115 VAC High Power Output Module

M/N 57C403

Instruction Manual J-3623-3



The information in trialuser's manual is subject to change without notice.

WARNING

THIS UNIT AND ITS ASSOCIATED EQUIPMENT MUST BE INSTALLED, ADJUSTED AND MAINTAINED BY QUALIFIED PERSONNEL WHO ARE FAMILIAR WITH THE CONSTRUCTION AND OPERATION OF ALL EQUIPMENT IN THE SYSTEM AND THE POTENTIAL HAZARDS INVOLVED, FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

WARNING

INSERTING OR REMOVING THIS MODULE OR ITS CONNECTING CABLES MAY RESULT IN UNEXPECTED MACHINE MOTION. POWER TO THE MACHINE SHOULD BE TURNED OFF BEFORE INSERTING OR REMOVING THE MODULE OR ITS CONNECTING CABLES. FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

CAUTION

THIS MODULE CONTAINS STATIC-SENSITIVE COMPONENTS, CARELESS HANDLING CAN CAUSE SEVERE DAMAGE.

DO NOT TOUCH THE CONNECTORS ON THE BACK OF THE MODULE. WHEN NOT IN USE, THE MODULE SHOULD BE STORED IN AN ANTI-STATIC BAG. THE PLASTIC COVER SHOULD NOT BE REMOVED. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN DEMAGE TO OR DESTRUCTION OF THIS EQUIPMENT.

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1.0 INTRODUCTION

The products described in this instruction manual are manufactured or distributed by Reliance Floctric Company or its subsidiaries.

This 115 VAC High Power Output Module will drive a maximum of sixteen 116 volt control signals as outputs from the DCS 5000AutoMax system. The output signal fractiency may be either 50 or 60 hertiz. Individual outputs are rated at a maximum current of 2 simple. Outputs have high innush capacity for hencing capacitive loads. Output signals have 2500 volt isolation to logic common. The module contains four isolated commons, such having four outputs.

Typically, this module is used to output on/off signals to devices such as sciencids or motor sisiters that may need up to 2 amps current or have a large initian current requirement.

This manual describes the functions and specifications of the module. It also includes a detailed overview of installation and servicing procedures, as well as examples of programming methods.

Fielated publications that may be of interest:

- J 3630 ReSource AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 1.0
- J 3649 AutoMax CONFIGURATION TASK MANUAL
- J-3650 AutoMax PROCESSOR MODULE
 INSTRUCTION MANUAL
- JA3675 AutoMax ENHANCED BASIC LANGUAGE INSTRUCTION MANUAL
- J-3676 AutoMax CONTROL BLOCK LANGUAGE INSTRUCTION MANUAL
- JA3677 AutoMax LADDER LOGIC LANGUAGE INSTRUCTION MANUAL
- JA3584 Resource AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 2.0
- J-3750 Resource AutoMay PROXBAM MING EXECUTIVE INSTRUCTION MANUAL VERSION 3.0
- IEEE 518 GUIDE FOR THE INSTALLATION OF ELECTRICAL EQUIPMENT TO MINIM ZE ELECTRICAL NOISE INPUTS TO CONTROLLE 35 FROM EXTERNAL SOURCES

2.0 MECHANICAL/ELECTRICAL DESCRIPTION

The following is a description of the faceplate LEDa, field termination connectors, and electrics) characteriatics of the tield connections.

2.1 Mechanical Description

The output module is a printed dirout board assembly that plugs into the backplane of the DCS 5000/AutoMaxirack. It consists of a printed dirout board, a faceplate and a protective enclosure. The faceplate contains table still he top and bottom to simplify removing the module from the rack. Module dimensions are field in Appendix A.

Let faceplate of the module contains a female connector, speech and 16 LED indicators that show the atstus of the jourputs. Output signals leave the module via a multi-conductor, cable (M/N 570370). One and of this cable attaches to the indexplate connector while the other end of the cable has stake-on connectors that attach to a terminal stric for easy. Teld wiring. The taceplate connector socket and cable outputs are keyed to prevent the cable from being clugged into the wrong module.

