## 4 Channel Analog Output Module

M/N 57C410

Instruction Manual J-3631-1



The information in trialuser's manual is subject to change without notice.

#### WARNING

THIS UNIT AND ITS ASSOCIATED EQUIPMENT MUST BE INSTALLED, ADJUSTED AND MAINTAINED BY QUALIFIED PERSONNEL WHO ARE FAMILIAR WITH THE CONSTRUCTION AND OPERATION OF ALL EQUIPMENT IN THE SYSTEM AND THE POTENTIAL HAZARDS INVOLVED, FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

#### WARNING

INSERTING OR REMOVING THIS MODULE OR ITS CONNECTING CABLES MAY RESULT IN UNEXPECTED MACHINE MOTION. POWER TO THE MACHINE SHOULD BE TURNED OFF BEFORE INSERTING OR REMOVING THE MODULE OR ITS CONNECTING CABLES. FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

#### CAUTION

THIS MODULE CONTAINS STATIC-SENSITIVE COMPONENTS. CARELESS HANDLING CAN CAUSE SEVERE DAMAGE.

DO NOT TOUCH THE CONNECTORS ON THE BACK OF THE MODULE. WHEN NOT IN USE, THE MODULE SHOULD BE STORED IN AN ANTI-STATIC BAG. THE PLASTIC COVER SHOULD NOT BE REMOVED. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN DAMAGE TO OR DESTRUCTION OF THE MATERIAL.

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## 1.0 INTRODUCTION

The products described in this instruction manual are manufactured or distributed by Reliance Floctric Gompany or its subsidiaries.

This 4 Channel Analog Output Module contains four 12-51 D/A converter channels. Each channel can provide  $\pm$ s voits,  $\pm$ 8 volts,  $\pm$ 10 volts, or a 4-20 ma current output. Output signals have 2500 volt isolation to logic common. Each channel has its own independent isolated common. The voltage outputs are current limited to protect the device in the event of a short drop to

Typically, this module is used to output voltage or current signals to devices such as onlye and process controllers.

This manual describes the functions and specifications of the module. It also includes a detailed overview of installation and servicing procedures, as well as examples of ping altiming methods.

Related publications that may be of interest.

- J-2611 DCS 5000 PRODUCT SUMMARY
- J 3675 DCS 5000 ENHANCED BASIC LANGUAGE INSTRUCTION MANUAL
- J 3600 DCS S000 CONTROL BLOCK LANGUAGE INSTRUCTION MANUAL
- JI 3602 DOS 5000 LADDER LOGIC LANGUAGE INSTRUCTION MANUAL
- Jaik29 DOS 5000 REMOTE (C INSTRUCTION MANUAL
- J-3631 ReSource AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 1.0
- J-3635 DCS 5000 PROCESSOR MODULE INSTRUCTION MANUAL
- J-3649 AutoMax CONFIGURATION TASK MANUAL
- LI3550 AutoMax PROCESSOR MODULE INSTRUCTION
  MANUAL
- J-3875 AutoMax ENHANGED BAS GILAN SUAGE INSTRUCTION MANUAL
- J-3876 AutoMax CONTROL BLOCK LANGUAGE INSTRUCTION MANUAL
- J-3677 AutoMax LADDER LOOIC LANCUAGE INSTRUCTION MANUAL
- J-3684 ReSource AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 2.0
- J-3750 ReSource AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 3.0
- IEEE 516 GUIDE FOR THE INSTALLATION OF ELECTRICAL EQUIPMENT TO MINIM ZE ELECTRICAL NOISE INPLTS TO CONTROLLERS FROM EXTERNAL SOURCES

## 2.0 MECHANICAL/ELECTRICAL DESCRIPTION

The following is a description of the taceptate LEDs field termination connectors, and electrical characteristics of the tield connections.

## 2.1 Mechanical Description

The output module is a printed dirout board assembly that plugs into the backplane of the DCS 5000/AutoMaxirack. It consists of a printed dirout board, a faceplate and a protective enclosure. The faceplate contains tabs at the top and boltont to simplify removing the module from the rack. Module dimensions are listed in Appendix A.

