24-115V A-C/D-C Low Power Output Module

M/N 57C402

Instruction Manual J-3624-1



The information in trialuser's manual is subject to change without notice.

WARNING

THIS UNIT AND ITS ASSOCIATED EQUIPMENT MUST BE INSTALLED, ADJUSTED AND MAINTAINED BY QUALIFIED PERSONNEL WHO ARE FAMILIAR WITH THE CONSTRUCTION AND OPERATION OF ALL EQUIPMENT IN THE SYSTEM AND THE POTENTIAL HAZARDS INVOLVED, FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

WARNING

INSERTING OR REMOVING THIS MODULE OR ITS CONNECTING CABLES MAY RESULT IN UNEXPECTED MACHINE MOTION. POWER TO THE MACHINE SHOULD BE TURNED OFF BEFORE INSERTING OR REMOVING THE MODULE OR ITS CONNECTING CABLES. FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN BODILY INJURY.

CAUTION

THIS MODULE CONTAINS STATIC-SENSITIVE COMPONENTS. CARELESS HANDLING CAN CAUSE SEVERE DAMAGE.

DO NOT TOUCH THE CONNECTORS ON THE BACK OF THE MODULE. WHEN NOT IN USE, THE MODULE SHOULD BE STORED IN AN ANTI-STATIC BAG. THE PLASTIC COVER SHOULD NOT BE REMOVED. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN DEMAGE TO OR DESTRUCTION OF THIS EQUIPMENT.

Reliance® is a trecemark of Reliance Electric Company or its subsidiaries

Table of Contents

1.0	Introduction	1-1
2.0	Mechanical/Electrical Description	2-1
	2.1 Mechanical Description	2-1
	2.2 Electrical Description	2-1
3.0	Installation	3-1
	0.1 Wring	3-1
	3.2 Initial Installation	3-1
	0.3 Mocule Replacement	3-
4.0	Programming	4-1
	4.1 Register Orcanization	7-1
	4.2 Configuration	2-1
	4.3 Reeding And Writing Osta in Application lasks	2.1
	4.3.* Ladeer Locic Task Example	42
	4.3.2 BASIC Task Example	4.2
	4.3.3 Control Block Task Example	12
5.0	Diagnostics And Troubleshooting	5-1
	5.1 Incorrect Data	5-1
	3.2 Bus Error	53

Appendices

Appendix A Technical Specificational	011		.A-1
Appendix B Module Block Diagram	12		8-1
Appendix C Field Connections			C-1
Appendix D Relates Components			- D-1
Appendix E Defining Variables in the Configuration Task	24	-	- E-1

List of Figures

Figure 2.1 Figure 2.2	- Typical Ostout Circuit - Module Facep ale	÷			2-1 2-2
Figure 3.1 Figure 3.2	Typical Field Signal Connections - Rack Sto: Numbers	8			32
Figure 4.1	- Organization of Register 6 ts	3ă	1	26	4-1

1.0 INTRODUCTION

The products described in this instruction manual are manufactured or distributed by Reliance Floctric Company or its subsidiaries.

This 24-115V AC/DC Low Power Output Module will drive a maximum of sixteen control signals as outputs from the DCS 5000/AutoMax system. The output signal voltage may range from 24-115 volta and DC through 60 hents. Maximum output current is limited to 200 ma. Leakage current is fessilihan 1 ms. Output signals have 2500 volt iso ation to logic common. The module contains four isolated commons, tool having four outputs.

Typically, this module is used to output on/off signals to devices such as citol lights or small relay coils that require less than 200 ma of current and low leakage current in the off siste.

This manual describes the functions and specifications of the module. It also includes a detailed overview of installation and servicing procedures, as well as examples of programming methods.

Felated publications that may be of interest:

- J-26"1 DCS 5000 PRODUCT SUMMARY
- J 3600 DCS 5000 ENHANCED BASIC LANGUAGE INSTRUCTION MANUAL
- J 3601 DCS S000 CONTROL BLOCK LANGUAGE INSTRUCTION MANUAL
- J 3602 DCS MCD LADDER LOGIC LANGUAGE INSTRUCTION MANUAL
- J-3629 DOS SUCE REMOTE (/O INSTRUCT ON MANUAL)
- JK3530 RoSpurce AutoMax PROGRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 1.0
- LI3535 DCS 5000 PROGESSOR MODULE
 INSTRUCTION MANUAL
- L3849 AutoMax CONFIGURATION TASK MANUAL
- J-3850 AutoMax PROCESSOR MODULE INSTRUCTION MANUAL
- J-3875 AutoMax ENHANCED BASIG LANGUAGE INSTRUCTION MANUAL
- J-3676 Auk/Msx CONTROL BLOCK LANCUAGE
 INSTRUCTION MANUAL
- J-3677 Auk/Msk LADDER LOGIC LANGUAGE INSTRUCTION MANUAL
- J-368/ Resource AutoMax PRCCRAMMING EXECUTIVE INSTRUCTION MANUAL VERSION 2.0
- J-3750 ReSource AutoMax PROCIDAM MINO EXECUTIVE INSTRUCTION MANUAL VERSION 3.0
- IEEE518 GUIDE FOR THE INSTALLATION OF ELECTRICAL EQUIPMENT TO MINIMIZE ELECTRICAL NOISE INPUTS TO CONTROLLERS TROM EXTERNAL SOURCES

2.0 MECHANICAL/ELECTRICAL DESCRIPTION

The following is a description of the taceptate LEDs field termination connectors, and electrical characteristics of the tield connections.

2.1 Mechanical Description

The output module is a printed circuit board assembly that plugs into the backplane of the DCS 5000/AutoMaxirack. It consists of a printed circuit board, a faceplate and a protective enclosure. The faceplate contains tabs at the top and bottom to simplify removing the module from the rack. Module cimensions are fisted in Appendix A.

Let faceplate of the module contribute a temple connector socket and t6 L=D indicators that show the alstus of the outputs. Output algorithm to the module via a multi-consultant cable (M(N 570370)) see Appendix D). One and of this cable attaches to the taccelete connector, while the other and of the cable has stake-on connectors that attach to a terminal strip for easy take writing. The taceplate connector socket and cable plug are keyed to prevent the cable from being plugged into the wrong module.

On the back of the module are two edge connectors that attach to the system backate \mathbf{r}_{e}

2.2 Electrical Description

The output module contains 16 output circuits for 24-115 volt control signals. Each group of four circuits shares a single isolated common. Output signals have 2500 volt solation to logic common. Heter to the block diagram in Appendix B.

Each output circuit consists of a full wave bridge rectifier with the load connected to the AC side and a power FET on the D-C side. The gate circuit of the FET is transformer isolated from the output buffer. A circuit diagram is shown in figure 2.1.



Figure 2.1 - Typical Oulput Orcuit

There are 16 LEDs on the faceptate of the module. The LEDs are arranged in the same order as the output terminals on the laceptate. They are numbered sequentially from zero through Fileen, corresponding to the bits in the register. The LED indicates diat data has been written to the output. See figure 2.2.



Figure 2.2 - Mocula Faceplate

3.0 INSTALLATION

This section describes how to install and remove the module and its cable assembly.

3.1 Wiring

The Installation of wiring anould conform to all applicable codes

To reduce the possibility of electrical noise interfering with the proper operation of the control system, exercise care when installing the wining from the system to the external devices. For detailed recommendations refer to IEEE 518.

3.2 Initial Installation

Use the following procedure to install the module:

- Step 1. Turn off power to the system. All power to the rack as well as all power to the wring leading to the module should be off.
- Step P. Mount the terminal strip (M/N 570370) on a panel, the terminal strip anould be mounted to permit easy socies to the acrew terminals on the terminal strip. Make certain that the terminal atrip to dose enough to the reck so that the cable will reach between the terminal strip and the module.
- Step 3 Faster field wires to the terminal strp. Note that the bit number and wire number are not the same. Refer to Appendix C for the a rangement of terminal strip connections. Meka certain that all field wires are securely fastened. Typical field signal connections are shown in tigure 3.1.



Figure 3.1 - Typical Field Signal Connections

- Step 4. Take the module out of its shipping container. Take it out of the anti-static bag, being careful net to touch the connectors on the back of the module.
- Step 5. Insert the module into the desired alot in the rack. Use a screwdriver to secure the module into the stot. Refer to figure 3.2.



Figure 3.2 - Rack Slot Numbers

Stap 6 Altach the field terminal connector (M/N 57C370) to the mating half on the module. Make certain that the connector is the proper one for this module. Use a screwdriver to secure the connector to the module.

> Note that both the module and the terminal slip connector are equipped with "keys." These keys should be used to prevent the wrong cable from being plugged into a module in the event that the connector needs to be removed for any reason and then realtabled taler.