On the back of the module are two edge connectors that attach to the system backatere.

2.2 Electrical Description

The output module containa 16 output direuta for 115 volt, controsignols. Each group of four circuits shares a single isolated common. Output signals have 2500 volt isolation to logic common. Refer to the block diagram in Appendix 8.

Each output circuit consists of a Triac with RC and MCV transient sucression. The Triac gate oriver is optically solated from the output buffer. A circuit diagram is shown in figure 2.1.

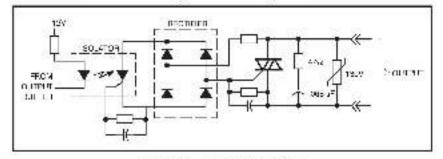


Figure 2.1 - Typical Output Dirout.

There are 16 LEDs on the 'aceptate of the module. The LEDs are arranged in the same order as the output term hals on the faceptate. They are numbered sequentially from zero through filteen corresponding to the bits in the register. The LED indicators display. the status of the logic level circuitry. A fit LED indicates that data has been written to the cutput. See figure 2.2.

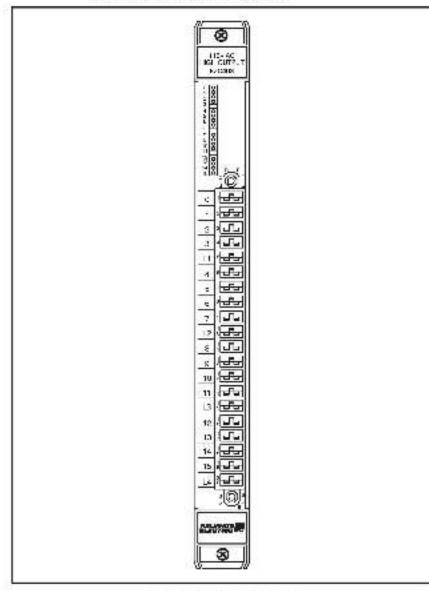


Figure 2.2 - Module Faceplate

3.0 INSTALLATION

This section describes how to install and remove the module and its cable assembly.

3.1 Wiring

The Installation of wiring anould conform to all applicable codes

To reduce the possibility of electrical noise interfering with the proper operation of the control system, exercise care when installing the wining from the system to the external devices. For detailed recommendations refer to IEEE 518.

3.2 Initial Installation

Use the following procedure to install the module:

- Step 1. Turn off power to the system. All power to the rack as well as all power to the wring leading to the module should be off.
- Step P. Mount the terminal ship (M/N 570370, 610595, or 610596) on a panel. The terminal ship should be mounted to semiillessly access to the screw terminals on the terminal ship. Make certain that the terminal ship ta close enough its the rack so that the cable will reach between the terminal ship and the module.
- Step 3 Faster field wirds to the terminal strp. Note that the bit number and wire number are not the same. Typical field signal connections are shown in figure 3.1. Befor to Appendix G for the ensagement of terminal strip connections. Make contain that all field wires are securely teatened.

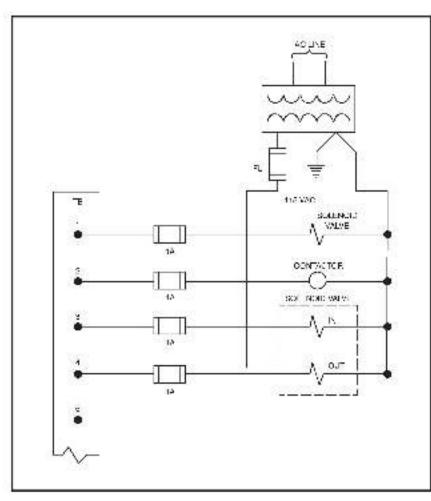


Figure 3.1 - Typical Field Signal Connections

Step 4. If the device to which you are connecting the output module contains an inductive load, install an BC suppression network across the output terminals of the device. If this is not cone, the output module may not always function correctly. Refer to figure 3.2.