Let faceplate of the module contistins a temate connector socket and 4 LED indicators that arow the status of the on-board isolated power supplies. Output signals, eave the module via a multi-conductor cable (M/N 57U374; see Appendix D). One end of this cable staches to the taceplate connector, while the other end of the cable staches stake-on connectors that stisch to a terminel atility for easy field within. The taceplate connector socket and cable plug are keyed to prevent the cable from being plugged into the wrong module.

On the back of the module are two edge connectors that attach to the system backate to:

## 2.2 Electrical Description

The output module contains 4 D/A converters that provide 12-bit resolution for 15 volts, 15 volts, and 10 volts and 11-bit resolution for 4-20 ma current outputs. Each D/A converter has its own laciated common. Output signals have 2500 volt iso ation to logic common. Refer to the block diagram in Accendtr 8.

Each output circuit consists of three operational amplifiers. The first amplifier provides the voltage output dumpers are provided on the terminal strip to acted, an output range of 5–6 or 10 volta. Current limiting is provided to protect the device against short circuits. A capacitor in the feedback path of this amplifier serves as a first order low pass output filter where the break frequency is approximately 100 hz. The other two amplifiers are used to generate the 4-80 ma current butput. A circuit diagram is shown in figure 2.1.





There are 4 LED indicators on the faceplate of the module. The LEDs are ananged in the same order as the output terminals on the faceplate. They are numbers acquentially from zero through three, corresponding to the D/A converter channels. This LED indicators display the status of the four isolated power supplies on the module. A fit LED indicates that the power supply for that channel is potentional. See figure 2.8.



Figure 2.2 - Modulo Escociato

## 3.0 INSTALLATION

This section describes how to install and remove the module and its cable assembly.

## 3.1 Wiring

The Installation of wiring anould conform to all applicable codes

To reduce the possibility of electrical noise interfering with the proper operation of the control system, exercise care when installing the wining from the system to the external devices. For detailed recommendations refer to IEEE 518.

## 3.2 Initial Installation

Use the following procedure to install the module:

- Step 1. Turn off power to the system. All power to the rack as well as all power to the wring leading to the module aboutd be off.
- Step P. Mount the terminal strip (M/N 570374) on a panel. Ite terminal strip anould be mounted to permit easy access to the acrew terminals. Make certain that the terminal strip is close enough to the rack so that the caple will reach between the terminal strip and the module.
- Step 3 Faster field wires to the terminal strip. Typical field, connections for voltage output and for 4-30 maisurent output are shown in figures 3.1 and 3.2, respectively.

Refer to Appendix C for the arrangement of terminal strip connections. Note that for each channel there is only one common, regardless of whether voltage or current output is desired. If you require e ther s volt or 6 volt outputs, you must connect a jumper between the desired voltage and the voltage output on the terminal strip. Make contain that all fact wires are securely fastened.



Figure 3-1 - Typical Field Connections for Voltage Output



Figure 3.2 - Typical Field Connections for 4-20 ma Current Output

- Step 4. Take the module out of its shipping container. Take it out of the anti-stolic hag, being careful not to touch the connectors on the back of the module.
- Step 5. Insert the module into the desired slot in the reak. Refer to figure 3.3. Use a screwdriver to secure the module into the slot.



#### Figure 3.3 - Rack Stot Numbers

Step 6 Atlach the terminal scrip connector (M/N 570374) to the mating half on the module. Make certain that the connector is the proper one for this module. Use a screwdriver to secure the connector to the module.

Note that both the module and the terminal atrip connector have "keys" that should be used to prevent the writing cable from being connected to the module.

Rotate the keys on the module and the connector so that they can be connected logather securely. It is recommended that, for modules so equipped, the keys on each successive module in the rack be rotated one position to the right of the keys on the proceeding module. Since the keys on the connectors must match their particular modules for the connector to fit, this method will eliminate the possibility of the wrong connector being pluegod into a module.

