1=1024; 2=2048; 3=4096; 4=5F	350 ms
2		Motor Polos (U.302)	0=2; 1=4; 2=6; 3=6 poles	350 ms
3		Motor Namoplate Base Frequency (U.003)	1 = 0.1 Hz	350 ms
4		Motor Namoplate Amps (U.004)	1 = 0.1 amps	350ms
5		Motor Namoplate RPM (U.005)	1 = 1 ∃PM	350 ms
6		Magnetizing Current (U.006)	magnetizing arross ≥ 1000 rated amps	350 ms
7		Motor Namoplate Volts (U.007)	1 - 1 volts	350 ms
8		Torque Self-Tune Result (U.009) See drive software instruction manual		350 ms
8		Reserved		
10		Torque Regulator Proportional Gain (U.014)	1 = 0.01	350m:
11		Terque Regulator Integral Gain (U.015)	1 - 0.1	350m
12		Field Weakening Start RPM (U.016)	1 = 1 RPM	350m:
13		Motor Top Speed (U.017)	1 = 1 FPM	
14		AC Line Volts (U.018)	1 = 1 volls	
15		Flux Current Fiegulator Proportional Gain (U.019)	1 - 0.01	350m:
18		Flux Current Regulator Integral Gain (U.020)	1 = 0.1	350m
17		Flotor Time Constant (U.021)	1 - 0.001 seconds	350 ms
18		Motor Namoplate Hersepewer (U.022)	1 = 0.1 HP	350m
19		Zero Speed Hold Time (U.025)	1 - 0.1 seconds	350m
20		SVC Slip Adjust (U.035)	1 = 0.01	350 ms
21	0 to 7	SVC Sync Direction (U.031)	See drive software instruction manual	350m3
	8 to 15	Outer Control Loop Lead-Lag Select (U.041)	0 = bypass; 1 = lead/lag; 2 = ag/lead	350m
22		SVC Flux Current Regulator Gain (U.032)	1 - 1 rad/s	350m:
23		Outer Control Loop Lead-Lag Law Frequency (U.042)	1 = 0.01 rad/s	350m
24		Outer Control Loop Lead-Lag Flatio (U.043)	1-1	350m
25		Outer Control Loop Reference Sain (U.044)	1 = 0.001	350m

Table 5.6 - Register Assignment for Drop. 3 Area (Vector) Read Only Registers (Continued)

Register	Bit	Description or GV3000/SE Parameter	Settings	Update*
28		Outer Control Loop Proportional Gain (U.045)	1 = 0.01	350ms
27		Outer Control Loop Integral Gain (U.046)	1 = 0.01	350ms
28		Drive panel amps	1 = 0.1 amps	350 ms
29		Drive pane, volts	1 = 1 VAC	350 ms
30		Outor Control Loop Trim Range Percentage (U.047)	1 = 0.001	350ms
31		Power Module Type (R099)		350 ms

Table 5.7 – Register Assignments for Drop. 3 Area (Vector) Read/Write Registers

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
32		Encoder PPR (U.001)	0=512; 1=1024; 2=2048; 3=4096; 4=SE	С
33		Motor Poles (U.002)	0=2; 1=4; 2=6; 3=8 pclcs	С
34		Motor Namoplate Base Frequency (U.003)	1 = 0.1 Hz	С
35		Motor Namoplate Amps (U.664)	1 = 0.1 amps	С
38		Motor Namoplate RPM (U.005)	1 = 1 RPM	С
37		Magnetizing Current (U.006)	magnatizing arros < ICCD rated arros	С
38		Motor Namoplate Volts (U.007)		С
39		Torque Regulator Proportional Gain (U.014)	1 = 0.01	T
40		Terque Regulator Integral Gain (U.015)	1 - 0.1	T
41		Field Weakering Start HPM (U.016)	1 = 1 HPM	С
42		Motor Top Speed (U.017)	1 - 1 FPM	С
43		AC Line Volts (U.018)	1 = 1 volts	С
44		Flux Current Regulator Propertional Gain (U.019)	1 - 0.01	τ
45		Flux Current Begulator Integral Gain (U.020)	1 = 0.1	T
48		Refer Time Constant (U.021)	1 - 0.001 seconds	Ţ
47		Motor Nameplate Horsepower (U.022)	1 = 0.1 HP	C

*Update Times: C=350ms or less when tune/config enable is on and the drive is stopped. T=350ms or less when tune/config enable is on.

Table 5.7 – Register Assignments for Drop. 3 Ares (Vector) Read Write Registers (Continued)

Register	Bit	Description or GV3000/SE Parameter	Settings	Update*
48		Zero Speed Hold Time (U.025)	1 = 0.1 seconds	T
49		Current Compounding Gain (U.026).	1 = 0.001	Т
50		Inertia Compensation Gain (U.027).	1 = 0.001	Т
51		Losses Compensation Gain (U.628).	1 = 0.001	Т
52		Reserved	Must be 0	
53		SVC Slip Adjust (U.030)	1 = 0.01	T
54	0 to 7	SVC Sync Direction (U.031)	See drive software instruction manual	С
	8 tu 15	Outer Control Loop Lead/Lag Select (U.041)	0 = bypass; 1 = lead/lag; 2 = .ag/lead	Т
55		SVC Flux Current Regulator Gain (U.032)	1 = 1 rad/s	Т
58		Reserved	Must be 0	
57		Outer Central Leep Lead/Lag Low Frequency (U.042)	1 = 0.01 rad/s	Ţ
58		Outer Control Loop Lead/Lag Ratio (U.043)	1 = 1	Т
59		Outer Central Loop Reference Gain (U.044)	1 = 0.001	Т
60		Oute: Control Loop Proportional Gain (U.045)	1 = 0.01	τ
61		Outer Control Loop Integral Gain (U.046)	1 = 0.01	T
62		Oute: Control Loop Trim Bange Percentage (U.047)	1 = 0.051	Т
63		Reserved	Must be 0	

*Update Times: C=350ms or less when tune/config enable is on and the drive is stopped. T=350ms or less when tune/config enable is on.

97

Table 5.8 – Register Assignment for Drop. SiAres (Vol.s/Hertz) Read Only Registers.

Register	Bit	Description or GV3000/SE Parameter	Settings	Update Time
0		Motor Nameplate Volts (H.000)	1 = 1 VAC	350ms
1		Motor Nameplate Base Frequency (H.001)	1 = 0.1 Hz	350ms
2		Motor Nameplate Ampa (H.002)	1 = 0.1 amps 36	
3		Torque Boost Voltage (H.003)	1 = 0.1% of nominal inverter voltage 36	
4		Slip Compensation (H.004)	1 = 0.01% of base frequency	350ms
5	G	DC Braking Enable (H.005)	1 – enabled	350ms
	1 to 15	Reserved		1
6		DC Braking Start Frequency (H.006)	1 = 0.1 Hz	350ms
7		DC Braking Current (H.007)	1 = 1.0% of motor nameplate ampa	350ms
8		DC Braking Time (H.008)	1 = 0.1 seconds	350ms
9	G	Avoidance Frequency Enable (H.009)	1 = enabled	350ms
	1 to 15	Reserved		1
10		Avoidance Frequency Midpoint 1 (H.010)	1 = 0.1 Hz	350ms
11		Avoidance Frequency Band 1 (H.CTT)	1 = 0.1 Hz	
12		Avoidance Frequency Midpoint 2 (H.012)	1 = 0.1 Hz	
13		Avoidance Frequency Band 2 (H.013)	1 = 0.1 Hz	350ms
14.		Avoidance Frequency Midpoint 3 (H.014)	1 = 0.1 Hz	350ms
15		Avoidance Frequency Band 3 (H.015)	1 = 0.1 Hz	350ms
15		Sync Direction (H.016)	See drive software instruction manual	350ms
17		Input Power/Snubber Configuration (H.017)	See drive software instruction manual	350ms
18		Valta/Hertz Curve Type (H.018)	See drive software instruction manual	350ms
19		Identification Result (H.019)	See drive software instruction manual	350ms
20		Reserved		
21		AC Line Volts (H.021)	1 = 1 VAC	350ms
22		Overfrequency Limit (H.022)	1 = 0.1 Hz	350ms
23 to 26		Reserved		
27		Power Module Outout Amps (P.095)	1 = 0.1 ampa	350ms
28		Drive panel amps	1 = 0.1 amps	350ms
29		Drive pane volta	1 = 1 VAC	350ms
30		Reserved		
31		Power Module Type (P.099)		350ms

*Update Times: 350 ms = 350 ms or less.

Table 5.9 – Register Assignment for Drop. 3 Area (Volts/Hertz) Read/Write Registers.