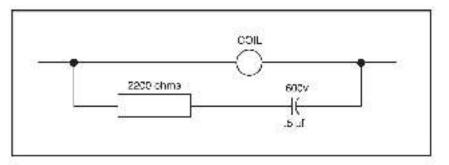


Figure 3.2 - BC Superession Network for Inductive Loads

- Step 9 Take the module out of its shipping container. Take it out of the anti-stella bag, being careful not to fouch the can rectors on the back of the module.
- Step 6 Insert the module into the desired slot in the reck. Use a screwdriver to secure the module into the slot. Befer to figure 3.3.

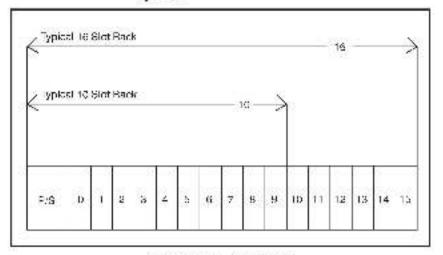


Figure 3.3 - Rack Stot Numbers

Step 7. Attach the field terminal connector (M-N 57C370, 61C50s, or 61C506) to the msting half on the module. Mske certain that the connector is the proper one for this module. Use a screwdriver to secure the connector to the module.

Note that both the module and the terminal atrip connector, are equipped with "keys." These keys should be used to prevent the wrong cable from being plugged into a module in the event that the connector needs to be removed for any reason and then reattached, later

At the time of installation, rotate the keys on the module and the connectorise that they can be connected together security. It is recommended that, for each module so recurpted, the keys on each successive module in the rack be rotated one position to the right of the keys on the preceding module.

If you use this motions, the keys on a particular connector, will be positioned in such a way as to fit together only with a specific module, and there will be liftle chance of the wrong connector being attached to a module.

- Step 8. Turn on power to the system.
- Step 8. Verily the inalstitution by connecting the programming terminal to the system and running the ReSource Software.

Stop all programs that may be running.

Use the I/O MONITOR function. If the module is in a local rack, onter the module slot number and register (always 0).

If the module is in a remote rack, enter the slot number of the master remote I/O module, remote I/O drop number (slop called the remote rack number), output module slot number and register (sloways 0).

One at a time, toggle each of the bits that have been wired to output erwines to verify that the installation has been completed correctly.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

3.3 Module Replacement

Use the following procedure to replace a module:

- Step 1. Furnioll power to the rack and all connections.
- Step 2. Use a sciewdriver to locaer the sciews holding the connector to the module. Remove the connector.
- Step 3. Leasen the screws holding the module to the rack. Berrove the module from the slot in the rack.
- Stap 4. Place the module in the anti-static bag it came in, being careful not to touch the connectors on the back of the module. Place the module in the cardboard shipping container.
- Step 5. Take the new module out of the anti-static beg, being osretunot to touch the connectors on the back of the module
- Step 6. Insert the module into the desired slot in the rack. Use a screwdrive to secure the module into the slot.
- Step 7. Attach the field terminal connector (M-N 57C370, 61C505, or 61 C506) to the mating half on the module. Make certain that the connector keys are priented correctly and that the connector is the proper one for this module (see step 7 in 3.2, nitial installation). Use a screwdriver to secure the connector to the module.
- Step 8. Turn on power to the reck.

4.0 PROGRAMMING

This section describes how data is organized in the module and provides examples of how the module is accessed by the application software. For more detailed information, refer to the AutoMax Enhanced BASIC Language Instruction Manual (J-3676).