- Step 7 Turn on power to the system. Verily that the four LEDs indicating each isolated power status are it.
- Step 8 Verify the inatslistion by connecting the programming forminal to the system and running the BeSource Software.

Stop all programs that may be running,

Use the I/O MON TOR function if the module is in the local rack, enter the module slot number and register (0-3, corresponding to the four D/A converter channels;

If the module is in a remote rack, enter the module slot number of the master remote I/O module, remote I/O drop number (slop celled the remote tack number), output module and number; and register (0-3).

Write a series of values to each of the channels and verify the analog voltage with a voltmeter. Refer to table 1 for the approximate voltages or currents that should be read.

#### WARNING

# BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

Table 1

value	±5V	±8V	±10V	4-20 ma
4095	+5.0V	+0.0V	-10.0V	20 ma
2047	+2.59	+4.09	- 5.09	12 ma
0	0.CV	0.CV	0.5%	am N
-2047	-2.5V	-4.0V	-a.0V	û ma
4095	5.0V	V0.5	10 CV	0 ma

### 3.3 Module Replacement

Use the following procedure to replace a module:

- Step 1. Turn off power to the rack and all connections.
- Step 2. Use a screwdriver to looser the screws holding the contractor to the module. Benave the connector.
- Step 3. Loosen the screws that hold the module to the rack. Remove the module from the stot in the rack
- Step 4. Place the module in the shiFistatic bag it came in, being careful not to touch the connectors on the back of the module. Place the module in the cardboard shipping container.
- Step 5. Take the new module out of the anti-static bag, being careful not to touch the connectors on the back of the module.
- Stap 6. Insert the module into the cesired alot in the reck. Use a screwdriver to secure the module into the slot.
- Step 8. Turn on power to the rack.

## 4.0 PROGRAMMING

This section describes bow the state is organized in the module and provides examples of how the module is accessed by the application software. For more detailed information, refer to DCS (ADM Enhanced BASIC Language Instruction Manual (J-S600) or AutoMax Enhanced Basic Language Instruction Manual (J-S675).

## 4.1 Register Organization

I he data in the module is organized as four 16-bit registers, one for each U/A converter channel. The dets in each register is treated as a single precision integer limited to values in the range of - 4095 through - 4095. Bit 15 is the sign bit sho bits 1-11 are the 2's complement data value. Refer to figure 1.1.

	15	11	13	12	11	10	8	6	7	6	5	1	3	2	1	0
regiszer 0.	s	s	S	s				CI	arn	icl D	Daat	8				12
register I	8	G	s	8				CH	acn	ici (	Dat	53				
mgister P	8	÷	\$	8				Gł	arn	ici P	Det	5				
redister 3	S	s	5	s				Gt	arn	iel S	Det	s :				

Figure 4.1 - Organization of Register Bits

## 4.2 Configuration

Before any application programs can be written, it is necessary to configure, or set, the definitions of system-wide variables. I.e. those that must be globally accessible to all tasks.

For DCS 5000 and AutoMax Version 2.1 and earlier, you define system-wide variables by writing a Configuration task. For AutoMax Version 3.0 and later, you define system-wide variables using the AutoMax Programming Executive. After these variables are defined you can generate the configuration file automatically, which eliminates the requirement to write a configuration task for the rack. If you are using AutoMax Version 2.1 or earlier, see the Appendix File received to define variables in the configuration task. If you are using AutoMax Version 3.0 or later, see the AutoMax Programming Executive (J-3750) for information accution figuring variables.

4.3 Reading And Writing Data In Application Tasks

> In order for an output module to be referenced by application software. It is first necessary to assign symbolic names to the physical hardware. In AutoMax Version 2.1 and earlier, this is accomplished by either IODEF or RIODEF statements in the corriguisation task. In AutoMax Version 3.0 and later, you assign symbolic names using the Programming Executive.