Register	Bit	Description or GV3000/SE Parameter	Settings	Update
32		Motor Namoplate Volts (H.000)	1 = 1 VAC	Т
33		Motor Namoplate Base Frequency (H.001)	1 = 0.1 Hz	Т
34		Motor Namoplate Amps (H.002)	1 = 0.1 amps.	
35		Torque Bous: Voltage (H.003)	1 = 0.1% of nominal invertor voltage	
38		Slip Componsation (H.004)	1 = 0.01% of base frequency	τ
37	C	DC Braking Enable (H.005)	1 = cnabled	T
	1 to 15	Reserved	Must be 0	
35		DC Braking Start Frequency (H.998)	1 = 0.1 Hz	Т
39		DC Braking Current (H.007)	1 = 1.0% of motor namicplate amps	Т
40		DG Braking Time (H.008)	1 = 0.1 seconds	T
41	Ç	Avoidance Frequency Fnable (H.009)	1 = chabled	T
	1 to 15	Reserved	Must be 0	
42		Avoidance Frequency Midpoint 1 (H.010)	1 = 0.1 Hz	τ
43		Avoidance Frequency Band 1 (H.011)	1 = 0.1 Hz	Т
44		Avoidance Frequency Midpoint 2 (H.012)	1 = 0.1 Hz	Т
45		Avoidance Frequency Band 2 (H.013)	1 = 0.1 Hz	τ
48		Avoidance Frequency Midpoint 3 (H.014)	1 = 0.1 Hz	Т
47		Avoidance Frequency Band 3 (H.015)	1 = 0.1 Hz	Т
48		Sync Direction (H.018)	See drive software instruction manual	С
49		Input Power/Snubber Configuration (H.017)	See drive software instruction manual	С
50		Volts/Hertz Curve Type (H.018)	See drive software instruction manual	С
51 to 52		Reserved	Must be 0	
53		AC Line Volls (H.021)	1 = 1 VAC	С
54		Overfrequency Limit (H.022)	1 = 0.1 Hz	С
55 to 63		Reserved	Must be 0	<u> </u>

*Update Times: T=350ms or less when tune/config enable is on. C=350ms or less when tune/config enable is on and the drive is stopped.

Register Map Summary

Table A.1 - Key to Table A.2

Update Rate	Indicated as	
Sir s	No shading with balo line around	
350 ms or less	No shading	
350ms or less when tunerconlig enable is on	Shaded with beloning aroung	
350 n s or less when tune config enable is on and the price is stopped	Struded	