4.1 Register Organization

I he date in the module is organized as one 16 bit register. The software allows you to optime the module as a single register (up in 16 bits) by referencing the entire module as a unit, or as up to 16 individual bits by referencing each of the bits separately. Refer to figure 4.1

	15	14	13	12	31	10	H.	н	7	- b	5	4	3	્ય	ા	ų
reçister C	96	EV.	2.9	-	EX!	9%	ħΛ'	BN7	-	EX.	R87	900	EW	36	642	R!>

Figure 4.1 - Organization of Ragister Bits

4.2 Configuration

Before any application programs can be written, it is necessary to compute, or set, the definitions or system-wide variables. Lo, those that must be globally eccessible to all tasks.

For DCS 5000 and AutoMax Version 2.1 and earlier, you define system wide variables by writing a Configuration task. For AutoMax Version 3.0 and later, you define system-wide variables using the AutoMax Programming Executive. Alter these variables are defined you can generate the configuration file automatically, which elimitates the requirement to write a configuration task for the rack. If you are using AutoMax Version 2.1 or codies refer to Appendix Elier examples that show how to define variables in the configuration task. If you are using AutoMax Version 3.0 or later, see the AutoMax Programming Executive (J-2750) for information acout configuring variables.

4.3 Reading And Writing Data In Application Tasks

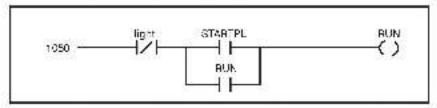
In order for an output module to be referenced by application software. It is first necessary to assign symbolic names to the physical hardware. In AutoMax Version 2.1 and curlier, this is accomplished by either IODEF or IRIDDEF softements in the configuration task. In AutoMax Version 3.0 and later, you assign symbolic names using the Programming Executive.

Each application program that references the sympolic names assigned to the module in configuration must beclare those inames. COMMON.

I he frequency with which tasks, or application programs, mad, their incuts and write their outputs depends on the language, deling used.

Laccerlogic and control block tasks read inputs once at the beginning of each scan and write outputs once at the end of each scan. BASIC tasks read an input and write an output for each reference throughout the scan.

4.3.1 Ladder Logic Task Example



The symbolic names RUN and STARTPL reference the output modules that were defined in the conficuration. The trailing at symbol "@" is not used in fadder togic tasks. The symbolic name "light," is local to the ladder togic task, and does not have FC associated with it.

4.3.2 BASIC Task Example

1000	LOCAL LIGHTOP	· Fault ight
1010	COMMON STARLPLOP	(Start Command
2000	COMMON RUNG	Viline run
5050	a series a series of the serie	
4000	£	
5000	RUN@ - NOT LIGHT@ AND RUN@)) (STARTPL@ OR
5600	1	
6000	END	

The symbolic names BUN(© and STARTPL©) reference the output modules that were defined in the configuration. The symbolic name LIGH (©) is local in the BASIC teak and does not have (C) associated with 1.

4.3.3 Control Block Task Example

2400	COMMON STARTFL:	\!Start command
2500	LOCAL MOMENTARY SI	Womentary output
3000	The state in the second second	2012/02/2012 02:00:00:00:00:00:00:00:00:00:00:00:00:0
4000	The second s	
5000	CALL TRANSITION (NEUT- OUTPUT-STARTFLEX)	MOMENTABY(Q).
5500	1	
DODO.	END	

The symbolic name STARTPD® references the cutput impoule that was defined in the configuration. The symbolic many MOMENTARY® is local to the control clock task and icode not have 1/2 associated with it

5.0 DIAGNOSTICS AND TROUBLESHOOTING

This section explains how to troubleshoot the module and field connections.

5.1 Incorrect Data

Problem: The device connected to theoutput is either always off, slways on, or acting different than expected. The possible causes of this are a module in the wrong slot, a programming error, or a instfunctioning module. It is also possible that the output is either not wred or wired to the wrong device. Use the following procedure to iso also the problem:

Step 1. Verify that the output module is in the correct slot and that the PO cell titlions are conect.

Refer to figure 3.2. Verify that the slot number libeing referenced agrees with the slot number libein the configuration. Verify that the register number is 0. Verify that the bit number refers to the proper bit. Note that the bit number and the wire number are not the same.