> At the time of installation, rotate the keys on the module and the connector so that they can be connected together securely. It is recommended that, for each module ac obuipade, the keys on each successive module in the rack be rotated one position to the right of the keys on the proceeding module.

If you use this method, the keys on a particular connector will be positioned in such a way as to fit logs, her only with a specific module, and there will be it the chance of the wrong connector being at ached to a module.

- Step 7 Turn on power to the system.
- Step 8 Vority the installation by connecting the programming terminal to the system and running the ReSource Software.

Stop all programe that may be running.

Use the FO MON TOR function, if the module is in a local rack, enter the module slict number sho register talways 00

If the module is in a remote rack, enter the slot number of the master remote (A) module, remote (O) drop number (also salled the remote rack number), output module slot number and register (always 0).

One at a time, toggle each of the bits that have been wired to output devices to verify that the installation has been completed correctly.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

3.3 Module Replacement

Use the following procedure to replace a module:

- Step 1. Durn off power to the rack and all connections.
- Step 2. Use a screwdriver to loceen the screws holding the opmestor to the module. Remove the connector.
- Step 3. Loosen the screws hooing the module to the reck. Berriove the module mm the slot in the rack.
- Step 4. Flace the module in the anti-static bag it came in, being careful not to touch the connectors on the back of the module. Place the module in the cardboard shipping container.
- Step 5. Take the new module out of the anti-static bag, being careful not to touch the connectors on the back of the module
- Step 5. Insert the module into the cealed aidt in the rock. Use a screwdrive to secure the module into the slot.
- Step 7. Attach the Tele contined connector (M/N 67C370) to the mating half on the module. Make certain that the connector keys are oriented correctly and that the connector keys are oriented correctly and that the connector is the proper one for this module (see step 6 in 6.2 initial installation). Use a screwdriver to secure the connector to the module.
- Step 8. Turn on power to the rack.

4.0 PROGRAMMING

This section describes how data is organized in the module and provides examples of how the module is accessed by the application software. For more detailed information, refer to DCS (ADM Enhanced BASIC Language Instruction Manual (J-3670), or AutoMax Enhanced BASIC Language Instruction Manual (J-3670).

4.1 Register Organization

I he data in the module is organized as one 16 bit register. The software allows you to define the module as single register (up to 16 bits) by referencing the entire module as a unit, or as up to 16 individual bits by referencing each of the bits apparately. Refer to figure 4.1

	15	3	13	12	11	10	5	8	7	6	5	1	3	2	1	0
ogistor C	56	F.97	3.5	56	EN?	35	FM'	RW	7.5	EV!	BA	507	E\$¥	34	F4/	R%



4.2 Configuration

Before any application programs can be written, it is necessary to configure, or set, the definitions of avatem-wide variables like. Those that must be globally accessible to all tasks.

For DCS 5000 and AutoMax Version 2.1 and ention you define system-wide variables by writing s Configuration teak. For AutoMax Version 3.0 and later, you online system-wide variables using the AutoMax Programming Executive. After these variables are defined you can generate the configuration file automatically, which eliminates the requirement to write a configuration teak for the rack. If you are using AutoMax Version 2.1 or earlier, refer to Appendix E for examples that show how to define variables in the configuration teak. If you are using AutoMax Version 3.0 or later, see the AutoMax Programming Executive (J-5750) for information addit configuring variables.

4.3 Reading And Writing Data In Application Tasks

In order for an output module to be referenced by applicst on software. It is first necessary to assign symbolic names to the physical nervous in AutoMsx Version 2.1 sincle effect this is accompliance by other IODEF or RIODEF statements in the computation task. In AutoMax Version 3.0 and leter, you sestion symbolic names using the Programming Executive.

Each application program that references the sympolic names assigned to the module in configuration must declare those names COMMON. The frequency with which tasks, or application programs, read their inputs and write their outputs depends on the language being used. Laddenlogid and control block tasks read inputs once at the beginning of each scan and write outputs once at the end of each scan. DASIC tasks read an input and write an output for each reference throughout the scan.

4.3.1 Ladder Logic Task Example



The symbolic names RUN and STARTPL reference the output modules that were defined in the configuration. The traiting at symbol "@" is not used in ladder logic tasks. The symbolic name right" is local to the ladder logic task and does not have I/O associated with it.