Register Map Summary A-*

Table A.2 – Register Map Summary

Torque Reference Source (LOCC) (bits 0 to 7) COL Feedback Select (LOCD) (bits 0 to 7) College of the sum (Botto Name plate Base Frequency (LOCD) (bits 0 to 7) College of the sum (Botto Name plate Base Frequency (LOCD) (bits 0 to 7) College of the sum (Botto Name plate Select (LOCD) (bits 0 to 7) College of the sum (Botto Name plate Select (LOCD) (LOCD) (Botto Name plate Select (LOCD) (LOC			Description or	GV3000 Parameter	
Depart of You's Vector torque feedback Encoder PPR (U.001) Motor Name plate Base Prequency (1.007)	Reg	Drop 1	Drop 2	Drop 3 (Vector)	Drop 3 (V/Hz)
2 Speed reliaum	0	Status word 1	Vector lorque reference		Motor Namepale Volls (H 000)
Speed Recibable Nework Out Reg Sources (1066, 1067) Motor Nameplate Sase Frequency (0.003) Torque Boost Voltage (H 000)	1	Speed ref value	Vector torque feedback	Encoder PPR (U.001)	Motor Nameplate Base Frequency (H.001)
Terminal strip analog input value Nework Out Pag Source (Flo56 Flo58) Motor Namepiate Amps (U.001) Stip Compensation (H.001)	2	Speed religion	Reserved	Mator Pales (U.002)	Mater Namepiale Amps (H.002)
5 Output speec/fectuency Terminal Strip Analog Input Offset (FLOS) Motor Namepiate RPM (J.ODS) DC Bristing Enable (H.ODS) 6 Output validage Terminal Strip Analog Input Osin (PD10) Magnetizing Surrent (J.COB) DC Bristing Start Frequency (H.ODS) 7 Output ourser) Terminal Strip Analog Input Osin (PD10) Motor Namepiate Volts (JLOS) DC Bristing Start Frequency (H.ODS) 8 Network output register 1 Perminal Strip Analog Culcul Source (PD12) Torque Sel -Tune Result (JLOS) DC Bristing Time (H.ODS) 9 Network output register 2 Culput Resy Configuration (PD13) Reserved Avoidance Prequency Enable (H.ODS) 10 Network output register 3 Tim Reference Source (PD14) Torque Regulator Proportional Cair (JLO14) Avoidance Prequency Microbin (H.ODS) 11 Network output register 4 Schieve Enable (PD19) Torque Regulator Proportional Cair (JLO14) Avoidance Frequency Band 1 (H.OT) 12 Drive Issuit listen bits — word 1 Jog Speed Reference (PD24) Field Weathering Start (PDM (JD16) Avoidance Frequency Band 1 (H.OT) 13 Drive Issuit listen bits — word 2 Jog Remp Accel Time (FD21) Motor Top Speed (JLO17) Avoidance Frequency Midpoint 2 (H.OT2) 14 of entry tig entire (bits 0 to 7) Avoidance Prequency Band 2 (H.OT2) 15 Entry tig entire (bits 0 to 7) Avoidance Prequency Band 2 (H.OT3) 16 Control Source (PD00) Function Loss Response (PD26) Fits Current Regulator Prop. Gain (JLO19) Avoidance Prequency Midpoint 3 (H.OT3) 17 Accel Time 1 (RAMP 1) (PD01) Fit was Prequency Science (PD28) Response (PD28) Seed Display Scaling (PD28) Response (HD02) Seed Display Scaling (PD28) Response (HD02) Validation Result (HD17) 18 Doel Time (RAMP 1) (PD02) Seed Display Scaling (PD28) Response (HD021) Response (HD021) Validation Result (HD17) 19 Maximum Speec (PD05) Motor American Preparation (HD17) Response (HD021) Respon	3	Speed feedback	Network Out Reg Sources (R.066, R.067)	Motor Nameplate Base Frequency (U.003)	Torque Boost Vollage (H.003)
6 Output valiage Terminal Stric Analog Input Osin (1010) Magnetizing Current (U.005) DC Braking Start Frequency (H.006) 7 Output ourser1 Terminal Stric Analog Input Configure (P011) Motor Nameplate Volta (U.007) DC Braking Current (H.007) 8 Network output register 1 Terminal Stric Analog Culcut Source (P012) Torque Sel-Tune Result (U.008) DC Braking Current (H.008) 9 Network output register 2 Culput Reay Configuration (1013) Reserved Avoidance Frequency Enable (H.009) 10 Network output register 3 Trim Telerence Source (P014) Torque Regulator Integrat Gain (U.015) Avoidance Frequency Microbint (H.010) 11 Network output register 3 Source Enable (P019) Torque Regulator Integrat Gain (U.015) Avoidance Frequency Microbint (H.010) 12 Drive Isult listen bits — word 2 Jog Remp Accel Time (P021) Motor Top Speed (U.017) Avoidance Frequency Band 2 (H.013) 13 Dive Isult listen bits — word 2 Jog Remp Decel Time (P022) AC Line Vota (U.018) Avoidance Frequency Band 2 (H.016) 14 Vici ment (equation (E016) Function (E007) Function (E007) Avoidance Frequency Midpont 3 (H.015) 15	4	Terminal strip analog input value	Network Out Reg Source (R068-R069)	Motor Nameplate Amps (U.001)	Slip Compensation (H.004)
7 Output current Terminal Strip Aralog Input Configure (PD11) Mictor Namepiate Valla (LL007) DC Braking Current (H 507) 8 National Cortifornia (Thins Strip Aralog Output Source (PD12) Torque Sel -Tune Result (LL008) DC Braking Time (H.008) 9 Network output register 2 Culput Rea, Configuration (PD13) Reservec Avoidance Prequency Enable (H.009) 10 Network output register 3 Trim Reference Source (PD14) Torque Regulator Proportional Carr (LL014) Avoidance Prequency Microsini (H.010) 11 Network output register 4 Source Enable (PD19) Torque Regulator Integral Cain (LL015) Avoidance Prequency Microsini (H.010) 12 Drive fault lation bits — word 1 July Speed Reference (PD20) Field Weakening Start RPM (LD16) Avoidance Prequency Midpoint 2 (H.012) 13 Drive fault lation bits — word 2 July Remp Accel Time (P021) Micro Top Speed (L.017) Avoidance Prequency Bene 2 (H.013) 14 Voil entry tog entries (Pilis 0 to 7) Parameter processing error flag bits 5: 15 Enrolog erroy Stope (P000) Function Loss Response (P028) Flux Current Regulator Integral Cain (LD10) Avoidance Prequency Bene 3 (H.015) 16 Control Source (P000) Function Loss Response (P028) Flux Current Regulator Integral Cain (LD10) Avoidance Prequency Bene 3 (H.015) 17 Accel Time 1 (PAMP 11 (P001) Forward/Teverse Cartiguistion (P027) Power/Shubber Configuration (H.017) 18 Depart Time (PAMP 11 (P001) Forward/Teverse Cartiguistion (P028) Micro Namepiate Horsepower (LD02) Voils/Hertz Curve Type (H.018) 19 Micro Intermit (P005) Micro Heads (LD40) (bit 0) Level Sanse Start Enable (L040) (bit 0) Level Sanse	5	Output speed/frequency	Terminal Strip Analog Input Offset (P.009)	Motor Namepiale RPM (U.005)	DC Braking Enable (H.005)
Network culput register 1 Terminal Stip Analog Outcut Source (PC12) Torque Set -Tune Result (U.009) DC Braking Time (H.008) Network output register 2 Culput Reay Configuration (1013) Reserved Avoidance Productory Enable (H.009) Network output register 3 Trim Reference Source (PC14) Torque Regulator Proportional Carr (U.014) Avoidance Preductory Microbin 1 (H.011) Network output register 4 Schore Enable (PD19) Torque Regulator Integrat Cain (U.015) Avoidance Preductory Band 1 (H.011) Network output register 4 Schore Enable (PD19) Torque Regulator Integrat Cain (U.015) Avoidance Preductory Band 1 (H.011) Orive fault listen bits — word 2 Jog Ramp Accel Time (P021) Motor Top Speed (U.017) Avoidance Preductory Midpoint 2 (H.013) Orive fault listen bits — word 2 Jog Ramp Accel Time (P022) AC Line Vota (U.018) Avoidance Preductory Band 2 (H.013) Orive fault listen bits — word 2 Jog Ramp Decel Time (P022) AC Line Vota (U.018) Avoidance Preductory Midpoint 3 (H.017) Orite fault entire (bits 0 to 7) Parameter processing error (lag (bits 0 to 7) Avoidance Preductory Midpoint 3 (H.017) Orite Source (P.001) Function Loss Response (P.026) Flux Current Regulator Prop. Gain (U.010) Avoidance Preductory Midpoint 3 (H.015) Orite Source (P.001) Function Loss Response (P.026) Flux Current Regulator Prop. Gain (U.010) Sync Direction ((H.017) Orite (PAMP 1 (P.001) Forward-Reviewe Configuration (P027) Patro Time Constant (H.020) Sync Direction ((H.017) Original Configuration (H.017) Prover(Shubber Configuration (H.017) Original Configuration (H.01	6	Output vallage	Tennina Strip Analog Input Gain (P010)	Magnetizing Current (U.006)	DC Braking Start Frequency (H.006)
9 Network output register 2 Culput fleay Configuration (1013) Fleaver Avoidance Frequency Enable (H 009) 10 Network output register 3 Trim Teterance Source (PC14) Torque Regulator Proportional Cain (L014) Avoidance Frequency Vitrosinin (H,010) 11 Network output register 3 Schole Enable (P019) Torque Regulator (Florational Coain (L014) Avoidance Frequency Vitrosinin (H,010) 12 Drive fault laten bits — word 2 Jog Remp Accel Time (F021) Motor Top Speed (L017) Avoidance Frequency Midpoint 2 (H,013) 13 Drive fault laten bits — word 2 Jog Remp Accel Time (F022) Motor Top Speed (L017) Avoidance Frequency Midpoint 3 (H,013) 14 Victional Coain (Coain (Coain) (L016) Jog Remp Accel Time (F022) AC Line Volls (U,018) Avoidance Frequency Band 2 (H,013) 15 Emortoglerity Stop Type (F022) Flux Current Regulator Frop. Gain (L019) Avoidance Frequency Band 3 (H,015) 16 Control Source (F000) Function Loss Response (F026) Flux Current Regulator Frop. Gain (L019) Symbolic Current Regulator Frop. Gain (L019) Symbolic Current (H019) 17 Accel Time 1 (F0AMP 1) (F002) Speed Display Scaling (F026) Motor Namepale Horsepower (L0022) <td>7</td> <td>Output current</td> <td>Terminal Strip Analog Inpu. Configure (P.011)</td> <td>Motor Nameplate Volts (U.007)</td> <td>DC Braking Current (H. 007)</td>	7	Output current	Terminal Strip Analog Inpu. Configure (P.011)	Motor Nameplate Volts (U.007)	DC Braking Current (H. 007)
Tim Telerance Source (R014) Torque Regulator Proportional Cain (L014) Avoidance Frequency Middoin 11 (H.010) Network output register 4 Schuwe Enable (R019) Torque Regulator Integral Cain (L015) Avoidance Frequency Band 1 (H.011) Drive fault lation bits — word 1 Jog Speed Reterance (R020) Field Weakening Start RPM (L015) Avoidance Frequency Band 1 (H.011) Drive fault lation bits — word 2 Jog Remp Accel Time (R021) Motor Top Speed (L.017) Avoidance Frequency Band 2 (H.013) Of entering entire (bits 6 to 7) Jog Ramp Decel Time (R022) AC Line Vota (L015) Avoidance Frequency Band 3 (H.014) Empring entry Stop Tyce (R025) Flux Current Regulator Prop. Gain (L.010) Avoidance Frequency Band 3 (H.015) Empring entry Stop Tyce (R025) Flux Current Regulator Prop. Gain (L.010) Avoidance Frequency Band 3 (H.015) Control Source (R000) Function Loss Response (R026) Flux Current Regulator Integral Carn (L020) Synd Direction (H.016) Accel Time 1 (RAMP 11 (R001) Fishware/Response (R025) Flux Current Regulator Integral Carn (L020) Synd Direction (H.016) Decel Time (RAMP 11 (R001) Fishware/Response (R025) Motor Namepiate Horsepower (L022) Votts/Herbz Curve Tybe (H.018) Motor (Nortiges Habite (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Lo Co Bus Fault Avoid Enable (R031) (Kil 1) Courrent Limit (R005) Properties (R031)	8	Network output register. I	Terminal Strip Analog Output Source (P012)	Torque Sell-Tune Result (U.003)	DC Braking Time (H.008)
Network culput register 4 S-Curve Enable (P019) Torque Regulator Integral Clain (U.015) Avoidance Frequency Band 1 (H.011)	9	Network output register 2	Culput Relay Caniiguration (?013)	Пеservec .	Avoidance Frequency Enable (H 009)
Drive fault latch bits — word 1 Jog Sceed Reference (1020) Field Weakening Start RPM (U016) Avoidance Frequency Midpoint 2 (H.012) Universal International Processing and 2 Jog Remp Accel Time (R021) Motor Top Speed (L017) Avoidance Frequency Band 2 (H.013) Avoidance Frequency Band 2 (H.013) Universal International Processing error libration (Bit 5 to 5 to 7) Parameter processing error libration (Bit 5 to 5 to 7) Parameter processing error libration (Bit 5 to 5 to 7) Parameter processing error libration (Bit 5 to 5 to 7) Processing error libration (Bit 5 to 5 to 7) Processing error libration (Bit 5 to 5 to 7) Processing error libration (Bit 5 to 7) Processing error libration (Bit 5 to 7) Processing error libration (Bit 5 to 7) Processing (R026) Processing error libration (Bit 5 to 7) Processing (R026) Processing	-0	Network output register 3	Trim Reference Source (P.014)	Torque Regulator Proportional Cain (U.014)	Avoidance Frequency Midpoint 1 (H.010)
Drive fault letch bits — word 2 Jog Ramp Accel Time (R021) Motor Top Speed (U.017) Avoidance Frequency Band 2 (H.013) 4 of enter tog entires (bits 0 to 7) Jog Ramp Decel Time (R022) AC Line Volta (U.018) Avoidance Frequency Mildpoint 3 (H.017) 5 Enter log entry Store (R000) Store (R000) Function Loss Response (R026) Flux Current Regulator Prop. Gain (U.019) Avoidance Frequency Band 3 (H.015) 6 Control Source (R000) Function Loss Response (R026) Flux Current Regulator Integral Carr (U.020) Sync Direction (H.016) 7 Accel Time 1 (RAMP 1) (R001) Forward Fleverse Configuration (R027) Rotor Time Constant (U.021) Power/Shubber Configuration (H.017) 8 Decel Time (RAMP 1) (R002) Speed Clapsy Sceling (R028) Motor Namepiate Forsepower (U.022) Volta/Hertz Curve Type (H.018) 9 Milimum Speed (R003) Motor (Ivertice) Heads (R064) (bit 1) Lo DC Bus Rault Avoid Enable (U.024) (bit 2) Lo DC Bus Rault Avoid Enable (U.024) (bit 3) CCL Proportional Tim Enable (U.024) (bit 3) CCL Proportional Tim Enable (U.024) (bit 3) 20 Maximum Speed (R005) Under Control Time Enable (U.024) (bit 3) Current Limit (R005) Under Control Time (R042) Sync Direction (U.031) (bits 0 to 7) CCL Lead Las Select (U.041) (bits 8 to 15)	-1	Network culput register 4	S-Curve Enable (P019)	Torque Regulator Integral Gain (U.015)	Avoidance Frequency Band 1 (H.011)
4 of enterlog entires (bits 0 to 7) Parameter processing error flag (bit 8) 5 Emortog error 6 Control Source (R000) 6 Function Loss Response (R026) 7 Accel Time 1 (RAMP 1) (R001) 7 Envaroffleverse Configuration (R027) 8 Dead Time (RAMP 1) (R002) 8 Speed Clap by Scaling (R028) 7 Michinum Speed (R003) 7 Michinum Speed (R003) 8 Michinum Speed (R003) 8 Michinum Speed (R003) 8 Michinum Speed (R003) 8 Michinum Speed (R003) 9 Michinum Speed (R003) 10 Michinum Speed (R004) 11 Michinum Speed (R004) 12 Ourent Limit (R005) 13 Page Proceed (R004) 14 Page Proceed (R004) 15 Page Proceed (R004) 16 Page Proceed (R004) 17 Page Proceed (R004) 18 Page Proceed (R004) 18 Page Proceed (R004) 19 Page Proceed (R004) 19 Page Proceed (R004) 19 Page Proceed (R004) 10 Page	-2	Crive fault latch bits — word *	Jog Speed Reference (P.020)	Field Weakening Start RPM (U.016)	Avoidance Frequency Midpoint 2 (H.012)
Parameter processing error flag (bit 8) 15 Emor log entry 16 Control Source (R000) 17 Accel Time 1 (RAMP 1) (R001) 18 Deset Time 1 (RAMP 1) (R002) 19 Mirimum Speed (R005) Moor (Nestige Habite (R004) (b) (d) Level Sense Start Enable (R004) (b) (d) Level Sense Start Enable (R004) (b) (d) Level Sense Start Enable (R004) (b) (d) CCL Procortical Tim Enable (R004) (b) (d) (d) (d) (d) (d) (d) (d) (d) (d) (d	-3	Crive fault latch bits — word 2	Jog Remp Accel Time (R021)	Motor Top Speed (U.017)	Avoidance Frequency Band 2 (H.013)
Function Loss Response (R026) Flux Quiren, Regulator Integral Gam (U.020) Sync Direction (H.016) Accel Time 1 (RAMP 1) (R001) Forward/Reverse Configuration (R027) Rotor Time Constant (U.021) Power/Snubber Configuration (H.017) Beach Time (RAMP 1) (R002) Speed Display Scaling (R028) Motor Namepiate Horsepower (U.022) Volta/Hertz Guive Type (H.018) Minimum Speed (R003) Motor (Vertopa Hinadis (P(V40) (bit 0) Level Sense Start Enable (R051) (bit 1) Lip DC Bus Rault Avoid Enable (U.021) (bit 2) COL Procedical Time Enable (U.021) (bit 3) COL Procedical Time Enable (U.028) (bit 3) COL Procedical Time (P.042) SVC Stip Adjust (U.030) Reserved Motor Overload Type (P.041) SVC Stip Adjust (U.030) Reserved Current Limit (P.005) Une Dip Ride-Through Time (P.042) SVC Sync Direction (U.031) (bits 0 to 7) COL Lead/Lag Select (U.041) (bits 8 to 15)	-4		Jog Ramp Decel Time (R022)	AC Line Volta (0.018)	Avoidance Frequency Midpoint 3 (H 017)
17 Accel Time 1 (RAMP 1) (R001) Forward/Reverse Configuration (R027) Rotor Time Constant (IU.021) Power/Snubber Configuration (H 017) 18 Decel Time (RAMP 1) (R002) Speed Display Scaling (R028) Motor Nameplate Horsepower (U.022) Volts/Hertz Gurve Tybe (H.018) 19 Minimum Speed (R003) Motor (Ivertops Happis (P040) (bit 3) Level Sense Start Enable (P040) (bit 3) Level Sense Start Enable (P040) (bit 1) Lo DC Bus Fault Avoid Enable (U.023) (bit 2) Hi DC Bus Fault Avoid Enable (U.024) (bit 3) COL Procortional Tim Enable (U.024) (bit 3) COL Procortional Tim Enable (U.024) (bit 3) COL Procortional Tim Enable (U.024) (bit 3) COL Procortional Time (P.042) SVC Stip Adjust (U.030) Preserved 20 Maximum Speed (R005) Une Dip Ride-Through Time (R042) SVC Sync Direction (U.031) (bits 0 to 7) COL Lead/Lag Select (U.041) (bits 8 to 15) AC Line Volts (H.021)	15	Error log entry	Stop Type (P.025)	Flux Current Regulator Prop. Gain (L.019)	Avaicance Frequency Banc 3 (H.015)
Decel Time (RAMP 1) (R002) Speed Clap ay Scaling (R028) Motor Nameplate Horsepower (U.022) Volts/Hertz Curve Tybe (H.018) Motor Nameplate Horsepower (U.022) Volts/Hertz Curve Tybe (H.018) Motor Nameplate Horsepower (U.022) Volts/Hertz Curve Tybe (H.018) Zero Speed Hold Time (U.025) Identification Result (H.019) Level Sense Start Enable (R064) (bit 1) Lo DC Bus Fault Avoid Enable (U.024) (bit 2) H DC Bus Fault Avoid Enable (U.024) (bit 3) CCL Proportional Time Enable (U.024) (bit 3) CCL Proportional Time Enable (U.025) SVC Stip Adjust (U.030) Reserved Current Limit (R005) Line Dip Ride-Thirtugh Time (R042) SVC Syno Direction (U.031) (bits 0 to 7) CCL Lead/Lag Select (U.041) (bits 8 to 15)	-6	Control Source (P.000)	Function Loss Response (P.026)	Flux Current Regulator Integral Gain (U.020)	Sync Direction (H.016)
Motor (Notrogo Heads (P040) (bt.0) Level Sense Start Enable (P051) (bit.1) Lo DC Bus Rault Avoid Enable (B051) (bit.2) Hi DC Bus Rault Avoid Enable (B051) (bit.3) COL Protortional Time Enable (B051) (bit.3) COL Protortional Time Enable (B051) (bit.3) COL Protortional Time (B051) (bit.3) Exercise Speed Hold Time (B.025) SVC Slip Adjust (B.030) Reserved Courant Limit (R005) Line Cip Ride-Through Time (R012) COL Lead/Lag Select (B.041) (bit.s 8 to 15)	17	Appel Time 1 (RAMP 1) (R001)	Forward/Teverse Configuration (P027)	Rotor Time Constant (U.021)	Power/Snubber Configuration (H 017)
Level Sense Start Enable (R.054) (bit 1) Lo DC Bus Pauli Avoid Enable (R.023) (bit 2) Hi DC Bus Pauli Avoid Enable (R.024) (bit 3) CCL Proportional Trim Enable (R.045) (bit 4) 20 Maximum Speed (R.004) Molor Overload Type (R.041) SVC Stip Adjust (R.030) Reserved 21 Current Limit (R.005) Line Cip Ride-Through Time (R.042) SVC Synd Direction (R.031) (bits 0 to 7) CCL Lead'Lag Select (R.041) (bits 8 to 15)	-8	Cecal Time (RAMP 1) (R002)	Speed Display Scaling (P.028)	Motor Namepiate Horsepower (U.022)	Valls/Hertz Gurve Type (H.018)
21 Current Limit (R005) Line Dip Ride-Through Time (R042) SVC Sync Direction (J.031) (bits 0 to 7) AC Line Volta (H.021) CCL Lead/Lag Select (U.041) (bits 8 to 15)	-9	Minimum Speed (R003)	Level Sense Start Enable (F.054) (bit 1) Lo DC Bus Paull Avoid Enable (L.023) (bit2) Hi DC Bus Pault Avoid Enable (L.024) (bit3)	Zero Speed Hold Time (IJ.025)	Identification Result (F.619)
CCL Lead/Lag Select (U.041) (bits 8 to 15)	20	Maximum Speed (R004)	Motor Overload Type (F.041)	SVC Slip Adjust (U.030)	Reserved
22 Trim Gain Percentage (2015) Fault Auto Reset Attempts (2013) SVC Rux Current Regulator Gain (J.032) Overfrequency Limit (H.022)	21	Current Limit (P.005)	Line Dip Ride-Through Time (P.342)		AC Line Volta (H.021)
	22	Trim Gain Fercentage (?015)	Fault Auto Resel Allempis (P.043)	SVC Flux Current Regulator Gain (U.032)	Overfrequency Limit (H.022)