For remote t/C installational also verify that the master slot and remote crop number are defined correctly.

Step 2 Verily that the power supply is functional.

Stop all tasks that may be running

Confirm that all connections at the terminal atrip are tight. Connect a vollmeter to the power supply connections on the terminal atrip. If the voltage is not correct, there is a problem with the power supply or the wring to the terminal strip.

Gheck the soble for continuity between the faceplate connector and the terminal airp.

Step 3 Verily that the module can be accessed.

Connect the programming terminal to the system and run the ReSource Software.

Stop all tasks that may be running.

Use the FO MON TOR function. Topple the output device and determine whether the cit is changing state by observing the condition of the LED on the modure. If the LED cost not change state, the hardware is malfunctioning.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

Step 4 Variily that the output circuit on the module is working correctly.

Connect a voltmeter to the proper points on the terminal atrip and continue to toggle the output device from the I/O MONITOR. The volumeter should alternate between 0 and the line voltage. If this does not happen, the output circuit is malfunctioning.

Step 5. Verify that the user spolication program is correct.

Verify that the application program that references the symbolic names associated with the module has declared those names COMMON.

Verify that the symbolic name in question is being referenced in the application program. This can be done indirectly with the VARIABLE MON TOR in the programmer.

Step 5. Verify that the hardware is working correctly.

Verify the hereware functionality by systematically swapping out modules. After each swap, if the problem is not corrected, replace the original module before swapping out the next module.

- To test oca FO, first replace the output module. Next, replace the processor module(s). If the problem persists, take all of the modules out of the backplane exceptione processor module and the output module. If the problem is now corrected, one of the other modules in the rack is mailunctioning. Reconnect the other modules one at a time unit, the problem reappears. If none of these tests reveals the problem, replace the backplane
- To test remote 70, first verify that the remote I/O system is communicating with the cross that contains the output module is eightested. Netc. By systematically swapping out modules, determine whether the culput module is the only module that is not working. If more than one module is not working conrectly, the problem most likely lies in the remote trO system.
- To test the remote rack, first replace the output module. Next, replace the slave remote I/O module. If the problem consists, take all of the modules out of the remote backplane except the slave constant/O module and the output module. If the amblem is now connected, one of the other modules in the rack is malfunctioning. Becomest the other modules in the rack is infinite until the problem respects. If the orbition proves to be nother in the remote PO system nor the remote tack, try replacing the remote backplane.

5.2 Bus Error

Problem: A "31" or "51" through "53" appears on the processor modula's L=3. This error message indicates that there was a ous error when the system stiempted to scores the module. The possible causes of this error are a missing module, s module in the wrong slot, or a melfunctioning module. It is also possible that the user has attempted to write to the wrong registers on the module. Refer to the AutoMax Procesor Module instruction Manual (J-3550) for more information. Use the following procedure to isolate s ous error.

Step 1. Verily that the output module is in the correct slot and that the (O cell nitions are correct.)

> Refer to ngure 3.2. Vorify that the slot number being referenced sgrees with the alot number defined in the configuration task. Verify that the register number is 0. Note that the bit number and the wire number are not the same.

For remote (/C installations, also verify that the master slot and remote crobinumber are defined correctly

Step 2. Verily that the module can be accessed.

Connect the programming terminal to the system and runthe ReSource Software.

Stop all programs that may be running.

Use the FO MON TOR function to cisplay register 0. If the programmer is able to monitor the outputs, then attempt to write to the outputs.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

If the programmer cannot read and write to the outputs, the programmer last in the hardware

Step 3 Verily that the hardware is working correctly.

Verify the herctware functionality by systematically swapping out the output module, the processor module(s), and the backplane. After each swap, if the problem is not connected, replace the original item before swapping out the next term.

For remote (O installations, systematically swap out the output module, the slave remote module, and the backplane. After each swap if the problem is not corrected, replace the original item before swapping out the next item.