4.3.2 BASIC Task Example

The symbolic names BUN(& and STARTPL(&) reference the culput theories has were defined in the configuration. The symbolic name LIGHT(&) is local to the SASIC teak and does not have t-C associated with 1.

4.3.3 Control Block Task Example

```
2400 COMMON STARTPL© (Start commane
2500 LOCAL MOMENTARY© (Momentary cutput
3000 L
4000 L
5000 CALL TRANSITION(IN PUT- MOMENTARY(©
0UTPUT- STARTPL©)
5000 L
5000 L
```

The symbolic name STARTPL© references the output module that was defined in the configuration. The symbolic name MOMENTARY© is local to the control clock task and does not have VO associated with it.

5.0 DIAGNOSTICS AND TROUBLESHOOTING

This section explains how to troubleshoot the module and field connections.

5.1 Incorrect Data

Problem: The device connected to the cutput is either sloways of, sloways on, or acting different than expected. The possible causes of this are a module in the wrong slot, a programming error, or a instfunctioning module. It is also possible that the cutput is either not wred or wired to the wrong device. Use the following procedure to iso also the problem:

Step 1 Verify that the output module is in the correct slot and that the PO cell hillions are correct.

Refer to figure 3.2. Vorify that the slot number being referenced agrees with the slot number defined in the configuration. Verify that the register number is 0. Verify that the bit number refers to the proper bit. Note that the bit number and the wire number are not the series.

For remote t/C installational also verify that the masterialot and remote crop number are defined correctly.

Step 9 Verify that the power supply is functional.

Confirm that all connections at the terminal strip are tight. Connect a volumeter to the proper points on the terminal strip and toggle the device. The volumeter should alternate between 0 and 115 volts. If this does not happen, there is a problem with either the external device, the DC prover supply, or the writing to the terminal strip.

Connect the programming terminal to the system and run the ReSource software.

Stop all tasks that may be running.

Confirm that all connections at the terminal strip are tight. Connect a voltmeter to the power supply connections on the terminal strip. If the voltage is not correct, there is a problem with the power supply on the writing to the terminal strip.

Check the cable for continuity between the faceplate connector and the terminal strip,

Step 3 Vority that the module can be accessed.

Connect the programming terminal to the system and run the ReSource Software.

Stop all tasks that may be running

Use the VO MON TOR function. Taggle the output device and determine whether the bit is a tanging state by observing the consistent of the LED on the module. If the LED does not change state, the bareware is malfunctioning.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

Step 4. Vority that the output circuit on the module is working correctly.

> Connect a voltmeter to the proper points on the terminal strip and continue to toggle the output device from the I/O MONITOR. The voltmeter should alternate between 0 and the line voltage. If this does not happen, the output circuit is malfunctioning and the module should be replaced.

Step 5. Verify that the user spolication program is correct.

Verify that the application program that references the symbolic names associated with the module has declared those names, COMMON,

Verify that the symbolic name in question is being referenced in the application program. This can be done indirectly with the VARIABLE MON TOR function in the ReSource software.

Step 6. Varity that the haraware is working correctly.

Verify the hardware functionality by systematically swepping out modules. After each swap, if the problem is not corrected, replace the original module before swepping out the next module.

- To test local I/O first replace the output module. Next, replace the processor module (s). If the problem persists, take still of the modules out of the cackplane except one processor module and the output module. If the problem is now corrected, one of the other modules in the rack is malfund, on ng. Reconnect the other modules one at a time until the problem reappears. If none of these tests reveals the problem reclace the packplane.
- In text remote (O), tital verify that the remote (O) system is communicating with the crop that contains the output module being tested. Next, by systemstically awapping out modules, determine whether the output module is the only module that is not working. If more than one module is not working objectly, the problem most likely ies in the remote VO system. If the problem does not lie in the system, it probably involves the remote rsos.
- To test the remote rack, first include the output module. Note, replace the slave remote 1/D module. If the problem censists, take all of the modules out of the remote backplane except the slave remote I/O module and the output module. If the problem is now corrected, one of the other modules in the rack is matuneticating. Reconnect the other modules on of a time until the problem reappears. If the problem proves to be notifier in the remote I/O system in the remote rack, my replacing the remote backplane.