> Each application program that references the symbolic names assigned to the module must declare those names CCMMON

The frequency with which taaks, or application programs, read their inputs and write their outputs depends on the language being used. Laccer logic and control block tasks read inputs once at the heginning of each acan and write outputs once at the end of scan. BASIC tasks read an input and write an output for each reference throughout the scan.

### 4.3.1 BASIC Task Example

2000 COMMON DISPLAY's | Display value 5000 DISPLAYS = 2048 5000 END The symbolic name DISPLAY's references the analog output channel

#### 4.3.2 Control Block Task Example

2400 COMMON DISPLAY:& \ Display value 3500 ! 5000 CALL INVERTER( NPUT=2048, & CUTPUT=DISPLAY%) 5000 ! 6000 END The symbolic name DISPLAY% references the enslog cutput channel

## 4.4 Restrictions

### 4.4.1 Dala Limitations

Register bit 0 is not connected to the D/A converter. Writing to it will have no effect on the analog output value, When the data is read back, bit 0 will always return 0.

Fiepister bits 12, 13, and 14 are also not connected to the D/A converter, if you expect that the digital value to be written to an output will exceed the range  $\pm$ 4095, place a software limit on the value before writing it to the shalog output. Otherwise, if a value greater than  $\pm$ 4095 is written to the analog output, the output will be the analog value proportional to the value of bits 1-11 and the sign bit 15.

## 5.0 DIAGNOSTICS AND TROUBLESHOOTING

This section explains how to troubleshoot the module and field connections.

## 5.1 Incorrect Data

Problem: The output is either slwsys off, always on, or different than expected. The possible causes of this are a module in the wrong stot, a malfunctioning module, or a programming error. It is also possible that the output is either not wired or wired to the wrong device. Use the following procedure to isolate the problem:

Step 1 Verify that the output module is in the correct slot and that the FO cell titlions are correct.

> Refer to figure 3.3. Varify that the slot number being referenced agrees with the slot number defined in the configuration task. For this module, the register number is always zero. Verify that the register number of the output module agrees with the D/A channel number (0-3).

For remote (/C instellations, also verily that the master slot, and drop number are delined correctly.

Step 2 Verify that the laciated power supplies are working.

Make certain that the four LEDs on the module lacep ateare lit. If any of them are not lit, the module is malfunctioning.

Step 3 Verily that the terminal board is wired correctly.

Confirm that all connections at the terminal strip are tight. Verify that each of the analog output channels is wired to the content device and that the jumpers on the terminal strip (if inculred) are connected. Befor to tigures 3.1 sec. 8.2.

Step 4. Verily that the module can be accessed.

Connect the programming terminal to the system and run the ReSource Software.

Stop all programs that may be running.

Connect a voltmeter to the voltage output of each channel being checked. Use the VO MONITOR function and write the values in table 1 to the channel being investigated. The voltmeter should read the voltages listed in table 1. If it does, the problem lies in the user application program (proceed to step 7).

If the values exceed the accuracy limit, the offset and gain acjustment are not correct and the module is matunctioning.

#### WARNING

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Step 5. Verily that the external field device(s) most module specifications.

To test voltage ou puts, remove the wres for the field devices from the terminal strip and repeat the test in step 4. If the voltmeter now reads the correct values, either the module is mail unctioning on the output device impedance, is too low and the current limit, feature is preventing the channel from outputing the proper voltage.

Verify the hardware functionality by systematically swapping out modules. After each swap. If the problem is not corrected, replace the original module before swapping out the next module.

To test 4-20 malour entitieutputs, remove the connector from the face of the module. Connect a voltmeter across the form hallst ip connections that are wired to the load and verify that the voltage is within specifications.

Next, connect a current meter across the terminal strip connections and verify that the current is approximately 20 ma. If these tests are not successfull, the proclemilies in the field wiring or the external device.

Gheck the osbie for continuity between the tecaplate connector and the terminal air(p. Remember to replace environment of connectors that have to be removed.