Appendix A

Technical Specifications

Ambient Conditions

- Storage temperature: -40° C 65°C
- Operating temperature: 0°C 60°C
- Jumidity: 5 90% non-condensing

Maximum Module Power Dissipation

30 Watts

Dimensions

- Height 11.75 inches
- Wieth: 1.25 Inches
- Depth: 7.375 inches.

System Power Requirements

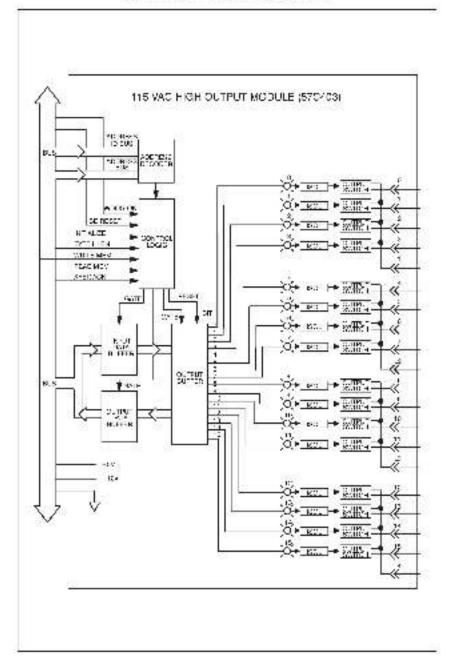
+6 volts: 1200 ma

Output Circuit

- Number of outputs; 16
- Meximum operating voltage: 132 voltaima.
- On state voltage drop, 1.5 volta at 2 smps.
- Peak Current for 20 msect 20 lamps.
- Maximum much (1 sec). 5 amps
- Maximum continuous current: 2 amps per autput;
 - 4 amps par common
 16 amps par module
 - to arrips par modul
- Maximum eekage current: 4 ma.
- Maximum Fuse rating: 5, amps per common.
- · Four inputs per isolated common
- 2500 will isolation between outputs and logic common.

Appendix B

Module Block Diagram



Appendix C

Field Connections

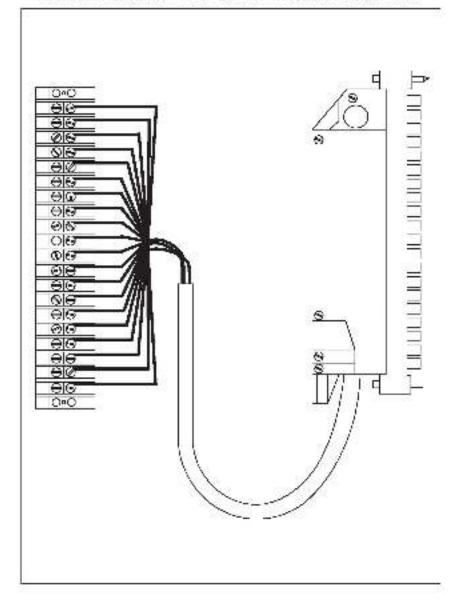
Terminal Board Number	Reg. 0 Bit		
1	D		
2	1		
3	2		
4	3		
5 L:	i.		
6	4		
7.	5		
δ	8		
£	- 6		
1012			
Ü.	8		
12	÷		
13	10		
17	17		
15L3	2		
16	12		
17	13		
18	14		
19	15		
2014			

Appendix D

Related Components

57C370 - Terminal Strip/Cable Assembly

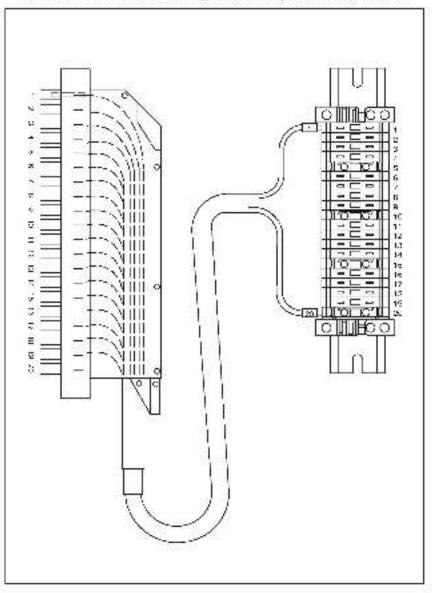
This assembly consists of a NEMA-style terminal strip loable, and matting connector, it is used to connect field signals to the taken ate of the output module.