5.2 Bus Error

Problem: A "31" or "51" through "58" appears on the processor modulers UED. This error message indicates that there was a ous error when the system stiempted to appears the module. This error message means that the module is missing, in the wrong slot, or matfunctioning. It is also possible that that user has attempted to write to the wrong registers on the module. Refer to the DCS Processor Module Instruction Manual (J-3635) or AutoMax Processor Module Instruction Manual (J-3655) for more information, bee the following procedure to solate a bus error.

Step 1 Verify that the output module is in the correct slot and men the PO definitions are correct.

> Refer to 1 gure 3.2. Verify that the slot number being referenced agrees with the slot number defined in the configuration task. Verify that the register number is 6. Note that the bit number and the vire number are not the same.

For remote bC installational also verify that the master slot and remote prop number are defined correctly.

Step 2 Vorily that the module can be accessed.

Connect the programming terminal to the system and runthe ReSource Software.

Stop all programs that may be running.

Use the I/O MON TOR function to display register 0. If the programmer is able to monitor the outputs, then attempt to write to the outputs.

WARNING

BE CAREFUL WHEN WRITING TO THE OUTPUTS TO INSURE THAT NO UNEXPECTED MACHINE MOTION WILL RESULT. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY OR DAMAGE TO EQUIPMENT.

> If the programmer cannot read and write to the outputs, the problem lies in the hardware

Step 3 Vorily that the barewore lies working correctly.

Verify the hardware functionality by systematically ewapping out the output module, the processor module(s), and the backplane. After each awap, if the problem is not corrected, reclade the original item before ewapping out the next tem.

For remote EC installational systematically swep out the output module, the slave remote module, and the backplane. After each swep, 1 the problem is not corrected, replace the original item before swapping out the next flem.

Appendix A

Technical Specifications

Ambient Conditions

- Storage temperature, -40° C 85° C.
- Operating temperature: 0° C 60° C
- Itumidity: 5.90% non-condensing.

Maximum Module Power Dissipation

20 Watts

Dimensions

- Height 11.75 inches
- Wieth: 1.25 Inches
- Depth: 7.375 inches.

System Power Requirements

- +6 volts: 525 ma
- +12 volts: 45 ma
- +12 so ts: 45 ms

Input Circuit

- Number of outputs, 16
- Maximum operating voltage: 132 volta mail
- On state voltage drop. 1.4 volts at minimum current 2.9 volts at 200 ma
- Maximum mush (.1 eec): 1.0 amp.
- Maximum mush (1 sec): .5 amp
- Maximum continuous current: 200 mail
- Maximum leakage current: 1.0 ma.
- Four outputs per iso aled common.
- 2500 volt isolation between outputs and logic common.

Appendix B

Module Block Diagram



Appendix C

Field Connections

Terminal Board Number	Reg. 0 Bit
1	0
2	<u></u>
a	Z
2	3
ăL1	
6	2
7	5
स	6
9	7
10 L2	
tt.	8
12	्रत
15	10
14	11
15 L3	
15	12
17	13
16	14
19	15
2014	

Appendix D

Related Components

57C370 - Terminal Stric/Cacle Assembly

This assembly consists of stremmististip, caple, and mating connector. It is used to connect tield signals to the tecepiste of the output module.



Appendix E

Defining Variables in the Configuration Task

Local I/O Definition

This section describes how to configure the output module when it is located in the same tack (i.e., the local rock) as the processor module that is referencing it. Refer to the figure below. Note that this procedure is used only if you are using the AutoMax Programming Executive software version 2.1 or cartler.



Module in a Local Rack

Single Register Reference

Use the following method to reference the entire module as a single register. Only one statement is required in the configuration task for the entire module. The symbolic name of the register about be as meeningful as possible:

rmnn IODEF SYMEOLIC_NAME% [SLOT-s, REGISTER-0]

Bit Reference

Use the 'cllowing method to reference individual bits on the module. For the entire module, a maximum of 16 statements can be included in the configuration task (one for each bit). The symbolic name of each bit should be as mean right as possible:

rinnin IODEF SYMBOLIO_NAME@ [SLOTHs, REGISTERHr, P/THb]

where:

mmm - BASIC statement number This number may range from 1-32767.

SYMBOLIC NAMES, - A symbolic name chosen by the user and ending with (%) . This indicates an integer data type and all references will access the entire module.

SYMBOLIC_NAME \gtrsim A symbolic name chosen by the user and ending with ((). This indicates a box can data type one all references will access bit number 'b' only.

 $\rm SLOT$ - Sist number that the module is plugged into. This number may range from 0-15.