Table A.2 - Register Map Summary (Continued)

		Description or GV3000 Parameter						
Reg	Drop 1	Drop 2	Drop 3 (Vector)	Drop 3 (V/Hz)				
23	Craw Gain Percentage (P.018)	Fault Auto Reset Time (P.044)	CCL Leas/Lag Law Frequency (U.M2)	Reserved				
24	Speed Regulstor Proportional Gain (U.012)	Encoder Loss Enable (P.039) (bit 0) Output Phase Loss Enable (P.045) (bit 1) Menual Peference Preset Enable P.053) (bit 2) AUTO/MAN Key Disable (P.052) (bit 3) STOP/FESET Key Disable (P.055) (bit 4)	OCL Lead/Lag Flatio (L.043)	Reserved				
25	Speed Regulator Integral Gain (U.013)	Current Compounding Gain (U.026)	OCL Reference Gain (U.044)	Reserved				
26	Status word 2	Carrier Frequency (kHz) (P.047)	OCL Proportional Cain (U.045)	Reserved				
27	Elapsed Time Meler (P.029)	Volts:Hertz or Vector Regulation (P048)	OCL Integral Gain (J.046)	Power Module Output Amps (P095)				
28	Network Connection Type (P061)	Country Celauts (P049)	Drive pane amps	Drive ganetamos				
29	Communication Loss Response (P.062).	Inertia Compensation Cain (U.027)	Drive pane valls	Drive panel volls				
30	Network Reference Source (P.263, P.054)	Lasses Compensation Gain (U.025)	CCL Trim Range Percentage (U.047)	Reserved				
31	So tware Version (P.098)	Type and Version (R085)	Power Module Type (P.092)	Power Module Type (P.093)				
32	Sequencing control word	Reserved	Encoder PPR (U.001)	Motor Namepale Vota (H 000)				
33	Option port speed/forque ref	Reserved	Major Pales (U.602)	Motor Namepale Base Frequency (H.001)				
5/	Option part trint reference	Terminal Strip Analog Output Source (P.012)	Motor Nameplate Base Preduency (0.003)	Motor Nan epiate Arrips (H.002)				
35	Network inertia compensation	Jog Ramp Accel Time (R021)	Motor Namepiale Amos (U.004)	Torque Boost Voltage (H.203)				
36	Reserved	Jog Tamp Dece Time (3022)	Motor Nameplate IPP8 (U.005)	Slip Compensation (H.004)				
37	Appel Time 1 (RAMP 1) (R001)	Forward/Reverse Configuration (R027)	Magnetizing Current (UICCS)	DC Braking Enable (H 305)				
38	Decel Time (RAMP 1;)R002;	Encoder Loss Enable (P.039; (b. 0) Output Phase Loss Enable (P.045; (b.11) Manual Ref. Preset Enable (P.053; (b.12) AUTO/MAN Key Disable (P.052) (bit 3) STORRESET Key Disable (P.055) (bit 4)	Malor Namepiale Vol.s (U.007)	DC Braking Start Frequency (F.005)				
39	Minimum Speed (R003)	S-Curve Erable (R019) (b., 4)	Torque Regulator Proportional Cam (IJ.014)	DC Braking Current (H 007)				
40	Max mum Speed (R004)	Mblo: Overload Enable (PC40) (bit 0) Level Sense Start Enable (PC64) (bit 1) Lo DC Bus Fault Avoid, Enable (UC22) (bit 2) Hi DC Bus Fault Avoid Enable (UC24) (bit 3) OCL Proportional Trim Enable (UC45) (bit 4)	Torque Regulator Integral Clain (U.015)	DC Braking Time (H 308)				
41	Current Limit (R005)	Motor Overload Type (R041)	Field Weakening Start RPM (U.016)	Accidance Frequency Enable (H.009)				