Step 6. Verify that the haroware is working correctly.

Verify the hardware functionality by systematically ewapping out modules. After each awap, if the problem is not corrected, replace the original module before ewapping out the next module.

- To test local I/O first replace the output module. Next, replace the processor module (a). If the problem persists, take sli of the modules out of the packplane exceptions processor module and the output module. If the problem is now corrected, one of the other modules in the reck is mail incritioning. Becomer the other modules one at a time until the problem reappears. If none of these tests reveals the problem recipied the packplane.
- To test remote 1:0, first verify that the remote 1:0 system is communicating with the crop that contains the output module being tested. Next actembre whether the output module is the only module in the rock that is not working. If more than one module is not working controlly the problem module likely lies in the rote VO system. If the problem does not lie in the system, it employs the remote rock.

- To test, the remote rack, first replace the output module. Next, replace the slave remote 1/0 module. If the problem backplane except the slave remote backplane except the slave remote bC module and the output module. The problem is now corrected, one of the other modules in the rack is mailtanctioning. Reconnect he other modules care at a time until the problem reappears. If the problem proves to be notifier in the remote 1/0 system nor in the remote rack, try replacing the backplane.
- Step 7 Verify that the user application program is correct.

If core of the above steps has connected the pinhiem, verify that the application errogiain that uses the sympolic names assigned to the module has defined these names as COMMON.

Verily that the symbolic name in question is being referenced in the application program. This can be done incirectly by monitoring the name with the VARIABLE MONITOR function in the ReSource software.

## 5.2 Bus Error

Problem: A '30' or '61' through '58' appears on the processor mocule's LED. This error message indicates that there visit a bus error when the system attempted to access the module. The possible causes of this error are a missing module, a module in the wrong slot, on a malunctioning module. Refer to the DCS Processor Module Instruction Manual (J 3635) or AutoMax Processor Module Instruction Manual (J-3650) for more information. Use the following procedure to iso ate a bus error.

Step 1. Verily that the output module is in the correct slot and that the (O definitions are correct.

Refer to squre 3.3. Verify that the alot number being referenced agrees with the alot number defined in the configuration task. Verify that the register number of the output module agrees with the D/A channel number (0-3).

For remote EQ installations, also verify that the masterislot, and remote crop number are defined correctly.

Step 2 Verily that the module can be accessed.

Connect the programming to minal to the system and run the Resource Software.

Stop all programe that may be running.

Use the PO MON TOR function to display each of the channels. If the programmer is able to monitor the outputs, then try to write zeros to the outputs.

#### WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

If the program ner is able to read and write to the output module, the problem lies in the application software and you need to refer to step 1 again.

If the programmer cannot read and write the outputs, the problem like in the hardware (proceed to step 3).

#### Step 3. Verify that the hardware is working correctly.

Verify the hardware functionality by systematically swapping out the output module, the processor module(s), and the backplane. After each swap, if the problem is not corrected, replace the original item before swapping out the next tem.

For remote t/C inststational systematically swap out the output module, the slave remote module, and the backplane. After each swap. If the problem is not corrected, replace the original item before swapping out the next item.

## Appendix A

## **Technical Specifications**

### **Ambient Conditions**

- Storage temperature, -40° C 85° C.
- Operating temperature: 0° C 60° C
- Itumidity: 5.90% non-condensing.

### Maximum Module Power Dissipation

157 Wetta

### Dimensions

- Height 11.75 inches
- Wieth: 1.25 Inches
- Depth: 7.375 inches.

### System Power Requirements

- +6 volts: 2750 ma
- +12 volts: 55 ma
- +\*2 vo ts: 5 min.