Appendix D (Continued)

61C505 - DIN-Style Terminal Strip/Cable Assembly (Fused)

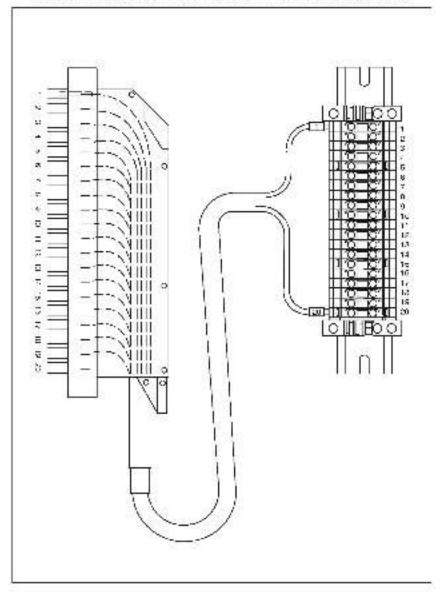
This assembly consists of a DIN-style terminal strip with fuses, cable, and moting connector. It is used to connect field algorits to the takep ate of the output module.



Appendix D (Continued)

61C506 - DIN-Style Terminal Strip/Cable Assembly (Unfused)

This assembly consists of a DIN-style terminal strip with fuses, cable, and mating connector. It is used to connect field signals to the taceplate of the output module.

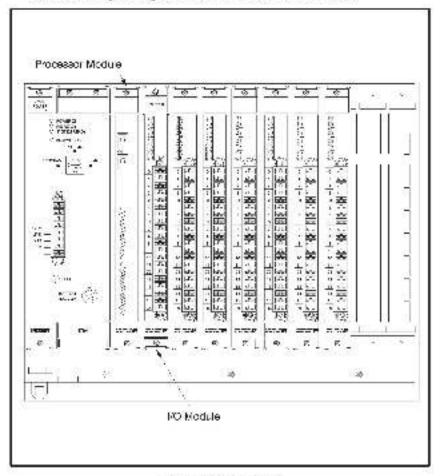


Appendix E

Defining Variables in the Configuration Task

Local I/O Definition

This section describes how to configure the output module when it is located in the same tack (i.e., the local rock) as the processor module that is referencing it. Refer to the figure below. Note that this procedure is used only if you are using the AutoMax Programming Executive software version 2.1 or cartler.



Module in a Local Back

Single Register Reference

Use the following method to reference all 16 outputs as a single register. Only one statement is required in the configuration task for the entire module. The symbolic name of the register should be as meaningful as possible.

nmmn ODEF SYMBOLIG_NAME%_ SHOT=s, REGISTER=0,

Bit Reference

Use the following method to reference individual outputs on the module. For the entire module, a maximum of 16 statements can be included in the configuration task tone for each city. The symbolic name of each bit should be semean right as possible.

rmmn_IODEF_SYMBOLIC_NAME(#[SLOT+s, REGISTER+1, BIT+5], where:

ronno - SASIG statement number. Ibla number may range from 1-32767.

SYMBOLIC_NAME% . A symbol ciname chosen by the user and ending with (%). This indicates an integer data type and all references will access the entire module.

SYMBOLIC_NAME@ - A symbolic name chosen by the user and anding with (@). This indicates a coolean data type and all references will access bit number "b" only.

 SLO^+ - Slot number that the module is purged into. This number may range from 0-15.