Table A.2 - Register Map Summary (Continued)

		GV3000 Parameter		
Reg	Drop 1	Drop 2	Drop 3 (Vector)	Drop 3 (V/Hz)
42	Terminal Strip Analog Input Offset (P009)	Line Dip Fide-Through Time (P.342)	Motor Top Speed (U.017)	Accidance Frequency Microint 1 (4.010)
43	Terminal Suip Ansky Input Cain (R010)	Faul: Auto Fleset Altempts (F.C45)	AC Line Vota (U.018)	Avoidance Prequency Band 1 (H.011)
44	TS Analog Input Configure (P.011)	Faul: Auto Fleset Time (F.041)	Flux Current Regulator Prop. Cain (U.319)	Avoidance Prequency Microsoft 2 (H.012)
45	Trim Cain Percentage (P315)	Network Out Hagister Sources (P066, P067)	Flux Ourien, Regulator Integral Carn (U.080)	Accidance Frequency Baro 2 (H.013)
46	Braw Gain Percentage (P.018)	Network Out Register Sources (R068, R069)	Rozar Time Caristant (U.021)	Accidance Frequency Micronit 3 (4.014)
47	Speed Rep. Proportional Gain (J.012)	Carrier Frequency (kHz) (P047)	Motor Namepiale Horsepower (U.022)	Avoicance Frequency Band 3 (H.015)
48	Speed Regulator Integral Gain (U.013)	Reserved	Zero Speed Hold Time (U.025)	Syno Direction (H 016)
19	Jog Speed Reference (P.320)	Country Defaults (P.043)	Current Compounding Gain (U.028)	Inout Pover/Smaller Configuration (H.017)
50	Blog Type (R025)	Reserved	Inertia Compensation Gain (U.027)	Valls/Hertz Curve Type (H.018)
51	Function Loss Response (PG28)	Reserved	Lasses Compensation Clain (U.028)	Reserved
52	Speed Display Scaling (F.026)	Reserved	Reserved	Réserved
53	Elspsec Time Meter Fleset (PC30) (bil0) Network inertia complenable (bit 1) Network speed F1 Imit control en (bit2)	Reserved	SVC Slip Adjust (J.036)	AC Line Vols (H.021)
5/	Reserved	Reserved	SVC Sync Direction (J.031) (bits 0 to 7) OCL Lead/Lag Select (U.041) (bits 8 to 15)	Overfrequency Limit (H.022)
55	Reserved	Reserved	SVC Flux Current Regulator Gain U.602	Reserved
56	Output Relay Configuration (P.013)	Reserved	Reserved	Reserved
57	Trim Reference Source (F.014)	Reserved	CCL Lead/Leg Low Frequency (U.S/S)	Reserved
58	Tarque Ref. Spurce (U.200) (ails@lo7) CCL Feedback Select (U.010) (bis8lo15)	Reserved	CCL Lead Lag Rairo (L. 043)	Reserves
59	Option port speed Pl high limit	Reserved	OQL Relevance Cain (U.014)	Reserved
60	Option port abead PHow limit	Reserved	OCL Proportional Cain (LL045)	Reserved
61	Nelwork Connection Type (P061)	Reserved	CCL Injeptal Gain (U.045)	Reserved
62	Communication Loss Tesponse (P.062)	Reserved	CCL Trim Range Percentage (U.047)	Reserved
63	Network Reference Sources (R083, R084)	Reserved	Reserved	Reserved

Parameter-to-Register Cross Reference

		Read Only		Read/Write		
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
AC Line Voits (H.021)	3, WHz	21		3, WHz	53	
AC Line Volts (U.018)	3, Vector	14		3. Vector	43	
Accel Time 1 (BAMP 1) (B001)	1	17		1	37	
Analog input signal less (Aln)	1	13	13	n/a		
Asymmetrical bus charge (UbS)	1	13	6	n/a		
Auto or manual reference selected	1	26	1	n/a.		
AUTO/MAN Key Disable (P.082)	2	24	3	2	38	3
Avoidance Frequency Band 1 (H.C11)	3, WHz	1.1		3, WHz.	43	
Avoidance Frequency Band 2 (H.013)	3, V/Ez	13		g, WHz	45	
Avoidance Frequency Band 3 (H.015)	3, V/Hz	15		g, WHz	47	
Avoidance Frequency Enable (H.009)	3, V/Hz	9	0	3, WHz	41	D.
Avoidance Frequency Midpoint 1 (H.010)	3, WHz	10		3, V/Hz	42	
Avoidance Frequency Midpoint 2 (H.612)	3, V/Ez	12		g, WHz	44	
Avoidance Frequency Midpoint 3 (H.014)	3, V/Hz	14		3, WHz.	46	
bYC	1	13	1	n/a		
Carrier Frequency (kHz) (P.047)	2	26		2	47	
CHS	1	12	Э	n/a		
Cloar error log	n/a.			1	32	В
Communication loss between	1	12	10	b/a.		
Regulator/PC/OIM (Srt.)						
Configurable Redieans (read)	?	19		n/a		
Control Source (R000)	1.	16		n/a		
Control word	n/a			1	53	
Country Delaults (P.049)	2	28		2	49	
Ourrent Compounding Gain (U.028)	2	25		3, Vector	49	
Ourrent Limit (R005)	1.	21		1	41	
DO Braking Current (H.007)	3, WHz	7		3, V/Hz	39	
DG Braking Enable (H.005)	3, V/Ez	5	0	3, V/Hz	37	D
DC Braking Start Frequency (H.006)	3. V/Hz	6		3, WHz	35	
DC Braking Time (H.008)	3, V/Hz	- 8		3, V/Hz	40	
DC bus charging bypass contactor (bYC)	1	13	7	n/a		
Decel Time (BAMP 1) (P.002)	1	18		1	38	
Default parameter restore (CHS)	1	12	9	wa		
Diagnostics Display (P.091)	n/a.			n/a		
Diagnostics Source (P.090)	n/a.			n/a		
Draw Gain Percentage (P.016)	1	23		1	48	
Drive fault latch bits (word 1)	1	12		p/a.		
Drive fault latch bits (word 2)	1.	13		n/a		
Drive overtemperature (OH)	1.	12	7	n/a		

	Read Only			Read/Write		
Description or GV3000/SE Parameter	Drop	Register	Biţ	Drop	Register	Bit
Drive panel amps	3	28		n/a		
Drive panel volts	3	29		rva		
Drive power electronic eventead (PUe)	1	13	6	rva		
Drive ready	1	0	0	n/a		
Drive running	1	0	1	rva		
Earth current failure (ground fault) (EC)	1	13	7	rva		
EEr	1	13	5	rva		
EL	1	13	12	n/a		
Elapsed Time Meter (P.029)	1	27		1	53	0
Electronic thermal everload (OL)	1	12	8	n/a		
Enceder less (EL)	1	13	12	rva		
Encoder Loss Enable (P.039)	2	24	0	2	38	0
Encoder PPR (U.001)	3, Vector	1		3, Vector	32	
Error log clear	n/a			1	32	В
Error log entry (most recent error)	1	15	8 to 15	n/a		
Error log entry (second most recent)	1	15	0 to 7	n/a		
Fatal system error	1	13	15	n/a		
Fault active	1	0	2	n/a		
Fault Auto Roset Attempts (P.043)	2	22		2	43	
Fault Auto Roset Time (P.044)	2	23		2	44	
Fault roset	n/a			1	32	2
Field Weakening Start RPM (U.016)	3, Vector	12		3, Vector	41	
FL (function loss)	1	12	8	n/a		
Flux Current Regulator Integral Gain (U.020)	3, Vector	16		3, Vector	45	
Flux Current Regulator Prop. Gain (U.019)	S, Vector	15		3, Vector	44	
Forward/Reverse Configuration (P.027)	2	17		2	37	
Forward/reverse reference invert	4	0	4	n/a	- 07	
Forward/reverse select	n/a			1	32	4
Function loss (FL)	1	12	8	n/a	- SE	
Function loss (PC)	2	16	0	1	51	
H.000, Motor Namoplate Volts	3, V/Hz	0		3, V/Hz	32	
H.001, Motor Namoplate Base Freq.	3, V/Hz	1		3, V/Hz	33	
H.002, Motor Namoplate Sase Picq.	3, V/Hz	2		3, V/Hz	34	
H.003, Torque Boost Voltage	3, V/Hz	3		3, V/Hz	36	
H.004, Slip Compensation	3, V/Hz	4		3, WHz	36	
H.005, DC 3raking Enable		5			37	- 0
	3, V/Hz 3, V/Hz	6		3, WHz	38	
H.006, DC Braking Start Frequency H.007, DC Braking Current		7		3, WHz	39	
	3, V/Hz			3, WHz	46	
H.006, DC 3raking Time	3, V/Hz	8	_	3, WHz		
H.009, Avoidance Frequency Enable	3, V/Hz	9	0	3, WHz	41	0
H.010, Avoidance Frequency Midpoint 1	3, V/Hz	10		3, WHz	42	
H.011, Avoidance Frequency Band 1	3, V/Hz	11		3, V/Hz	43	
H.012, Avaidance Frequency Midpoint 2	3, V/Hz	12		3, V/Hz	44	
H.013, Avoidance Frequency Band 2	3, V/Hz	13		3, V/Hz	45	
H.014, Avoidance Frequency Midpoint 3	3, V/Hz	14		3, V/Hz	46	
H.015, Avoidance Frequency Band 3	3, V/Hz	15		3, V/Hz	47	
H.016, Sync Direction	3, WHz	18		3, V/Hz	48	
H.017, Input Power/Snubper Config.	3, WHz	17		3, WHz	49	
H.018, Velts/Hertz Curve Type	3, WHz	18		3, WHz	50	
H.019, Identification Posuit	3, WEz.	19		n/a		
H.020, Identification Request	n/a			n/a		