## **Output Circuit**

- Number of channels, 4
- Output ranges: ±s volts 10 maimax ±8 volts 10 maimax ±10 volts, 10 maimax 4-20 ma, external sower supply required (12-48 volts) load impedance <= 500 phms.</li>
- Resolution: voltage outputs +12 bits including sign 4 20 ma + 11 bits (sign bit always 0)
- Accuracy:  $\pm$  0.10% of full scale (voltage output)  $\pm$  0.15% of full scale (current output)
- Output Tilter: ±5 Volts = first order 200 Hz low pass ± 8 Volts = first order 125 Hz low pass ±10 Volts = first order 100 Hz low pass 4 20 ma = none
- Voltage cutputs short-circuit protected.
- Each channel individually isolated.
- 2500 volt isolation between legic common and outputs.

## Appendix B

## Module Block Diagram



# Appendix C

## **Field Connections**

Channel	Pin No.	Function
	Ť	5 valt_umpar
	2	vo lage culput
Q	3	Bivolt_umper
	4	ourrent output
	5	comman
	6	ь voltjumper
	7	vo tago cutput
1	ß	8 volt umper
	e	i current output
	10	continon
	11	5 volt jumper
	12	vo lage culput
2	13	8 volt_umper
	าง	current output
	13	common
	16	5 volt_umper
	17	vo tago culpat
3	18	8 volt jumper
	19	carrent output
	201	common

## Appendix D

## **Related Components**

57C374 - Terminal Stric/Caple Assembly

This sseembly consists of a termine latip, cable, and mating connector, it is used to connect field signals to the taceplate of the output module.



## Appendix E

## Defining Variables in the Configuration Task

### Local I/O Definition

This section describes how to configure the output module when it is located in the same tack as the processor module that is referencing it (i.e., the local rack). Refer to the figure below. Note that this procedure is used only if you are using the AutoMax Programming Executive software version 2.1 or cartler.



Module in a Local Rade

### **Register Reference**

One statement is required in the configuration task for each channel that will be used. The symbolic name of each register should be as meaningful as possible.

mmnn IODEF SYMSOLIG NAME%, SLOT = a, REGISTER= 1

#### where:

rmmn - BASIC statement number. This number may isope from 1-32757. SYMBOLIC\_NAME% - A symbolic name chosen by the user and ending with (%). This indicates an integer data type.

 ${\rm SLOT}^+$  . Slot number that the module is plugged into. This number may range from 0-1a.

REG STER - The register number corresponding to the analog output channel  $\left(0.3\right)$ 

### Example Of Local I/O Definition

The following statement assigns the symbolic name DISPLAY% is analog output channel number 2 on the putput indicated in stol 4.

1020 IDDEF POSITION34 SLDT-4, REGISTER-2]

### Remote I/O Definition

This section describes how to configure the module when it is located in a rack that is remote from the processor module referencing it. Refer to the figure below.



Module in a Remote Reck

### **Register Reference**

One statement is required in the configuration task for each channel that will be used. The symbolic name of each channel should be as mesningful as possible.

rmmn BIOJEF SYMBOLIC NAME%[ MASTER SLOT=m, DBOP=d, SLOT=s, BEGIS\_E6=r]

where:

rmmn - BASIC statement number. This number may range from 1-32767.

 $SYMBOLIC\_NAME\%$  - A symbolic name chosen by the user and ending with (%). This indicates an integer data type.

MASTER SLCT - Slo, number that the master remote (/O module is plugged into. This number may range from 0.15.

 ${\rm HEG\,STER}$  - The register number corresponding to the enslog output channel (0-3)

DROP Drop number of the slave remote I/O module that is in the same back as the output module. This number may range from 0-7.

 $\rm SLC^{-}$  - Slot number that the module is plugged into. This number may range from 0-15,

HEG STER - The register number corresponding to the enslog output channel  $\left( 0.3\right)$ 

## Example of Remote I/O Definition

The following statement assigns the symbolic name LEVEL% to a talog output shan tel number 1 ou the output module located in slot 4 of remote I/O onp 3. This remote drop is connected to the remote I/O system whose master is located in slot 15 in the master rack:

1020 RIGDEF LEVEL% [ MASTER\_SLOT=15, DROP=3, SLOT=4, REGISTER=1]

## For additional information

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