REG STER - Always zero for this module.

BIT - Loop with booleon data types only. Specifies the bit in the register that is being referenced. This number may range from 0-15.

Examples Of Local I/O Definitions

The following statement assigns the symbolic name DISPLAY's to the output module located in stol 4:

1020 IODEF DISPLAYS/[SLOT-4, REGISTER-0]

The following statement assigns the symbolic name RUN@ to bit 9 on the output module located in slot 7:

2050 IODEF RUN@ SLOT-7, REGISTER-0, BIT-9]

Remote I/O Definition

This section describes now to configure the output module when it is localed in a rack that is remote from the processor module referencing it. Refer to the figure below:



Module in a Remote Rack

Single Register Reference

Lae the following method to reference the entire module as a single register. Only one statement is required in the configuration task for the entire module. The symbolic name of the register about be as meaningful as possible:

rmmin RIODEF SYMBOLIC_NAME% [MASTER_SLOT-m_DROP-o: SLOT-s, & REGISTER-0]

Bit Reference

Use the "cllowing method to reference individual bits on the module. For the antire module, a maximum of 16 statements can be included in the configuration task (one for each bit). The symbolic name of each bit should be as mean right as possible:

mmm RIODEF SYMBOLIC_NAME@] MASTER_SLOTHm, DROPHd. SLOTHa, 名 REGISTERHD_BITHD

witche:

mmm - BASIC statement number. This number may range from 1-32767.

SYMBOLIC NAME% - A symbolic name chosen by the user and ending with (%). Ubla indicates an integer data type and all references will access the entire module.

SYMBOLIC_NAME(a) - A symbolic name chosen by the user and ending with ((b)). This indicates a beel can data type and all references will access bit number "b' only.

MASTER_SLOT - Slot number that the master remote I/O module is plugged into. This number may range from 0-15

DBOP - Drop number of the slave remote I/O module that is in the same maxies the input module. This number may range from 1-7.

 $\rm SLO^{+}$ - Slot number that the module is plugged into. This number may range from 0.1 s.

REC STER - Always zero for this module.

BIT - Loss with boolean data types only. Specifies the bit in the register that is boling referenced. This number may range from 0-15.

Examples Of Remote I/O Definitions

The following statement assigns the symbolic name LEVEL% to the output module located in slot 4 of remote I/O drop 3. This remote drop is connected to the remote (/O system whose master is located in slot 15 in the master rack:

1020 RIODEF LEVELS [MASTER_SLOT+16, DROP=3, SLOT=4, REGISTER=2]

The following attement assigns the symbolic name \$TABTPL% to at 9 on the output module located in slot 7 of remote I/D drop 2. This remote drop is connected to the remote I/D system whose master is located in slot 6 in the master rack.

20:00 RIODEF STARTFL@[MASTER_SLOT=6, DROP=2, SLOT=7, & REGISTER=0, DIT=9]

For additional information

1 Allen-Bradley Drive Mayfield Heights, Ohio 44124 USA Tel: (800) 241-2886 or (440) 646-3599 http://www.reliance.com/automax

seven actives before the company

European Hankaparan Indonesi Kalamata, 20 Milani, Mataran Anna, Lak 140, Minanina, M. 1920-500, 1991, 1993, 1493, 1492, 1202, 1493

Hankgueren for Allen-Bredley Protoco, Rockwall Software Produce, and Othel Manaface day Solution. Ann war behavel faithere, an Eur Soull dava die an Helwaten. W 2004-2008 Eds hier (144-2002) (Eds 1000) (Eds 20 Roch Hell, SadVille, Allen Helman, and Protocol and Allendon, and Eur Charles and Allendon (Eds 2004) (Eds 20 Allendon (Eds 2004) (Eds 2004)

Hechigan tarah Badga and Kalawas Rambia Nadata Anno 2 Janbari Annor 20,070 (radar Gary Geradia, 2008) - 617, 53, 56 (radar 2000), 56 (radar 2007) Baraz Mala Sad Mira Tarah Salami za Mili yang 21 (radar 2004) Bala Salar Sana Tarah Kala Si Mila Jan Ka Sati (2015) Bala Takabal Kalami ata Kalami za Mili yang 21 (radar 2004) Bala Salar Sati (radar 2005) Bala Sati (radar

Californi Maaisis kaa laa

Copy join 4: 2008 Rockwell Accuration, 1:21, A high measures Hinselin U.S.A.