	Read Only					
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
H.021, AC Line Volts	3, V/Hz	21		3, WHz	53	
H.022, Overfrequency Limit	3, WHz	22		3, V/Hz	54	
Hild (high time identification aborted)	1	13	2	n/a		
High DC Bus Fault Avoid, Enable (U.024)	2	19	3	2	40	3
High DC bus voltage (HU)	1	12	4	n/a		
High line voltage (HIL)	1	13	4	n/a		
High time identification aborted (HID)	1	13	2	n/a		
Identification request not performed (rild)	1	13	3	n/a		
Identification Result (H.019)	3, WHz	19		n/a		
Inertia Compensation Gain (U.027)	2	29		3, Vector	50	
Input phase loss (IPL)	1.	13	11	n/a		
Input Power/Snubber Config. (H.017)	3, WHz	17		3, WHz	49	
IPL (input phase loss)	1	13	11	n/a		
Log Ramp Accol Time (P.021)	2	13		2	35	
Log Ramp Decel Time (P.022)	2	14		2	38	
Log Speed Reference (P.020)	2	12		1	49	
Level Sense Star: Enable (R054)	2	19	1	2	40	1
Line Dip Ride Through Time (R642)	2	21		2	42	<u> </u>
Lusses Compensation Gain (U.028)	2	30		3, Vector	51	
Low DC Bus Fault Avoid, Enable (U.023)	2	19	2	2	40	2
Low DC bus voltage (LU)	1	12	5	n/a	70	-
Magnetizing Current (U.006)	3, Vector	6	·	3, Vector	37	
Manual Reference Preset Enable (R653)	2	24	2	2	38	2
Maximum Speed (P.004)		20	- E	1	40	Ľ
Minimum Speed (R003)	1	19		1	39	
Missing Power Medule ID connector (PUc)	1	13	9	n/a	35	
Motor Namoplate Arnos (H.002)	3, V/Hz	2	,	3, WHzi	34	
Motor Namoplate Arros (U.664)	3, Vector	4		3, Vector	35	
Motor Namoplate Base Frequency (H.001)	3, V/Hz	-		3, WHz	33	
Motor Namoplate Base Frequency (4.001)	3, Vector	3		3, Vector	34	
Motor Namoplate Horsepower (U.022)		18			47	
	3, Vector 3, Vector	5		3, Vector	38	
Motor Namoplate RPM (U.335)				3, Vector	32	
Motor Namoplate Volts (H.000)	3, V/Hz	7		3, V/Hz		
Motor Namoplate Volts (U.007)	3, Vector	12	- 1.1	3, Vector	38	
Motor output phase loss (OPL)	-		14	n/a	45	_
Motor Overload Enable (R040)	2 2	19	0	2	40	0
Motor Overload Type (R041)		20			41	
Motor Poles (U.002)	3, Vector	2		3, Vector	33	
Motor Top Speed (U.017)	3, Vector	13		3, Vector	42	
Network communication loss (nCL)	1	13	0	n/a	54	
Network Connection Type (P.061)	1.	28		1	61	-
Notwork Incrita compiregister enable	0/8			1	53	7
Notwork Inertia compensation	n/a	-		1	35	
Notwork output register 1	1	8		n/a.		
Notwork output register 2	1.	9		n/a		
Notwork output register 3	1	10		n/a.		
Notwork output register 4	1	11		n/a		
Network Output Register 1 Source (R066)	.2	3	0 to 7	2	45	0 to 7
Notwork Output Pogister 2 Source (R087)	2	3	8 to 15	2	45	8 to 15
Notwork Output Register 3 Source (R068)	2	4	0 to 7	2	46	0 to 7
Network Output Pegister 4 Source (P.069)	2	4	8 (0.15)	2	46	8 to 15

	Read Only			Read/Write		
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
Network speed PI finit central enable	n/a			1	53	2
nld (Identification request not performed)	1	13	3	n/a		
Number of error log entries	1	14	0 to 7	n/a		
NVFAM write failure (EEr)	1	13	5	n/a		
OC (evercurrent, steady state)	1	12	0	n/a		
OCA (evercurrent, at acceleration)	1	12	-	n/a		
OC5 (overcurrent, at DC braking)	1	12	3	rva		
OCd (overcurrent, at deceleration)	1	12	2	n/a		
OF (overfrequency)	1	12	15	n/a		
OH (drive evertemperature)	1	12	7	rva		
OL (electronic thermal everload)	1	12	8	n/a		
OPL (mutor output phase loss)	1	12	14	tva		
Option port speed PThigh limit	n/a	1.2		1	59	
Option port speed PHow limit	n/a			1	60	
Option port speed/.orque direct ref	n/a			1	33	
Option port trim ref (when P.014=2)	n/a			1	34	
Option Port: Com Loss Response (P.062)	1	29		1	62	
Option Port: Network Rol Source (P.663)	1	30	0 to 7	1	63	0ω7
Option Port: Netw Trim Ref Source (R684)	1	30	8 to 15	1	63	8 to 15
	2	31	01010		00	0.00.10
Option Port: Type and Version (R085)	1	12	40	n/a		
OSP (overspeed; vector unity)		12	13	iva		_
Outer control loop (OCL) enable	n/a 1	200		1	32	5
Outer control loop enabled		26	2	n/a		51.46
OCL Foodback (U.040)	3, Vector	0	8 to 15	1 2 32 1 1	58	8 to 15
OCL Integral Gain (U.048)	3, Vector	27		3, Vector	61	
OCL direct reference	n/a	20		2.161	34	
OCL Lead/Lag Low Freq. (U.042)	3, Vector	23		3, Vector	57	
OCL Lead/Lag Ratio (U.643)	3, Vector	24	51.45	3, Vector	58	B
OCL Lead/Lag Select (U.041)	3, Vector	21	8 to 15	3, Vector	54	8 to 15
OCL Proportional Gain (U.045)	3, Vector	26		3, Vector	60	
OCL Proportional Trim Enable (U.048)	2	19	4	2	40	4
OCL Reference Gain (U.044)	3, Vector	25		3, Vector	59	
OCL Trim Range Percentage (U.047)	3, Vector	30		3, Vector	62	
Output Gurrent	1	7		rva		
Outout Phase Loss Enable (P.045)	2	24	1	2	38	1
Outout Relay Configuration (R013)	2	9		1	56	
Output speed/trequency (RPM display)	1	5		īva		
Output voltage (VOLTS display)	1	6		tva		
Overcurrent, at acceleration (OCA)	1	12	-	n/a		
Overcurrent, at DC braking (CCb)	1	12	3	n/a		
Overcurrent, at deceleration (OCd)	1	12	2	n/a		
Overcurrent, steady state (OC)	1	12	0	n/a		
Overfrequency (QF)	1	12	15	in/a		
Overfrequency Limit (H.522)	3, WHz	22		3, V/Hz	54	
Overspeed; vector only (OSP)	1	12	13	n/a		
P.000, Control Source	1	18		n/a		
P.001, Accel Time 1 (BAMP 1)	1	17		1	37	
P.002, Decel Time (RAMP 1)	1	18		1	38	
P.003, Minimum Speed	1	19		1	39	
P.004, Maximum Speed	1	20		1	40	
P.005, Current Limit	1	21		1	41	