REG STER - Always zero for this module.

BIT - Used with boolean data types only. Specifies the bit in the register that is being referenced. This number may range from 0-15.

Examples Of Local I/O Definitions

The following statement assigns the symbolic name DISPLAY% to the output inclute located in stot 4:

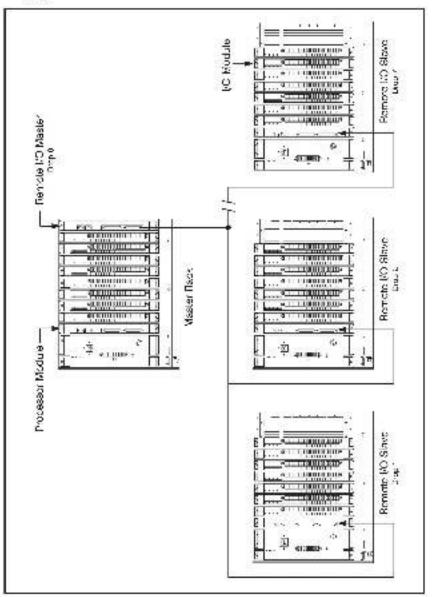
1020 IODEF DISPLAY% SLOT-1, REGISTER-0]

The following statement assigns the symbolic name RUN(3) to bit 9 on the output module located in slot 7:

2050 IODEF RUN@[SLOT-7, REC STER-0, B T-9]

Remote I/O Definition

This section describes how to configure the output module when it is located in a rack that is remote from the processor module referencing it. Refer to the figure below:



Module in a Remote Rack

Single Register Reference

Use the following method to reference all 16 outputs as a single register. Only one statement is required in the configuration task for the entire module. The symbolic name of the register should be as meaningful as possible:

ronon BIO HE SYMBOLIC_NAMES.[MASTER_SLOT-m, DBOP-c, SLOT-a REGISTER-0]

Bit Reference

For the entire module, a maximum of 16 statements can be included in the configuration task tone for each bit. The symbolic name of each bit should be as meaningful as possible.

rnnnn RIODEF SYMBOLIC_NAME@[MASTER_SL0T=m, DROP=c ... SL0T=s, REGISTER=0, BIT=s]

where.

rnnnn - BASIG statement number. This number may range from 1-32767.

SYMBOLIC_NAMES - A symbolic name chosen by the user and ending with (%). This indicates an integer data type and all references will access the entire module.

SYMBOLIC_NAME \otimes - A symbolic name chosen by the user and ending with (\oplus) . This indicates a boolean data type and all references will access bit number "b" only.

MASTER SL() \sim Sict number that the resister remote I/O module is plugged into. This number may range from 0-15

DROP Drop number of the slave terroto I/O module that is in the same rack esthe input module. This number may range from 1.7.

 $\rm SLO^{+}$ - Sict number that the module is plugged into. This number may range from 0-15,

REG STER - Always zero for this module.

BIT - Lese with boolean date types only. Specifies the bit in the register that is being referenced. This number may range from 0.15.

Examples Of Remote I/O Definitions

The following statement assigns the symbolic name LEVEL% to the output module located in slot 4 of remote I/O drop 3. This remote drop is connected to the remote (/O system whose master is located in slot 15 in the master rack)

1020 RICDEF LEVEL% [MASTER_SLOT-15, DROP-3, SLOT-1, REG STER=0]

The following statement easigns the symbolic name $STARTPI \not\in$ to all 9 on the output module located in slot 7 of remote I/O drop 2. This remote crop is connected to the re-

more I/O system whose mester is located in slot 6 in the mester rack.

2050 RIGDEF STARTPL@[WASTER_SLOT=6, DROP=2, SLOT=7, REG STER=0, BIT=9]

For additional information

1 Allen-Bradley Drive Mayfield Heights, Ohio 44124 USA Tel: (800) 241-2886 or (440) 646-3599 http://www.reliance.com/automax

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