	Read Only			Read/Write		
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
P.006, Second Menu Password	n/a			n/a		
P.007, Term Strip Digital Inouts Configure	n/a.			n/a		
P.008, Term Strip Speed Reference Source	n/a.			n/a		
P.009, Terminal Strip Analog Input Offset	2	5		1	42	
P.010, Terminal Strip Analog Input Gain	2	6		1	43	
P.011, Term Strip Analog Input Configure	2	7		1	44	
P.012, Term Strip Analog Output Source	2	8		2	34	0 to 7
P.013, Output Relay Configuration	2	9		1	56	
P.014, Trim Reference Source	2	10		1	57	
P.015, Trim Gain Percentage	1	22		1	45	
P.016, Draw Gain Percentage	1.	23		1	48	
P.017, Accel Time 2 (RAMP 2)	n/a			rva		
P.018, Decel Time 2 (RAMP 2)	n/a			rva		
P.019, S Curve Enable	2	11		2	39	
P.020, Jog Speed Reference	2	12		1	49	
P.021, Jog Ramp Accel Time	2	13		ż	35	
P.022, Jog Ramp Decel Time	2	14		2	36	
P.023, MOP Accel/Decel Time	n/a.	1.7		n/a	- 55	
P.024, MOP Reset Configuration	n/a			n/a	+	
R025, Step Type	2	15	0 to 7	1	50	
R026, Function Loss Response	2	16	0.10 /	1	51	
P.025, Foreston Loss Response P.027, Forward/Reverse Configuration	2	17		ż	37	
	2	18		1	52	
P.028, Speed Display Scaling	1	27		<u> </u>	92	
P.029, Elapsed Time Meter		21		n/a	===	_
P.030, Elapsed Time Meter Reset	n/a.			1/	53	0
P.031, Presc: Speed 1	n/a			n/a	1	
P.032, Presc: Speed 2	n/a			n/a.		
P.033, Presc: Speed 3	n/a			n/a.		
P.034, Presc: Speed 4	n/a			n/a.		
P.035, Presc: Speed 5	n/a			n/a		
P.036, Presc: Speed 6	n/a			n/a		
P.037, Presc: Speed 7	n/a			n/a.		
P.038, Presc: Speed 8	n/a			n/a.	<u> </u>	
P.039, Encoder Loss Enable	2	24	0	2	38	0
P.040, Motor Overload Enable	2	19	0	2	40	0
P.041, Motor Overload Type	2	20		2	41	
P.042, Line Dip Ride Through Time	2	21		2	42	
P.043, Fault Auto Roset Attempts	2	22		2	43	
P.044, Fault Auto Roset Time	2	23		2	44	
P.045, Output Phase Loss Enable	2	24	1	2	38	1
P.047, Carrier Frequency (kHz)	2	26		2	47	
P.048, Volts/Hertz or Vector Regulation	2	.27		n/a.		
P.049, Country Defaults	2	28		2	49	
P.050, Restore Defaults	n/a			n/a.		
P.051, Programming Disable	n/a,			n/a		
P.052, AUTO/MAN Key Disable	2	24	3	2	38	3
P.053, Manual Reference Preset Enable	2	24	2	2	38	2
P.054, Level Sense Start Enable	2	19	1	2	40	1
P.055, stor/heset Key Disable	2	24	4	2	38	4
P.060, Network Drop Number	n/a			n/a		
P.061, Network Connection Type	1	28		1	61	

	£	Read Only		3	Read.Write	00-000-
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
P.062, Option Port: Comm Loss Response	a t	29	l venesee.		62	Andrews and
P.063, Option Port: Network Rdi Source		30	0 to 7	1	63	0 to 7
P.064, Option Port: Netw Trim Rel Seurce	1	30	8.015	3 1	63	8 to 15
P.065, Option Port: Type and Version	2	31		n/a		Secretary Section
P.066, No.work Output Register 1 Source	2	3	0 to 7	2	45	0 to 7
P.087, No.work Output Register 2 Source	2	3	8 to 15	2	45	8 to 15
P.068, No.work Ou.put Register 3 Source	2	4	0 to 7	2	48	0 to 7
P.069, No.work Culput Register 4 Source	2	4	8 to 15	2	48	8 to 15
P.090, D'agnostics Source	n/a		>	n/a		()
P.091, Diagnostics Display	n/a	1		n/a		Ť .
P.095, Power Medule Output Amps	3, WHz	27	5	rva		Ď.
P.098, Softward Version Number	1	31		n/a		
P.099, Power Medule Type	3	31	5	Iva	2	ė.
Parameter processing error flag	Ť	14	8	n/a		*
Power Module no, identified (PUn)	1 1	13	10	rva		in .
Power Module Output Amps (P.095)	3. V/Hz	27	- 14	-		Ÿ.
	3, V/HZ	31		n/a	Ŷ.	
Power Module Type (R099)		3		n/a		5
Programming Disable (R051)	n/a			n'a		
PUc (missing Power Medule ID connector)	1	73	9	n/a		0
PUn (Pewer Module not identified)	1	13	10	30/8		
PUe (drive power electronic eventesd)	1	13	- 6	m/a		10
Restore Defaults (P.050)	nya			n/a		ĬĬ.
RMI (r.) parameters	n/a	1000	}	n/a	1 27.0	G.
Refor Time Constant (U.021)	3, Vector	17		3, Vector	46	Ĭ
Run/jog status	1	0	3	rva		6
Run/jug select	n/a		. 545	1	32	3
S Curvo Enablo (R019)	2	77	(2	39	0
Selected speed reference value	1	83		ारंच	2000	ii .
Self tuning status (SF)	1	12	12	n/a	120,140	6
Sequencing control word	n/a		78-2	1	32	Ŷ
Slip Compensation (H.004)	3, WHz	4	(3, WHz	36	6
Softward Version Number (R098)	1	31		#/ H	J-100	î .
Speed Display Scaling (P.028)	2	18	5	1	62	Č.
Speed feedback	1	3		m/a		Ť.
Speed reference sum	1 1	2	5	11/El		iii
Speed regulation select	n/a	1000		1	32	7
Speed Regulator Integral Gain (U.013)	1	25	5	1 1	45	
Speed Regulator Prop Gain (U.012)	1	24		1	47	*
Spurious host PC comm interrupt (UAr)	1 1	-2	- 11	n/a	5.00%	ė.
SrL (comm loss between	1	12	10	n/a		7
Regulator/PG/OIM)	25	0,000	36000	i.e.		
Start	n/a	1		1	32	0
Status word 1	1	ō		n/a	- OL	
Status word 7	1	26	-			ő.
Stop		e0		nya 1	32	131
	n/a	-			130	S. 491
Stop sequence in progress	1	0	5	n/a	0000	100
Stop Type (P.925)	2	15	0 to 7	1	50	
storyndset Key Disable (P.655)	2	24	4	2	38	4
SVC Flux Current Regulator Gain (U.032)	3, Vector	22		3, Vector	55	
SVC Slip Adjust (U.030)	3, Vector	20	}	3, Vector	53	10.
SVC Sync Direction (U.031)	3, Vector	21	0 to 7	3, Vector	54	0 to 7

		Read Only			Read/Write	
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
Sync Direction (H.016)	3, WHz	16		3, V/Hz	48	
Terminal Strip Analog Input Config (P.011)	2	7		1	44	
Terminal Strip Analog Input Gain (P.010)	2	6		1	43	
Torminal Strip Analog Input Offset (P.009)	2	- 6		1	42	
Torminal strip analog input value	1.	4		n/a		
Terminal Strip Analog Output Source (P.012)	2	8		2	34	0 to 7
Torminal strip digital input 1 (start)	1	0	в	n/a		
Torminal strip digital input 2 (stop)	1	ō	9	rva		
Terminal strip digital input 3 (fault reset)	1	0	10	n/a		
Terminal strip digital input 4 (run/jeg)	1	ō	11	rva		
Torminal strip digital input 5 (function loss)	1	ō	12	n/a		
Torminal strip digital inputs 8	1	ő	13	n/a		
Torminal strip digital inputs 7		Ö	14	n/a		
Torminal strip digital inputs 8	-	Ö	15	n/a		
Torque Boos: Voltage (H.003)	3, V/Hz	3	10	3, V/Hz	35	
	3, Y/HZ		_		30	
Torque or speed regulation	5 Monday	28	0 0 (n 7	11/81	F0	013
Torque Reference Source (U.000)	3, Vector	0	0 to 7	1	58	0 to 7
Torque Regulator Integral Gain (U.015)	3, Vector	11		3, Vector	40	
Torque Regulator Prop Gain (U.014)	3, Vector	10		3, Vector	39	
Torque Self Tune Result (U.009)	3, Vector	8		n/a		
Trim Gain Percentage (P.015)	1	22		1	45	
Trim Reference Source (P.014)	2	10		1	57	
Tunable Booleans (Read)	2	24		n/a		
Tune/config input chable	1	0	δ	1	32	14
Tune/config update synchronization flag	1.	0	7	1	32	15
U.000, Torque Reference Source	3, Vector	0	0 to 7	1	58	0 to 7
U.001, Encodor PPR	3, Vector	1		3, Vector	32	
U.002, Motor Poles	3, Vector	2		3, Vector	33	
U.003, Motor Namoplate Base Freq	3, Vector	3		3, Vector	34	
U.004, Mutor Namoplate Amps	3, Vector	4		3, Vector	35	
U.005, Motor Namoplate RPM	3, Vector	5		3, Vector	38	
U.008, Magnetizing Current	3, Vector	6		3, Vector	37	
U.007, Mutor Namoplate Voits	3, Vector	7		3, Vector	38	
U.008, Torque Self Tune Enable	n/a			n/a		
U.009, Torque Self-Tune Result	3, Vector	9		n/a		
U.012, Speed Regulator Pres Gain	1	24		1	47	
U.013, Speed Regulator Integral Gain	1	25		1	48	
U.014, Torque Regulator Prop Gain	3, Vector	10		3, Vector	39	
U.015, Torque Regulator Integral Gain	3, Vector	11		3, Vector	40	
U.018, Field Weakoning Start RPM	3, Vector	12		3, Vector	41	
U.017, Mutar Too Speed	3, Vector	13		3, Vector	42	
U.D*8, AC Line Velts	3, Vector	14		3, Vector	43	
U.019, Flux Current Regulator Prop Gain	3, Vector	15			44	
		18		3, Vector	45	
U.020, Flux Current Reg Integral Gain	3, Vector	17		3, Voctor		
U.02*, Rotor Time Constant	3, Vector			3, Voctor	46	
U.022, Motor Nameplate Hersepower	3, Vector	18		3, Voctor	47	
U.023, Low DC Bus Fault Avoid Enable	2	19	2	2	40	2
U.024, High DC Bus Fault Avoid Enable	2	19	3	2	40	3
U.025, Zerc Speed Hold Time	3, Vector	19		3, Vector	45	
U.528, Current Compounding Gain	2	.25		3, Voctor	49	
U.027, Inertia Compensation Gain	2	29		3, Vector	50	

	Read Only			Read/Write		
Description or GV3000/SE Parameter	Drop	Register	Bit	Drop	Register	Bit
U.028, Losses Compensation Gain	2	30		3, Vector	51	
U.030, SVC Slip Adjust	3, Vector	20		3, Vector	53	
U.031, SVC Sync Direction	3, Vector	21	0 to 7	3, Vector	54	0 to 7
U.032, SVC Flux Current Regulator Gain	3, Vector	22		3, Vector	55	
U.040, OCL Feedback Scient	3, Vector	0	8 to 15	1	58	8 to 15
U.041, OCL Lead/Lag Select	3, Vector	21	8 to 15	3, Vector	54	8 to 15
U.042, OCL Lead/Lag Lew Frequency	3, Vector	23		3, Vector	57	
U.043, OCL Lead/Lag Ratio	3, Vector	24		3, Vector	58	
U.344, OGL Reference Gain	3, Vector	25		3, Vector	59	
U.045, OCL Proportional Gain	3, Vector	26		3, Vector	60	
U.048, OCL Integral Gain	3, Vector	27		3, Vector	ଶ୍ରୀ	
U.047, OCL Trim Range Percentage	3, Vector	30		3, Voctor	62	
U.948, OCL Proportional Trim Enable	2	19	4	2	40	4
UAr (spurious host PC comm interrupt)	1	12	11	n/a		
UbS (asymmetrical bus charge)	1	13	8	n/a		
Voctor terque feedback	2	1		n/a		
Vactor terqua reference	2	0		n/a		
Valts/Hartz Curve Type (H.018)	3, WHz	18		3, WHz	50	
Volts/Hortz or Vector Regulation (R.048)	2	27		rva		
Zero Speed Hold Time (U.025)	3, Vector	19		3, Vector	48	

75 ohm terminating load, 1-2	D
A	DeviceNot Network Communication Option Board, 3-2
a ternative synchronization methods, 4-4	direct
AutoMax	reference, 3-7
Network Communication Option board,	trim reference, 3-8
description, 1-1	tirive
network, connecting to, 2-38	configuration, 3-1
Processor, -2	connecting to AutoMax network, 2-38.
Programming Executive, 1-2	power-up, 3-2
	ready status bit. 4-5
В	response to network communication loss, 3-2, 3-4
bass data amandas 0.0	grop cable, Installing, 2-38
base drop number, 3-2	drop number, 3-2
basic crive connection, 3-1, 3-2, 3-3	Drop 1
broadcast reference, 3-7	read only registers, 5-2
	read/write registers, 5.5
trim reference, 3-8	Drap_2
	read only registers, 5-8
C	read/write registers, 5-10
	Drop 3, 4-5
clear error log bit, 4-4	vector
communication loss, response to, 3-4	read only registers, 5 ° 2
Communications Passive Tap. 1-2	read/write registers, 5-13
configurable	volts/hertz
data, 4.1	read only registers, 5-15
inputs	read/write registers, 5-16
enabling transfer, 4.2	craps. 3 1
timing, 4-4	
configuring	E
drive, 3-1	D L
network communication, 3.1	enabling transfer of tunable and configurable.
Control and Configuration Software, 1-2	inputs, 4-2
Control Source (P.000), 3-1	error
control sources and matwork, 4-1	log, clearing, 4-4
control/reference data, 4-7	status flag, 4-4
timing, 4-4	
ControlNet Network Communication Option Board,	3 <u>2</u>
3-2	F
counter register, pulse encoder, 4-5	S Friedle accorded of
cross reference, parameter to register, B-1	fault reset. 4-4
CS3000 software, 1-2	full drive connection, 3-1, 3-2, 3-3

Index 1

G	Network Output Register 1 Source (P.066), 3-9
	Network Output Register 2 Source (P.067), 3-9
GV3000/SE drive, connecting to network, 2-38	Network Oulput Register 3 Source (P.068), 3-9 Network Oulput Register 4 Source (P.060), 3-9
Ĺ	026
6.	0
VO update enable logic summary, 4-2	
input data, transfer rates, 4-1	Option Port: Communication Lass Response
instal ation, 2-1	(P.062), 3-2, 3-4
1 to 20 HP @ 230 VAC drives, 2-12 1 to 5 HP @ 460 V drives, 2-4	Option Port: Network Reference Source (P.063). 3-7
100 to 150 HP @ 460 VAC drives, 2 25 15 to 25 HP @ 460 V drives, 2-21	Option Port: Network Trim Helerence Source (P.064), 3 8
2 to 15 Amp drives, 2-32	Option Port: Type and Version (P.065), 3-8
200 to 400 HP @ 460 VAC drives, 2-20	organ zation, network register, 4-5
24 to 30 Amp crives, 2 32	output data, transfer rates, 4-2
25 to 60 HP @ 460 V drives, 2-21	
30 to 100 HP @ 230 VAC drives, 2-16	P
50 to 100 HP @ 460 VAC drives, 2-25	1950
7.5 to 10 HP @ 460 VAC crives, 2-8	P.060 Network Drop Number, 3-2
75 to 200 HP @ 460 VAC drives, 2-16	P.061 Network Connect on Type, 3-3
J	P.062 Option Port: Communication Loss Response, 3-4
J	P.063 Option Port: Network Reference Source, 3-7
jumper	P.064 Option Port: Network Trim Reference
locations, 2-3	Source, 3-8
settings, 2-3	P.065 Option Port: Type and Version, 3-8
2000 PM 12 2	P.066 Network Output Register 1 Source, 3-9
•	P.067 Network Output Register 2 Source, 3-9
L	P.068 Network Output Register 3 Source, 3-9
	P.069 Network Output Register 4 Source, 3-0
load, terminating, 1-2	parameter
instal ing, 2-38	descriptions, 3-2
loss of network communication, 3-2	network inaccessible, 4-6
	processing error status Tag, 4-4
N	reg ster cross reference. B
	unacceptable values, 4-4
network	passive tap, 1-1, 1-2
and other control sources, 4-1	installing, 2-38
configuring communication, 3-1	phone support, 1-2
drop cable, 1-1	pulse encoder counter register, 4-5
option board description, 1-1	paise a code contenegate, 4-3
parameter descriptions, 3-2	92
reference source, 3-7	R
register organization, 4-5	Sor
response to communication loss, 3-4	read only registers, 4-5
transier rates, 4-1	Drop_1, 5-2
Network Communications Module, 1-2	Drap_2, 5-8
Network Connection Type (P.061), 3-1, 3-3	Drap_3 (vector), 5-12
Network Drop Number (P.060), 3-1, 3-2	Drap_3 (valts/hertz), 5-15

read/write registers, 4-5	timing requirements, 4-4
Drop_1, 5-5	transfer rates, network, 4-1
Drop_2, 5-10	transferring data types, 4-2
Drop_3 (vector), 5-13	transmit time, 4-4
Drop_3 (volts/hertz), 5-16	trim reference, network source, 3-8
reference	troubleshealing, 1-2
source, network, 3-7	tunable data. 4 1
trim, network source, 3-8	
register	tunable input
map summary, A-1 map tables, 5-1	enabling transfer, 4-2 timing, 4-4
maps, 4-5	tunable, configurable, and status cata, 4-2
parameter cross reference, B-1	Tune/Config Input Enable bit, 4-2
related hardware and software, 1-2	tune/config update synchronization flag, 4.3
ReSource™ Interface Cable, 1-2	to order ig apasto by billor abuser tog, b
runtime signal data, 4.2	222
AND	U
S	unacceptable parameter values, 4-4
start input, timing, 4-4	
synchron zarion	V
a ternatives, 4-4	- 100 - 100
flag. 4-3	vector
0.000 100 - 1 00 0.00 0.00 0.00 0.00 0.00 0.00 0.00	read only registers, 5-12
9 -1	read/write registers, 5-13
Т	volts/hertz
technical assistance, 1-2	read unly registers, 5-15
terminating load, 1-2	read/write registers, 5-16
instal ing, 2-38	Valts/Hertz or Vector Regulation (P.048), 3-1
mous my, 2-00	i arran rente al resson ringgararari il 1940), a-r

Index-3

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